

Neousys Technology Inc.

Nuvo-10108GC Series

User Manual

Revision 1.7

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For our contact information, please visit our [official website](#).

Declaration of Conformity

FCC

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at own expense.

CE

The product(s) described in this manual complies with all applicable European Union (CE) directives if it has a CE marking. For computer systems to remain CE compliant, only CE-compliant parts may be used. Maintaining CE compliance also requires proper cable and cabling techniques.

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Safety Precautions

- Read these instructions carefully before you install, operate, or transport the system.
- Install the system or DIN rail associated with, at a sturdy location
- Install the power socket outlet near the system where it is easily accessible
- Secure each system module(s) using its retaining screws
- Place power cords and other connection cables away from foot traffic. Do not place items over power cords and make sure they do not rest against data cables
- Shutdown, disconnect all cables from the system and ground yourself before touching internal modules
- Ensure that the correct power range is being used before powering the device
- Should a module fail, arrange for a replacement as soon as possible to minimize down-time
- If the system is not going to be used for a long time, disconnect it from mains (power socket) to avoid transient over-voltage

Battery Warning

- Batteries are at risk of exploding if incorrectly installed.
- Do not attempt to recharge, force open, or heat the battery.
- Replace the battery only with the same or equivalent type recommended by the manufacturer.

Caution!



Service and Maintenance

- ONLY qualified personnel should service the system
- Shutdown the system, disconnect the power cord and all other connections before servicing the system
- When replacing/ installing additional components (expansion card, memory module, etc.), insert them as gently as possible while assuring proper connector engagement

ESD Precautions

- Handle add-on module, motherboard by their retention screws or the module's frame/ heat sink. Avoid touching the PCB circuit board or add-on module connector pins
- Use a grounded wrist strap and an anti-static work pad to discharge static electricity when installing or maintaining the system
- Avoid dust, debris, carpets, plastic, vinyl and styrofoam in your work area.
- Do not remove any module or component from its anti-static bag before installation

Restricted Access Location

The controller is intended for installation only in the certain environment where both these condition apply:

- Access can only be gained by SERVICE PERSONS or by USERS who have been instructed about the reasons for the restrictions applied to the location and about any precautions that shall be taken
- Access is through the use of a TOOL or lock and key, or other means of security, and is controlled by the authority responsible for the location.

About This Manual

This manual introduces Neosys Nuvo-10108GC series featuring Intel® 14th/ 13th/ 12th-Gen Core™ 35W/ 65W LGA1700 processors and an NVIDIA® graphics card. The Nuvo-10108GC system supports an NVIDIA® RTX™ 40 series graphics card or the latest RTX™ Ada GPU for advanced inference capabilities.

The guide also demonstrates the system's installation procedures.

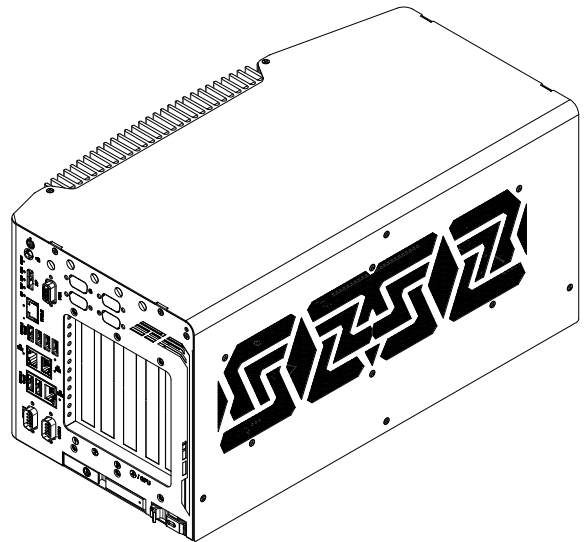
Revision History

Version	Date	Description
1.0	Oct. 2023	Initial release
1.1	Nov. 2023	Updated optional NVMe tray/ chassis installation procedure
1.2	Feb. 2024	Update 8-pin connector pinout definition
1.3	May. 2024	Updated dimensions specifications
1.4	Jun. 2024	Added support for Intel® 14 th Gen Core CPUs Updated DisplayPort output descriptions
1.5	Feb. 2025	Updated SATA port specifications Updated memory support specifications
1.6	Apr. 2025	Updated system specifications
1.7	Jul. 2025	Updated NVIDIA® RTX 50 series graphics card installation procedure

1 Introduction

Nuvo-10108GC is a ruggedized Edge AI computer with extreme CPU and GPU performance for autonomous driving and AI-powered factory automation. It leverages an Intel® 14th/ 13th/ 12th-Gen CPU and an NVIDIA® RTX™ 40 series or the latest RTX™ 6000 Ada GPU, offering single-precision GPU performances up to 48 TFLOPS or 91 TFLOPS, respectively.

Powered by an Intel® 14th/ 13th/ 12th-Gen CPU with up to 24 cores and 32 threads, Nuvo-10108GC offers up to double the performance when compared to previous Intel® 10th or 11th-Gen platforms. It supports ECC memory to deliver mission-critical computation, e.g., automated driving in urban traffic while inheriting a proven thermal dissipation design for the CPU and GPU to guarantee rugged, -25°C to 60°C wide-temperature operation. To withstand continuous shaking and juddering conditions for on and off highway applications, Nuvo-10108GC features an innovative GPU locking bracket to fasten the GPU to the chassis, and Neosys' patented damping bracket to absorb high-frequency vibration.



Nuvo-10108GC also features an abundance of I/Os, such as 6x USB3.2 Gen2, 2x 2.5GbE, 1x GbE, and 1x optional 10GbE. Expansion-wise, Nuvo-10108GC offers 3x additional PCIe slots for GMSL2/ industrial camera frame grabbers and various add-on cards. Also, it provides 2x full-size mini PCI Express sockets for CAN bus/ COM expansion and 1x M.2 B key sockets for mobile connectivity with 4G LTE, 5G NR, or WiFi modules. In terms of data storage, Nuvo-10108GC offers an M.2 2280 M socket for Gen4x4 NVMe, and dual front-accessible storage options, including a 2.5" SATA HDD/SSD and an optional M.2 2280 Gen4x4 NVMe tray.

By utilizing Intel's 14th/ 13th/ 12th-Gen platform, NVIDIA® RTX™ inference capability, and Neosys' industrial-grade power, thermal and mechanical designs with rich I/O and expansion, Nuvo-10108GC is a rugged edge AI platform that offers unprecedented GPU and CPU computing power for modern AI applications.

1.1 Product Specifications

1.1.1 Nuvo-10108GC Specifications

System Core	
Processor	<p>Supports Intel® 14th-Gen Core™ CPU (LGA1700 socket, 65W/ 35W TDP)</p> <ul style="list-style-type: none"> - Intel® Core™ i9-14900/ i9-14900T - Intel® Core™ i7-14700/ i7-14700T - Intel® Core™ i5-14500/ i5-14400/ i5-14500T - Intel® Core™ i3-14100/ i3-14100T <p>Supports Intel® 13th-Gen Core™ CPU (LGA1700 socket, 65W/ 35W TDP)</p> <ul style="list-style-type: none"> - Intel® Core™ i9-13900E/ i9-13900TE - Intel® Core™ i7-13700E/ i7-13700TE - Intel® Core™ i5-13500E/ i5-13400E/ i5-13500TE - Intel® Core™ i3-13100E/ i3-13100TE <p>Supports Intel® 12th-Gen Core™ CPU (LGA1700 socket, 35W/ 65W TDP)</p> <ul style="list-style-type: none"> - Intel® Core™ i9-12900E/ i9-12900TE - Intel® Core™ i7-12700E/ i7-12700TE - Intel® Core™ i5-12500E/ i5-12500TE - Intel® Core™ i3-12100E/ i3-12100TE - Intel® Pentium® G7400E/ G7400TE - Intel® Celeron® G6900E/ G6900TE
Chipset	Intel® R680E Platform Controller Hub
Graphics	Integrated Intel® UHD Graphics 770 (32EU)/ 730 (24EU)
Memory	Up to 128GB ECC/ non-ECC DDR5 4800 SDRAM (two SODIMM slots) ^[1]
AMT	Supports Intel vPro/ AMT 16.0
TPM	Supports dTPM 2.0
I/O Interface	
Ethernet	<p>2x 2.5G Ethernet port by Intel® I226-IT</p> <p>1x Gigabit Ethernet port by Intel® I219-LM</p>
10G Ethernet (optional)	1x 10GBASE-T port by Marvell AQC113CS, supporting NBASE-T (5G/ 2.5G) and 1000BASE-T
USB3.2	6x USB3.2 Gen2x1 (10Gbps) ports
USB2.0	1x USB2.0 port (internal dongle use)
Serial Port	2x software-programmable RS-232/ 422/ 485 ports (COM1/ COM2)
Video port (integrated)	1x VGA connector, supporting 1920 x 1200 resolution

graphics)	1x DisplayPort connector, supporting 4096 x 2304 resolution
Audio	1x 3.5mm jack for speaker-output and microphone-input
Storage Interface	
SATA	1x front-accessible, hot-swappable HDD tray for 2.5" HDD/ SSD installation
M.2	1x M.2 2280 M key socket (PCIe Gen4 x4) for NVMe SSD 1x front-accessible M.2 2280 M key tray (PCIe Gen4 x4) for NVMe SSD (optional)
Expansion Bus	
PCI Express	1x PCIe x16 slot @Gen4, 16-lanes with 65 mm slot width. (The standard GPU locking bracket is designed for NVIDIA® RTX™ A4000, A5000, A6000, 6000 Ada, and selected RTX 40 Series GPU cards.) 3x PCIe x8 slots@Gen3, 4-lanes
Mini-PCIe	2x full-size mini-PCIe sockets with internal SIM sockets
M.2	1x M.2 2242/ 3052 B key socket with internal SIM socket
Power Supply	
DC Input	3-pin + 4-pin pluggable terminal block for 8V to 48V DC input with ignition control*
Mechanical	
Dimension	214 mm (W) x 400 mm (D) x 196 mm (H)
Weight	6.5Kg
Mounting	Wall-mount with damping brackets
Environmental	
Operating temperature	With 35W CPU and dual NVIDIA® 350W GPU -25°C to 60°C ^[2] / ^[3] / ^[4] With 65W CPU and dual NVIDIA® 350W GPU -25°C to 60°C ^[2] / ^[3] / ^[4] (with optional fan kit) -25°C to 50°C ^[2] / ^[3] / ^[4] (without optional fan kit)
Storage temperature	-40°C to 85°C
Humidity	10% to 90%, non-condensing
Vibration	MIL-STD-810H, Method 514.8, Category 4 (with damping bracket)
Shock	MIL-STD-810H, Method 516.8, Procedure I (with damping bracket)
EMC	CE/ FCC Class A, according to EN 55032 & EN 55035

[1] As of Aug. 2023, the maximum single DDR5 SODIMM capacity is 48GB.

[2] System load under 100W, the required DC input range is 8V to 48V.

System load between 100W to 480W (single GPU), the required DC input range is 13.8V to 48V.

[3] For sub-zero operating temperature, a wide temperature HDD drive or Solid State Disk (SSD) is required.

[4] For 65W CPUs, the optional fan kit is recommended for operating at ambient temperatures higher than 50°C.

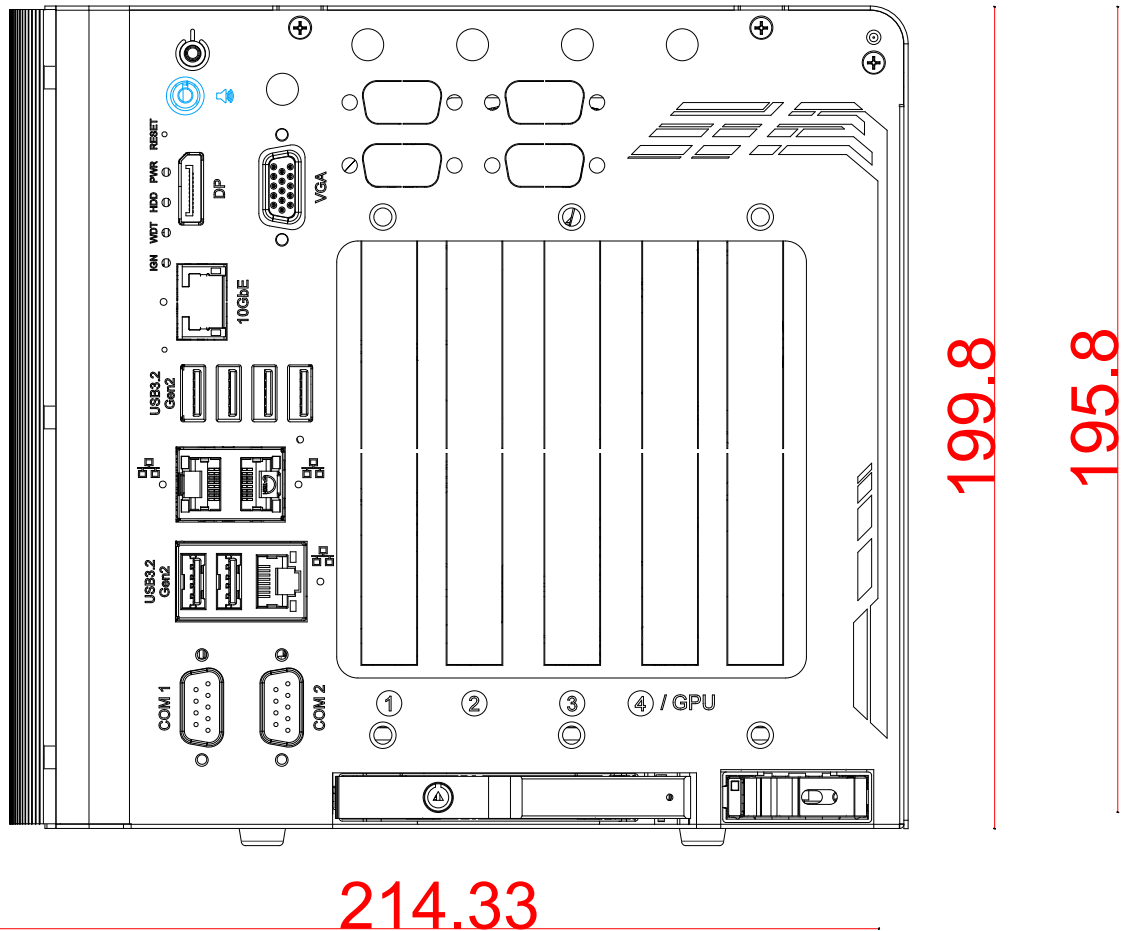
1.2 Nuvo-10108GC Dimension



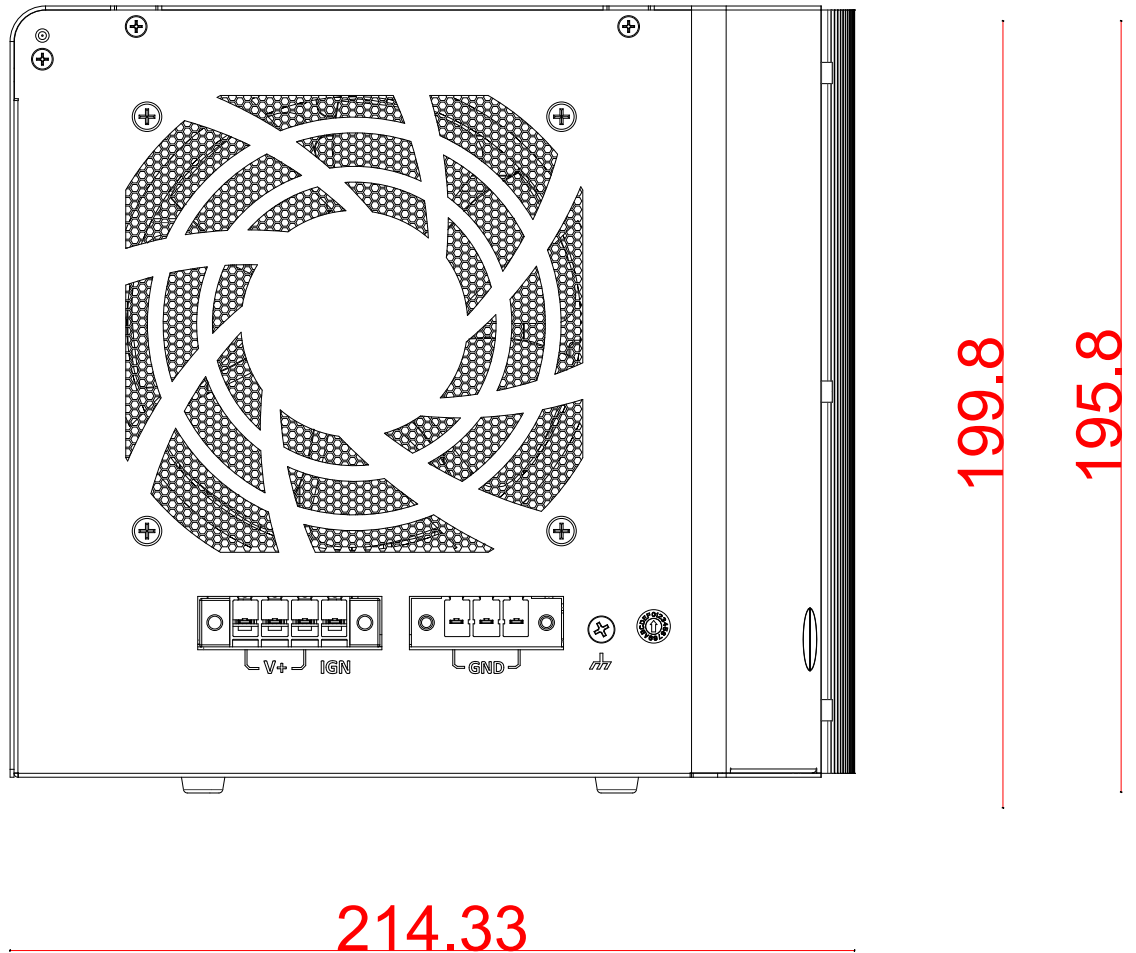
NOTE

All measurements are in millimeters (mm).

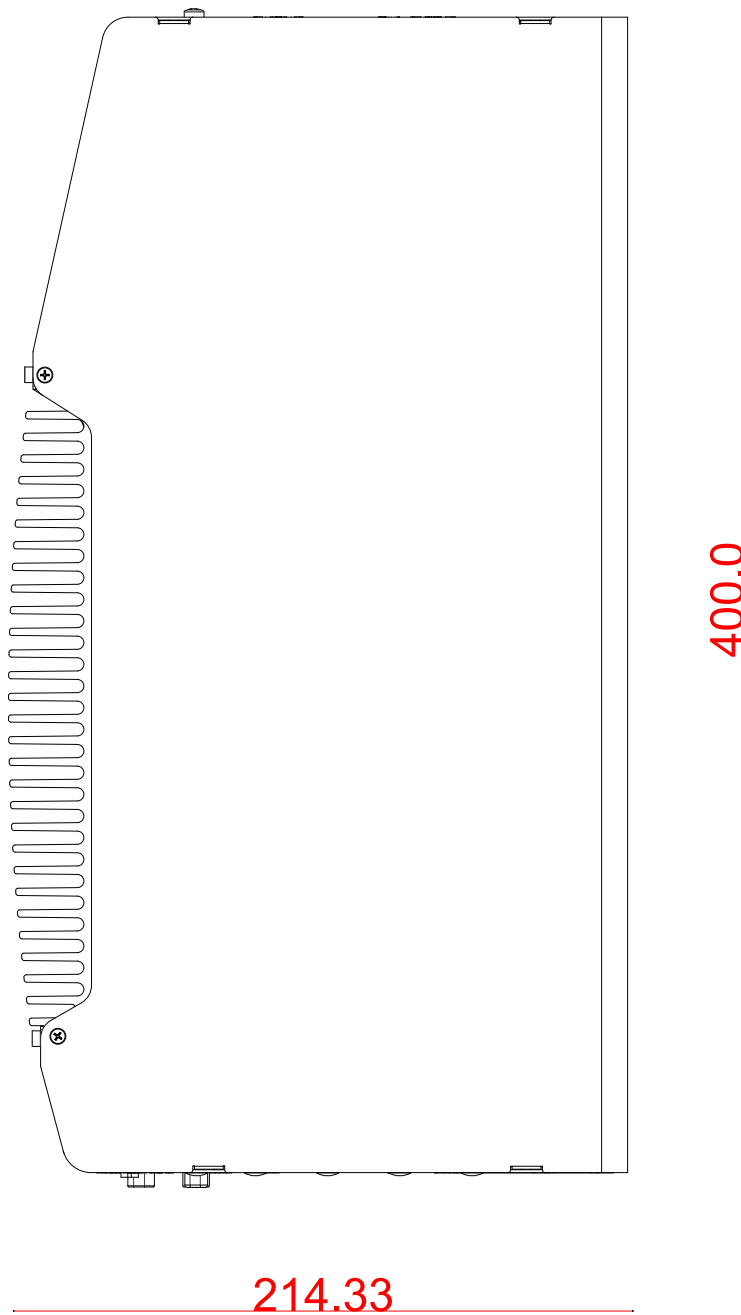
1.2.1 I/O Panel View



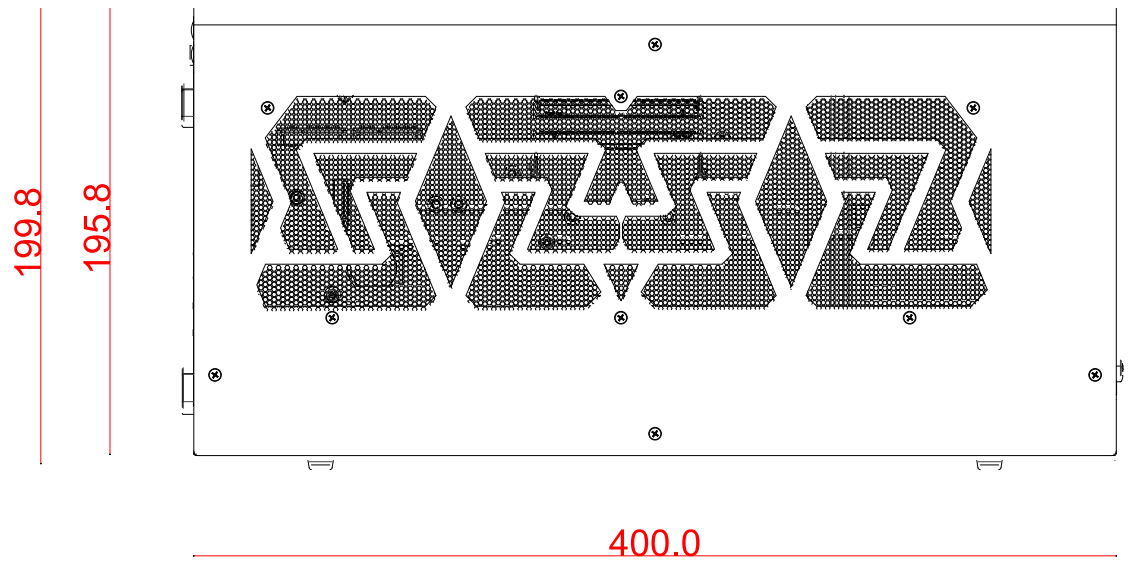
1.2.2 Ignition/ 4/3-Pin Terminal Block Panel View



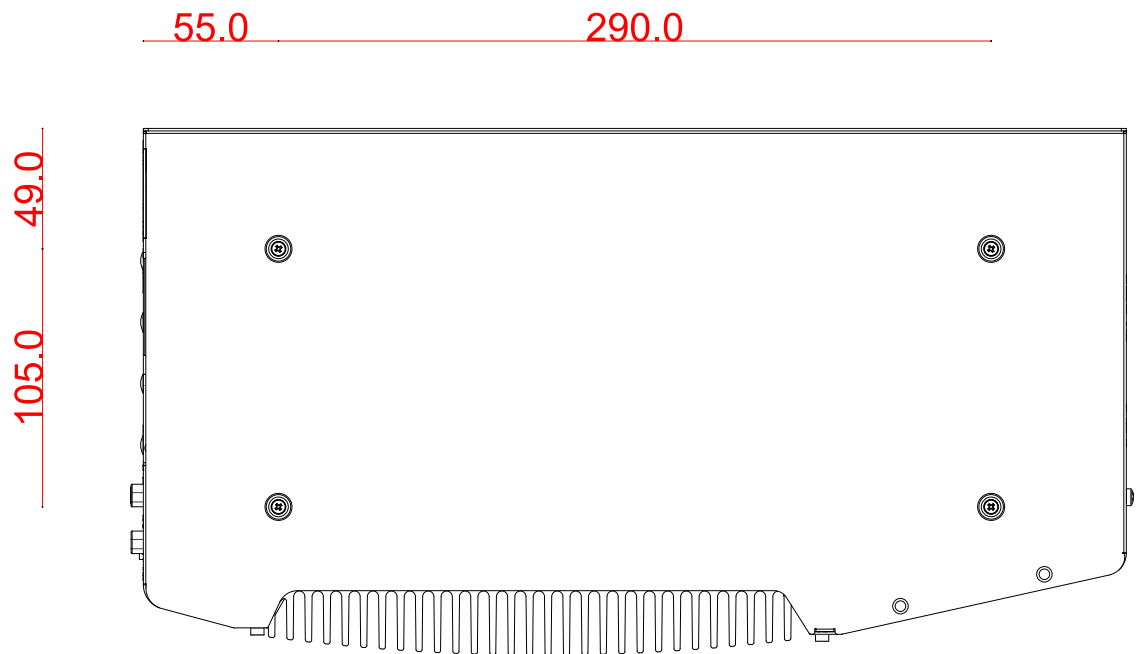
1.2.3 Top Panel View



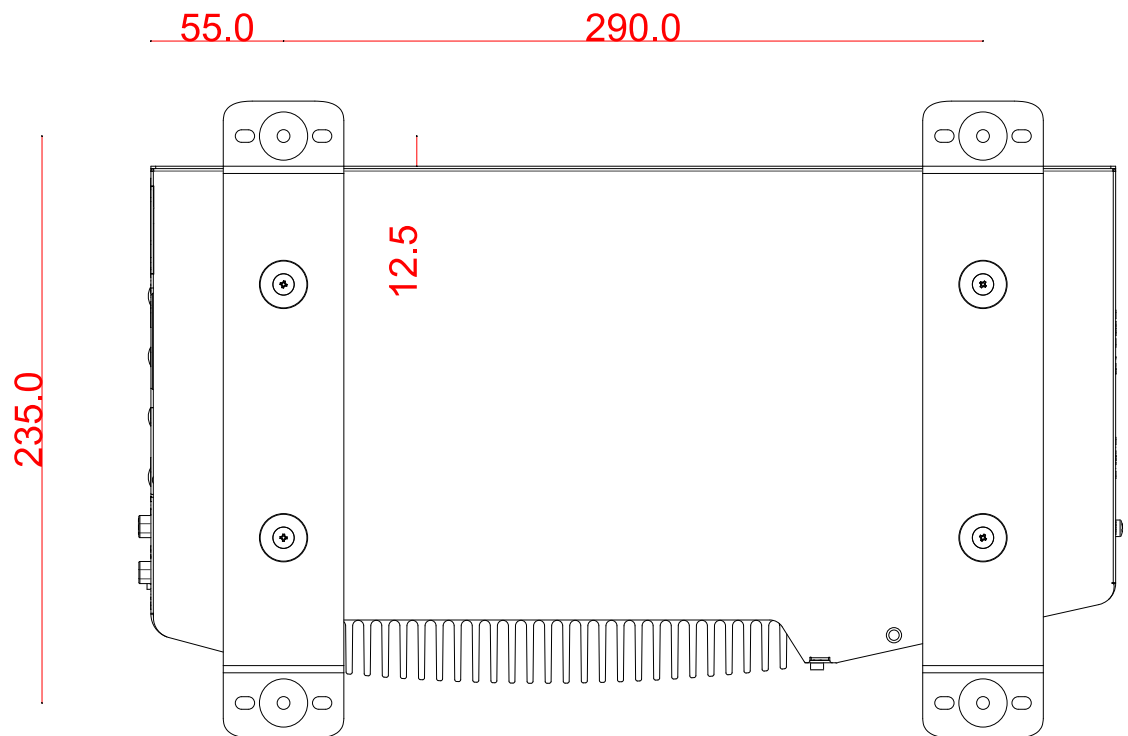
1.2.4 Side Panel View



1.2.5 Bottom View



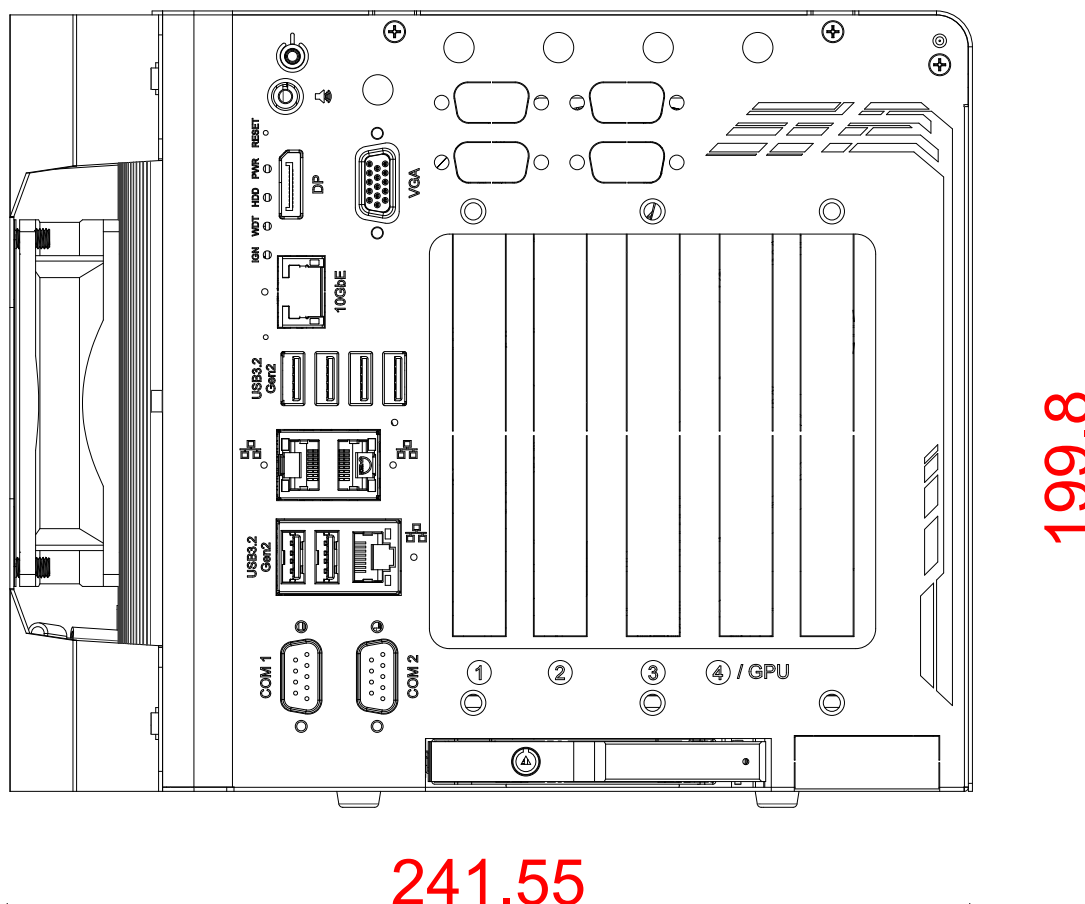
1.2.6 Wall-mount Dimension



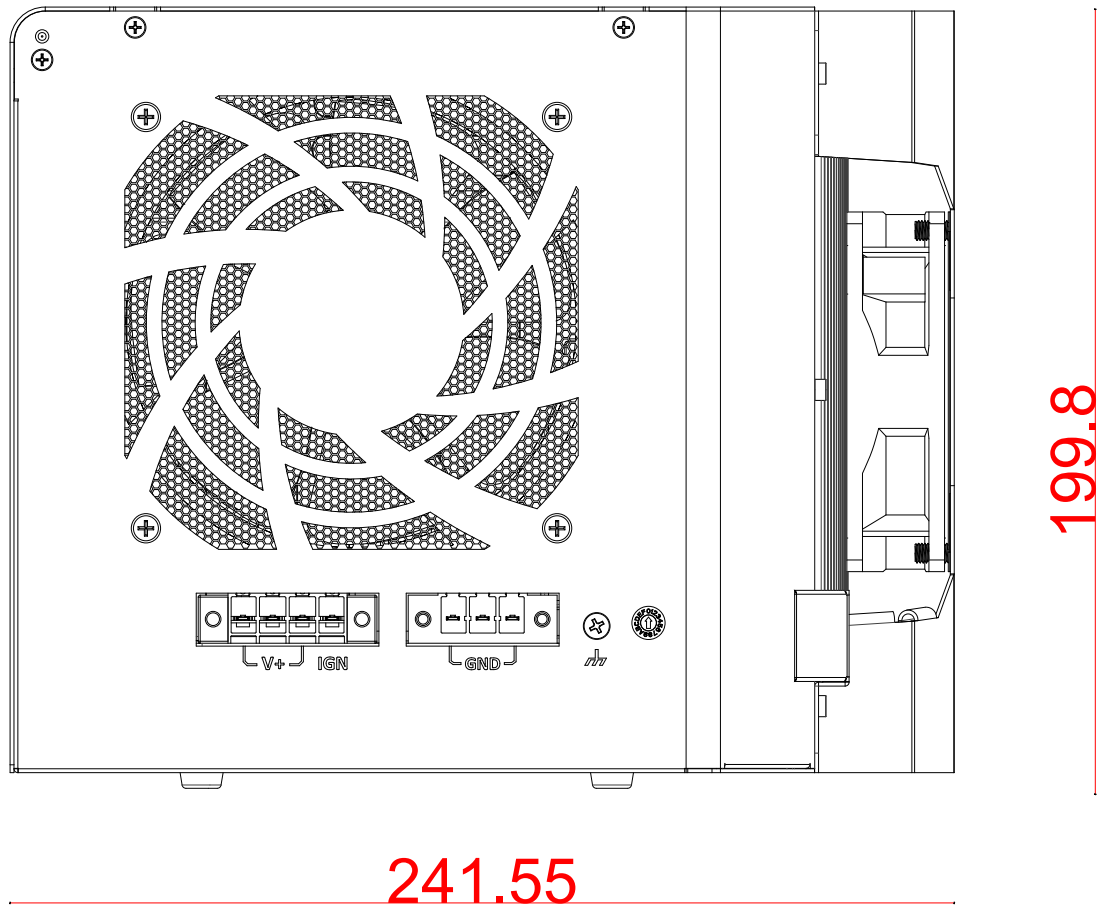


All measurements are in millimeters (mm).

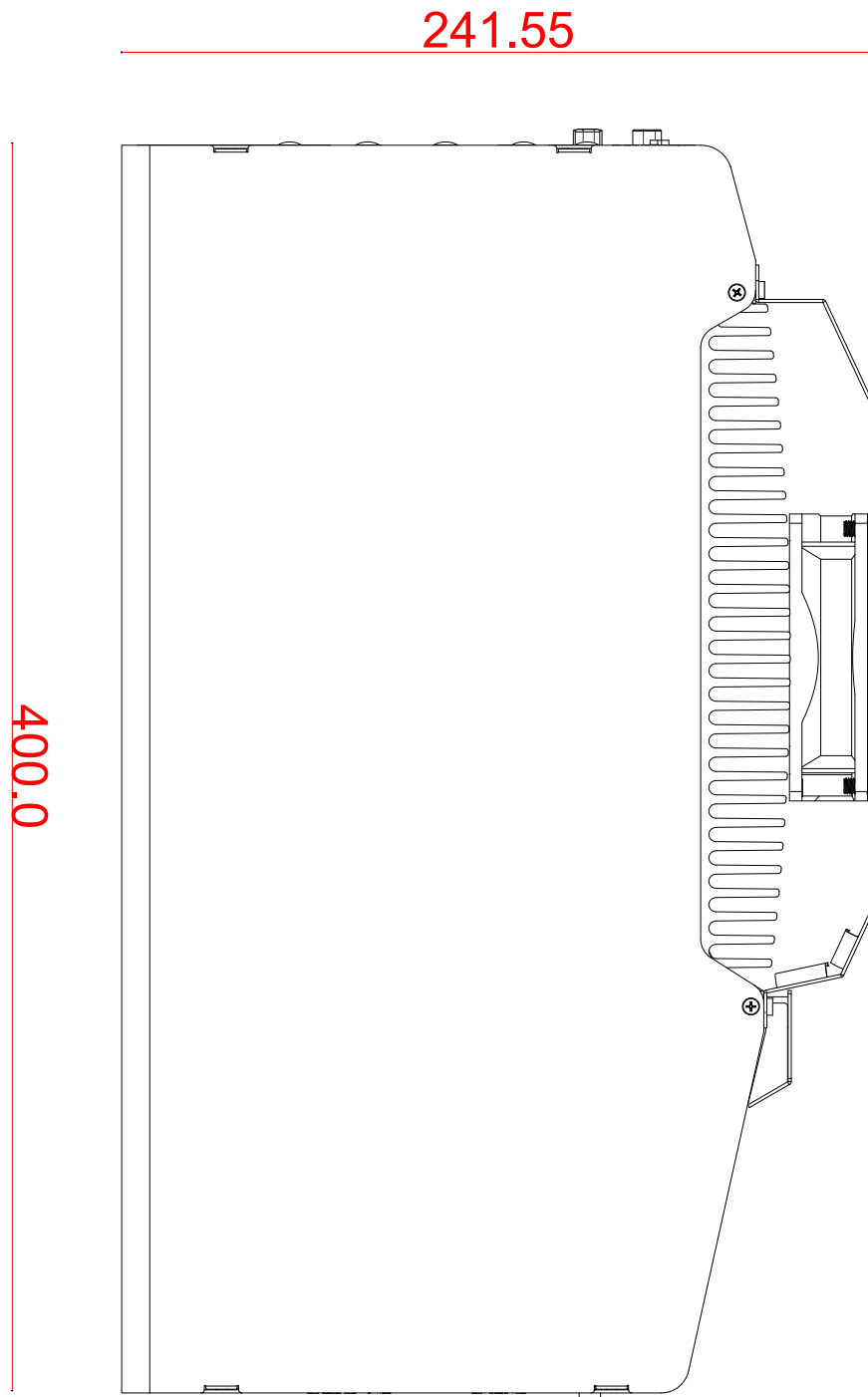
1.3.1 I/O Panel View with Opt. Fan Kit



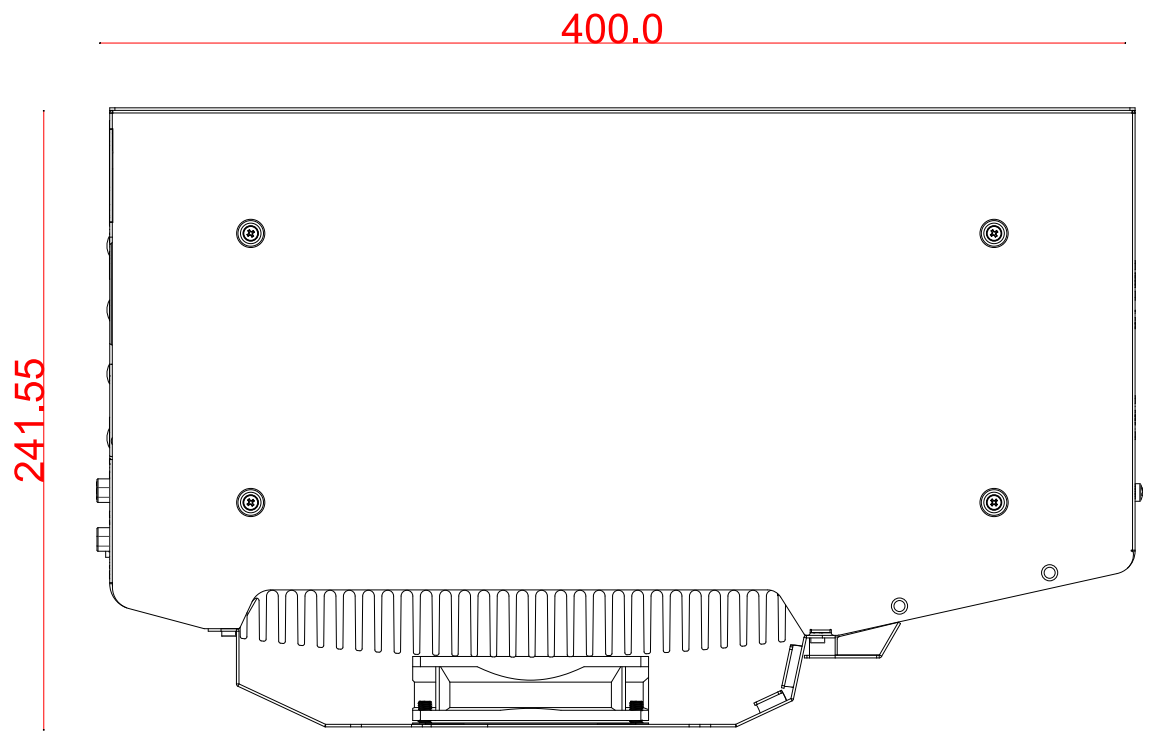
1.3.2 Ignition/ 4/3-Pin Terminal Block Panel View with Opt. Fan Kit



1.3.3 Top Panel View with Opt. Fan Kit



1.3.4 Bottom View with Opt. Fan Kit



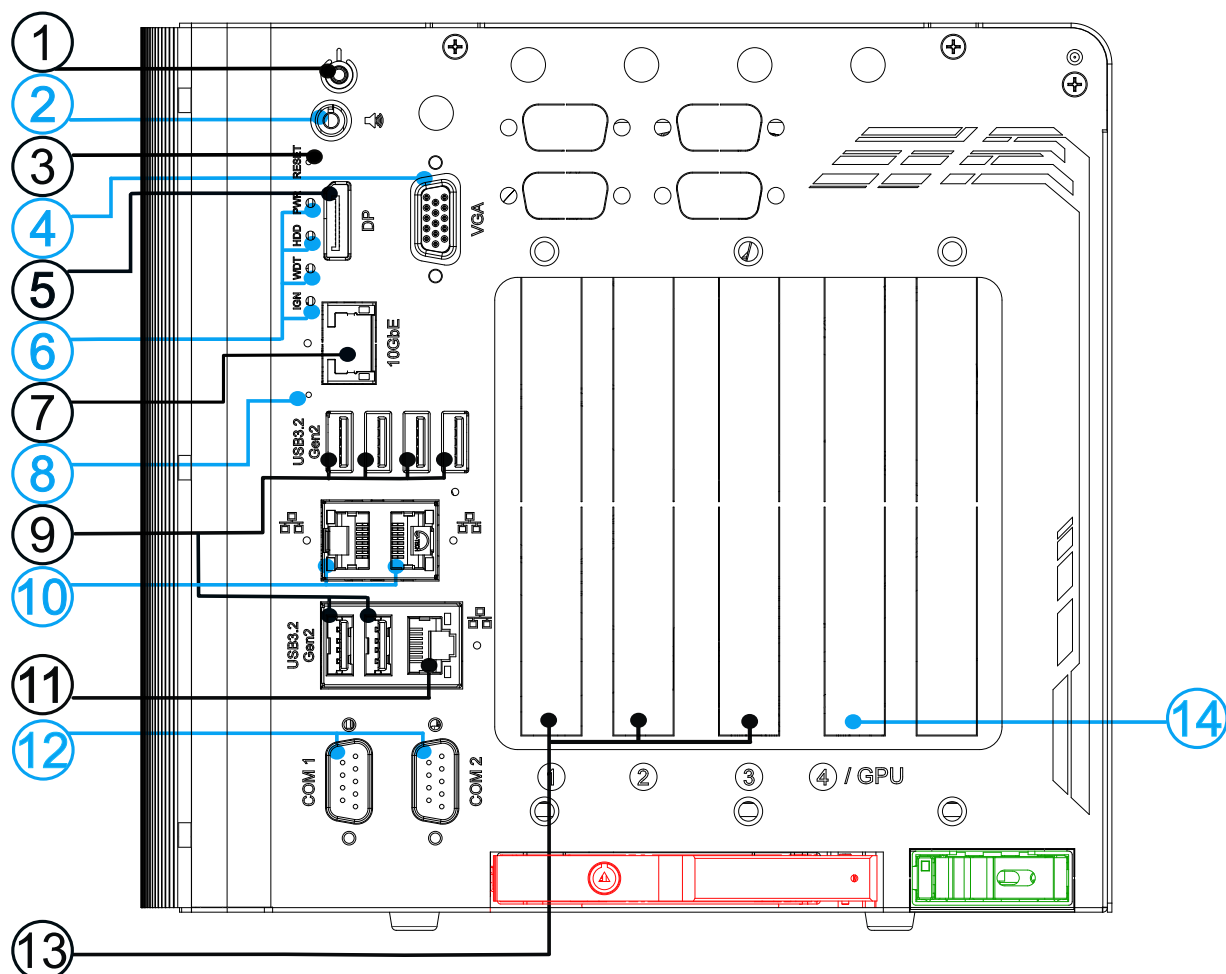
2 System Overview

Upon receiving and unpacking your Nuvo-10108GC system, please check immediately if the package contains all the items listed in the following table. If any item(s) are missing or damaged, please contact your local dealer or Neousys Technology.

2.1 Nuvo-10108GC Packing List

System Pack	Nuvo-10108GC	Qty
1	Nuvo-10108GC system (If you ordered CPU/ RAM/ HDD, please verify these items)	1
	Accessory box, which contains <ul style="list-style-type: none"> ● CPU bracket ● GPU cable sorting peg ● 35cm 12VHPWR(12+4P) male to 12VHPWR(12+4P) male GPU Cable ● Nuvo-10108GC GPU bracket ● Nuvo-10108GC Wall Mount Bracket (without any anti-vibration grommet) ● Anti-Vibrate Grommet ● Hex key for 2.5" SSD Tray ● Standoff, M3-5, H6.5, L4 _ for M.2 2242/3052 B Key standoff ● Terminal Block plug w/Flanges 3-Pole 7.62mm ST _ 3-Pin Terminal Block ● Terminal Block plug w/Flanges 4-Pole 7.62mm ST _ 4-Pin Terminal Block ● Screw Pack 	1 1 1 1 1 8 1 1 1 1 1

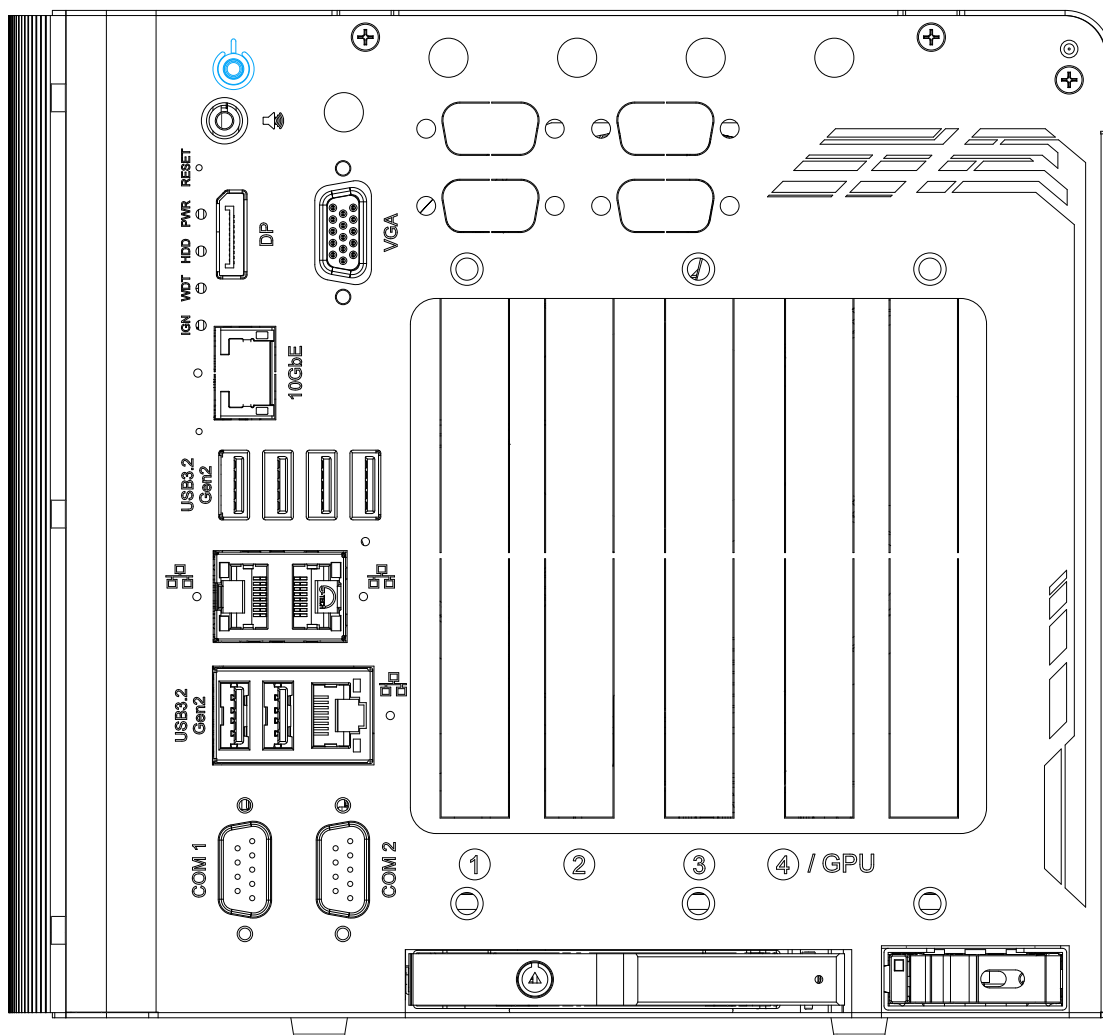
2.2 External I/O Panel



No.	Item	Description
1	Power button	Use this button to turn on or shutdown the system.
2	4-pole 3.5mm speaker-out/microphone-in jack	3.5mm jack for speaker-output and microphone-input.
3	Reset button	Use this button to manual reset the system.
4	VGA port	VGA output supports resolution up to 1920x1200@60Hz
5	DisplayPort	Support display resolutions up to 4096 x 2304. Compatible with HDMI/ DVI via respective adapter/ cable (resolution may vary).
6	LED indicator	From top to bottom, the four system LEDs are PWR (system power), HDD (hard disk drive), WDT (watchdog timer) and IGN (ignition control).
7	10Gb Ethernet (optional)	The optional 10Gb Ethernet port is backward compatible with 5GBASE-T, 2.5GBASE-T, and 1Gb Ethernet protocols.

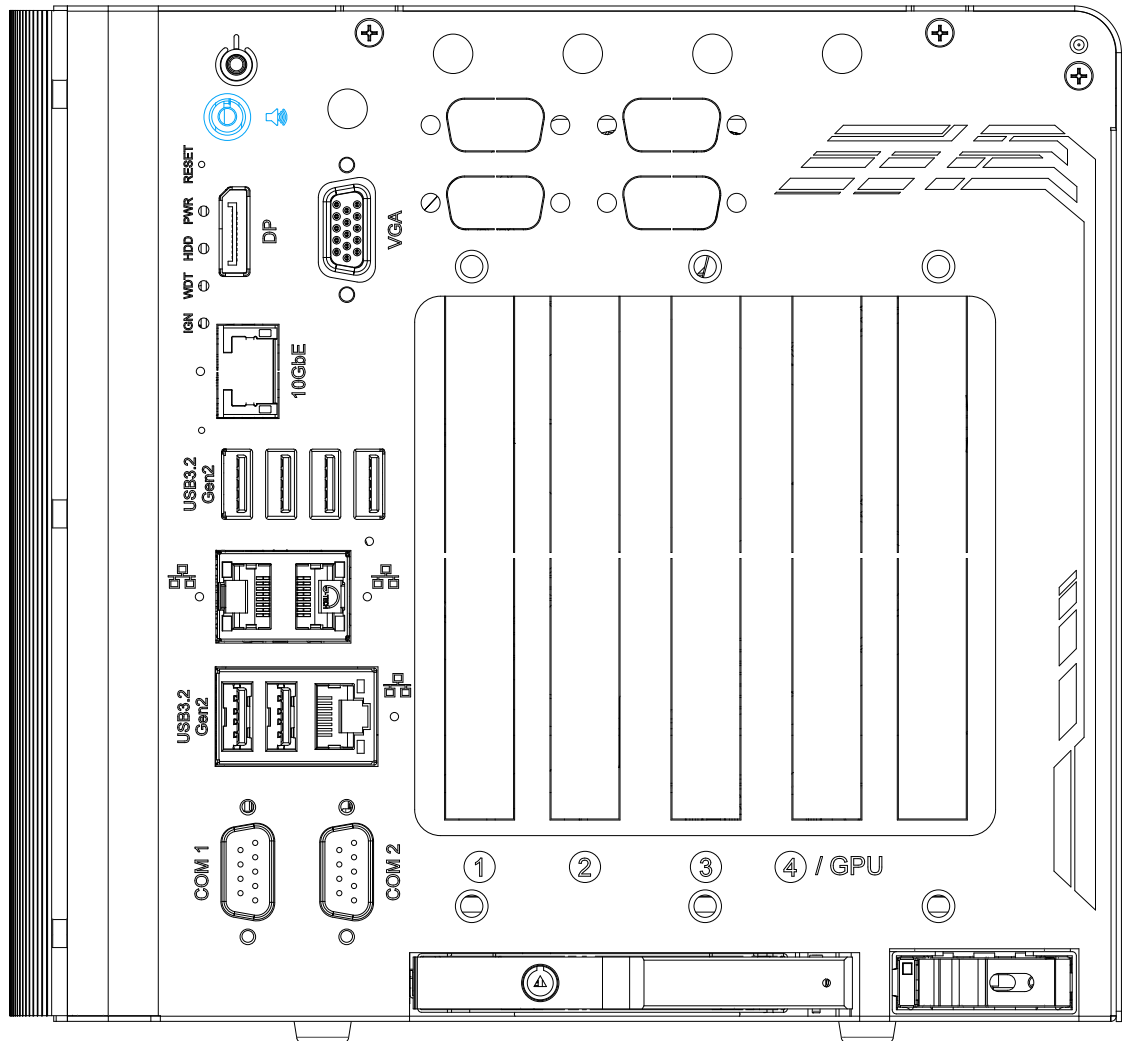
8	CMOS reset button	Use this button to manually reset the motherboard BIOS.
9	USB 3.2 Gen2 port	USB3.2 Gen 2 port (SuperSpeed+) offers up to 10Gbps, twice the bandwidth over existing SuperSpeed USB3.1 Gen. 1 connection. It is also backwards compatible with USB3.0 and USB2.0
10	2.5Gb Ethernet port	2x 2.5Gb Ethernet ports by Intel I226-IT
11	1Gb Ethernet port	1x 1Gb Ethernet port by Intel I219-LM
12	COM port	The software-selectable RS-232/422/485 ports. The operation mode of COM1 and COM2 can be set in BIOS.
13	PCIe slots	3x PCIe x8 slots @ Gen3, 4-lanes expansion slot
14	GPU slot	Primary PCIe x16 slot @ Gen4, 8-lanes expansion slot
Area in green		M.2 2280 SSD front-accessible tray
Area in red (optional)		2.5" HDD/SSD front-accessible tray


2.2.1 Power Button



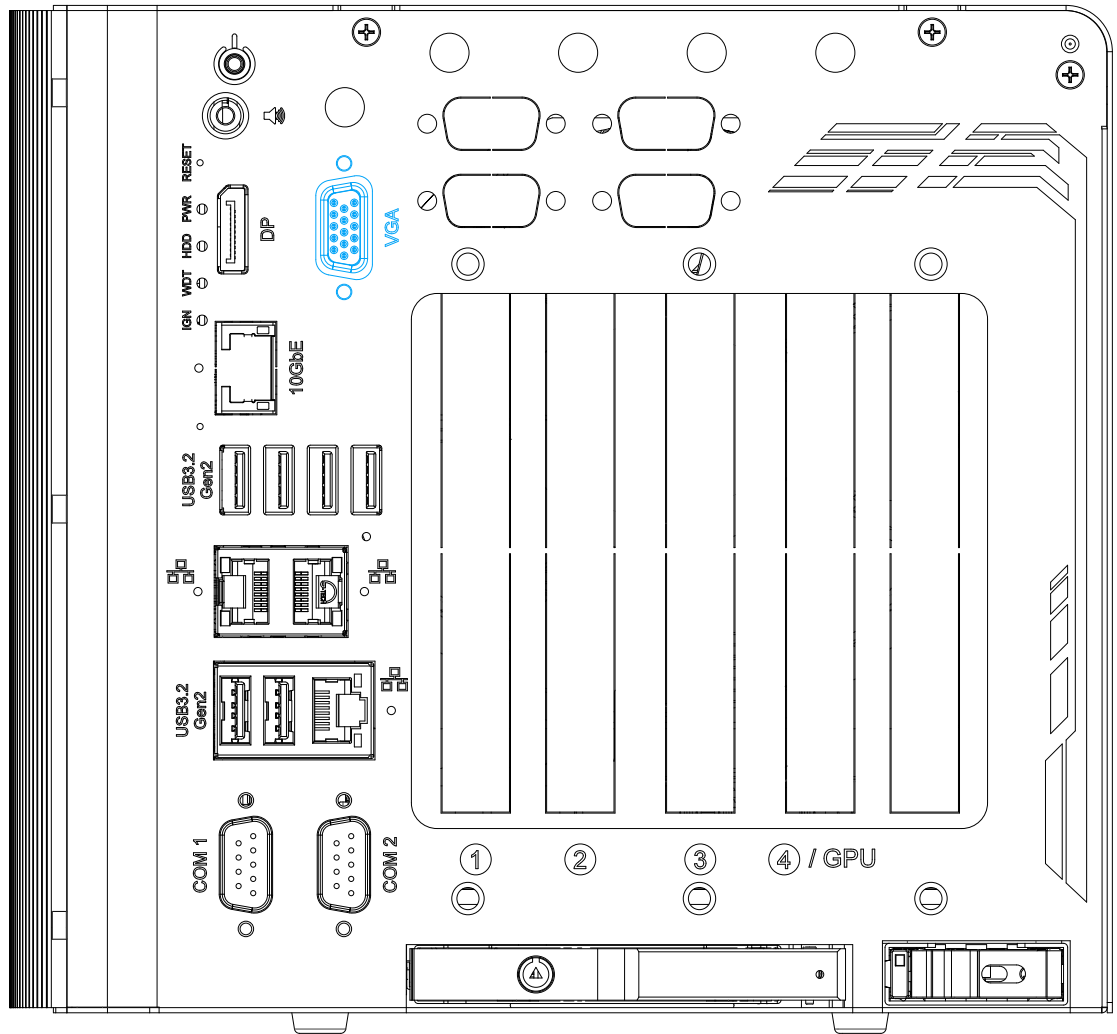
The power button is a non-latched switch for ATX mode on/off operation. To turn on the system, press the power button and the PWR LED should light-up green. To turn off the system, issuing a shutdown command in OS is preferred, or you can simply press the power button. To force shutdown when the system freezes, press and hold the power button for 5 seconds. Please note that there is a 5-second interval between on/off operations (i.e. once the system is turned off, there is a 5-second wait before you can power-on the system).

2.2.2 4-pole 3.5mm Speaker-out/ Microphone-in Jack



The system audio function uses high definition audio. There is a female 4-pole  audio jack for headphone (speaker) output and microphone input. To utilize the audio function in Windows, you need to install corresponding drivers for both Intel® chipset and audio device drivers.

2.2.4 VGA Port



The VGA port is the most common video display connection. The VGA output supports up to 1920x1200@60Hz resolution.

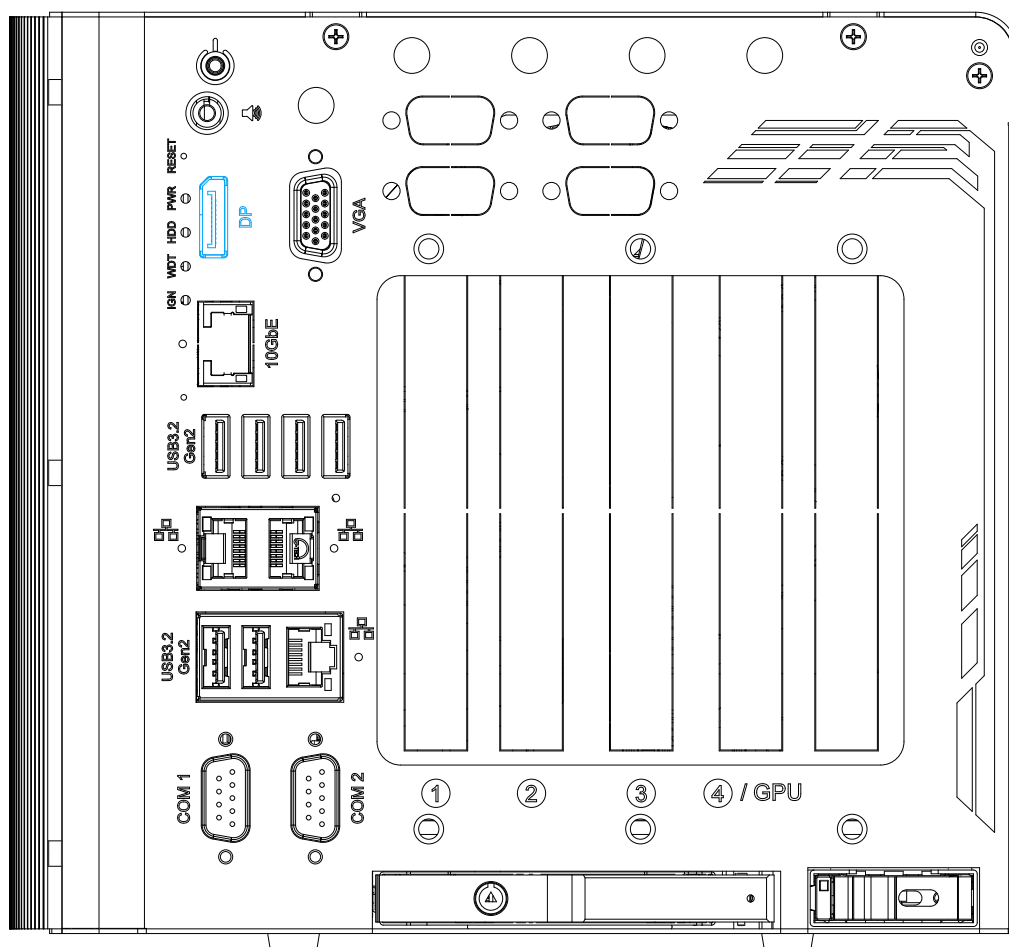
The system supports dual independent display outputs by connecting display devices to VGA and DisplayPort connection. To support multiple display outputs and achieve best VGA output resolution in Windows, you need to install corresponding graphics drivers. Please refer to section [OS Support and Driver Installation](#) for details.



NOTE

Please make sure your VGA cable includes SDA and SCL (DDC clock and data) signals for correct communication with monitor to get resolution/timing information. A cable without SDA/ SCL can cause blank screen on your VGA monitor due to incorrect resolution/timing output.

2.2.5 DisplayPort



The DisplayPort (DP) output is a digital display interface that mainly connect video source and carry audio to a display device. When connecting a DP, it can deliver up to 4K UHD (4096 x 2304) in resolution. The system is designed to support passive DP adapter/ cable. You can connect to other display devices using DP-to-HDMI cable or DP-to-DVI cable.



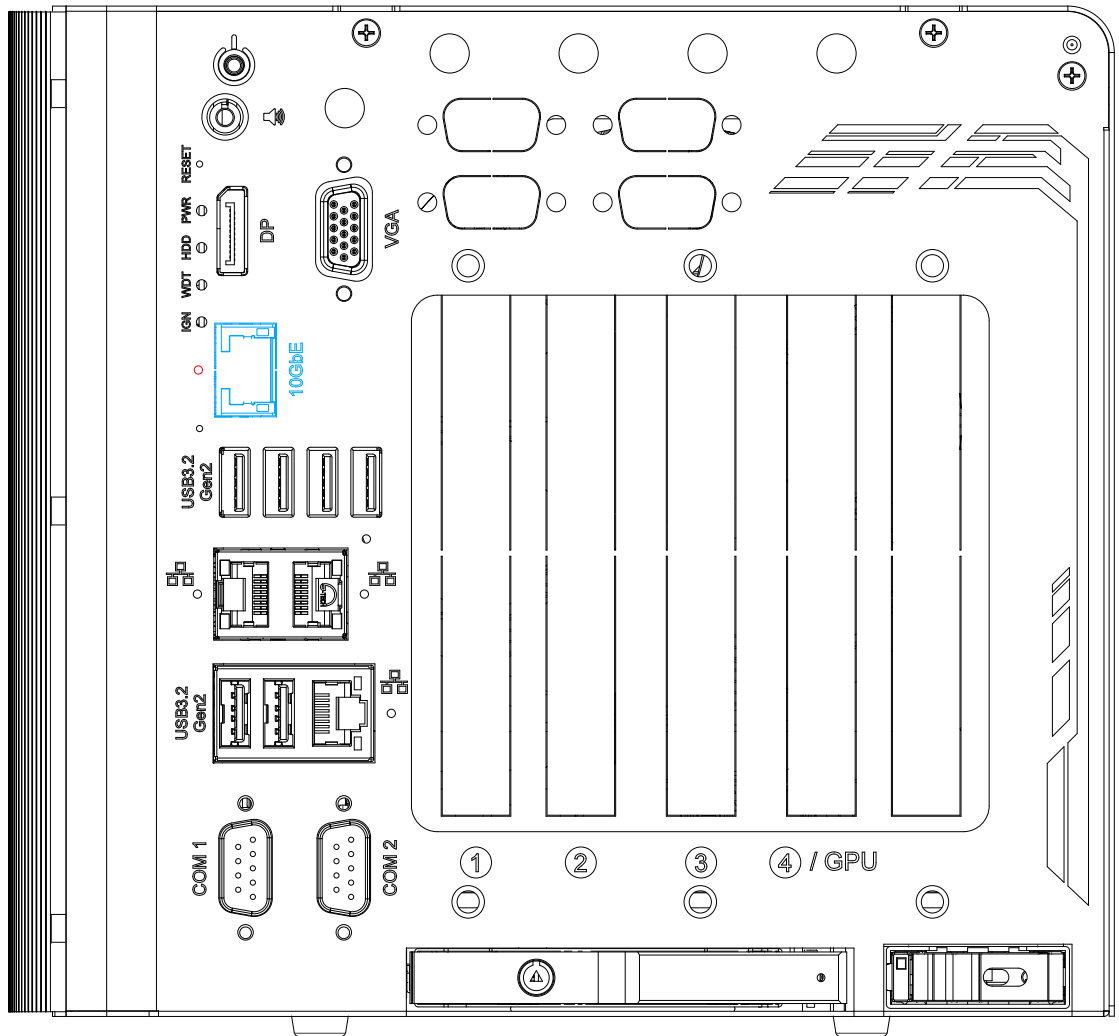
DP-to-HDMI



DP-to-DVI

The system supports dual independent display outputs by connecting display devices to VGA and DisplayPort connection. To support multiple display outputs and achieve best DisplayPort output resolution in Windows, you need to install corresponding graphics drivers. Please refer to section [OS Support and Driver Installation](#) for details.

2.2.7 10Gb Ethernet Port (Optional)



The optional high-speed data transmission 10G Ethernet port is backward compatible with 5GBASE-T and 2.5GBASE-T to work with NBASE-T industrial cameras. Indicated in **red** is a screw-lock hole for the corresponding Ethernet port.

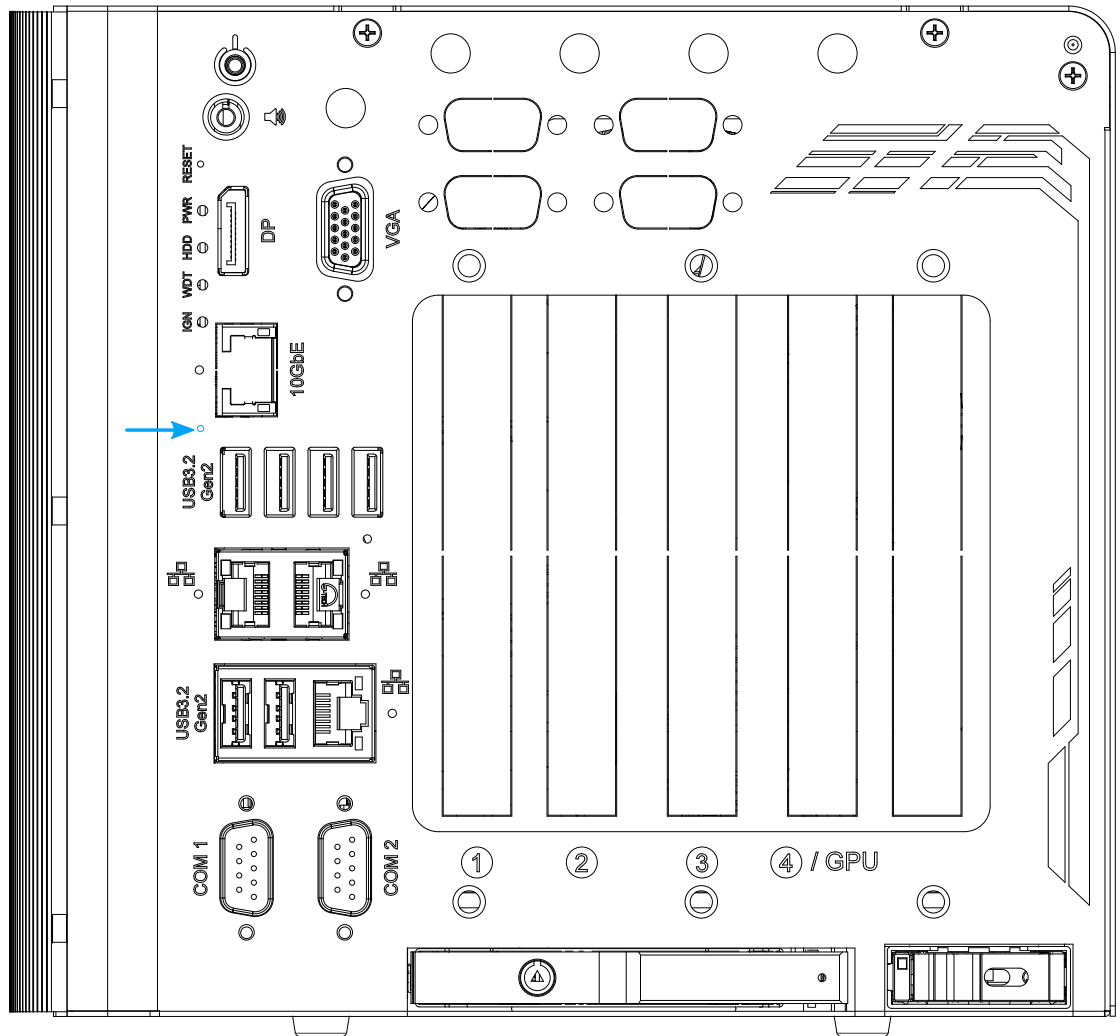
Speed LED (Top)

LED Color	Status	Description
Green or Orange	Off	Ethernet port is disconnected
	Orange	10/ 100/ 1000/ 2500/ 5000 Mbps
	Green	10000 Mbps

Active/Link LED (Bottom)

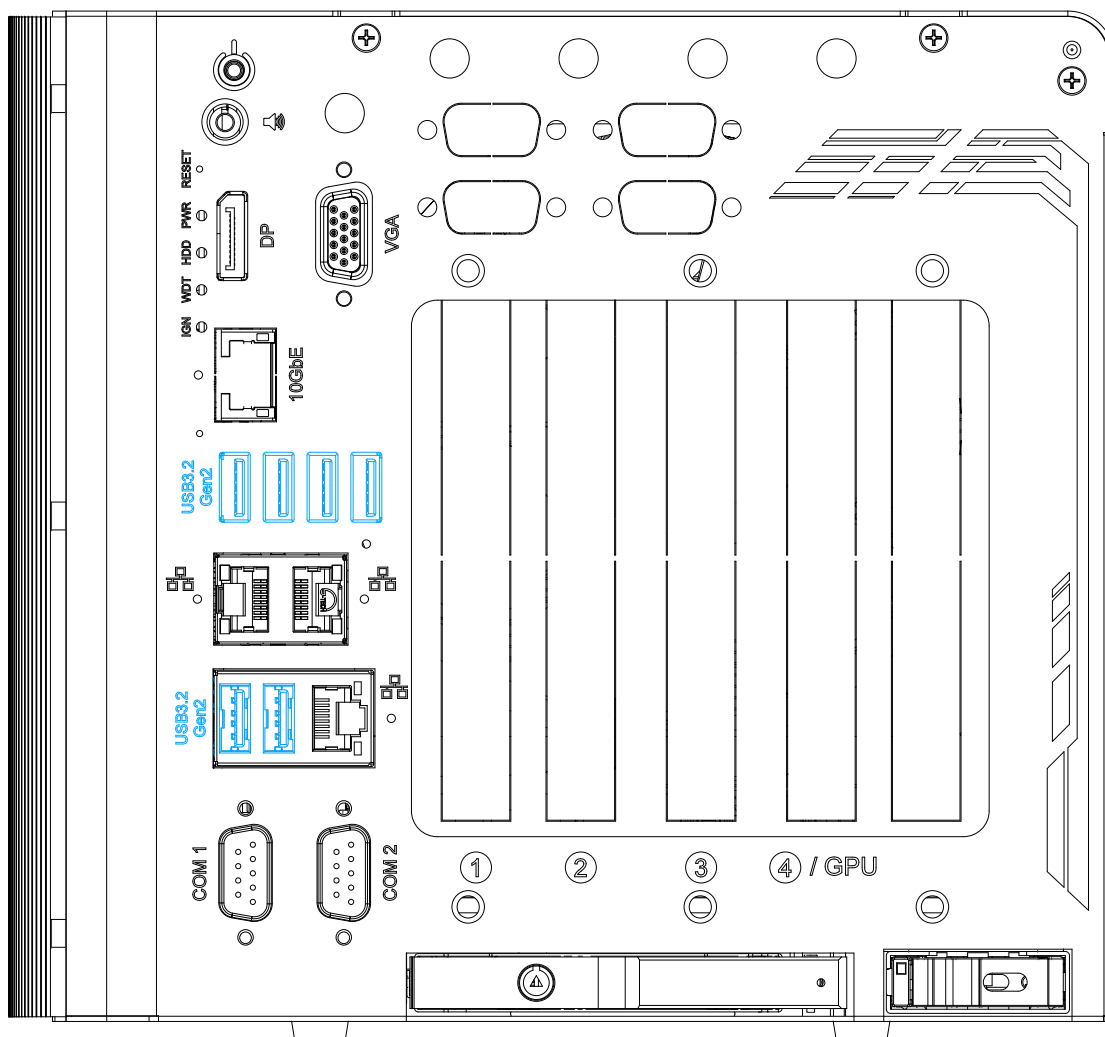
LED Color	Status	Description
Green	Off	Ethernet port is disconnected
	On	Ethernet port is connected and no data transmission
	Flashing	Ethernet port is connected and data is transmitting/receiving

2.2.8 CMOS Reset Button



Positioned between 10GbE and USB ports, indicated by the **blue arrow**, the CMOS Reset button is used to manually reset the motherboard BIOS in case of system halt or malfunction. To avoid unexpected operation, it is purposely placed behind the panel. To reset, please use the tip of a pen, press and hold for at least 5 seconds to reset the BIOS.

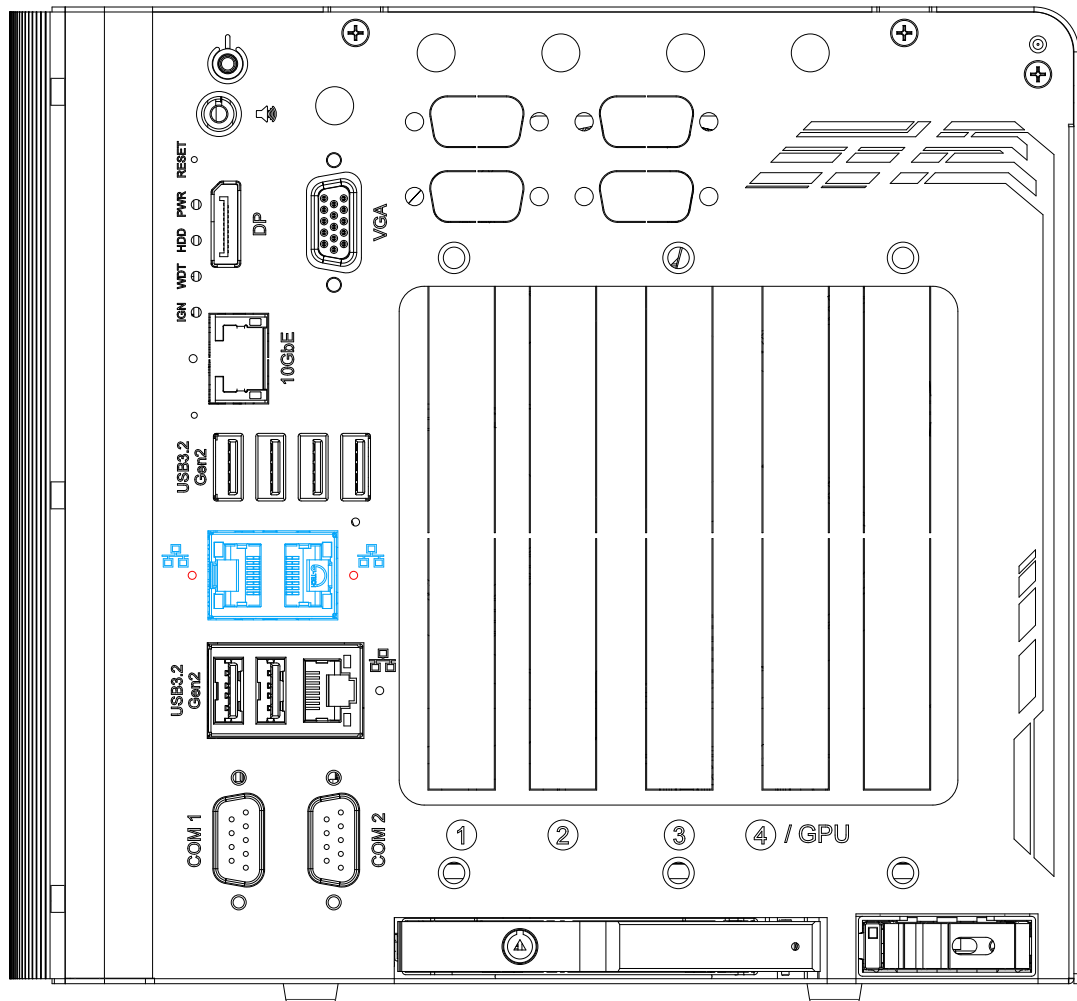
2.2.9 USB3.2 Gen 2 Port



The system's USB 3.1 Gen 2 ports (10Gbps) are implemented via native xHCI (eXtensible Host Controller Interface) controller and are backward compatible with USB3.1 Gen.1 USB 2.0, USB 1.1 and USB 1.0 devices. Legacy USB is also supported so you can use USB keyboard/mouse in DOS environment.

xHCI driver is supported natively in Windows 10, therefore you do not need to install xHCI driver in prior to utilize USB functions.

2.2.10 2.5Gb Ethernet Port



The systems has two 2.5Gb Ethernet ports feature panel screw fix holes (indicated in **red**). Each port has one dedicated PCI Express link for maximum network performance. Please refer to the table below for LED connection statuses.

Active/Link LED

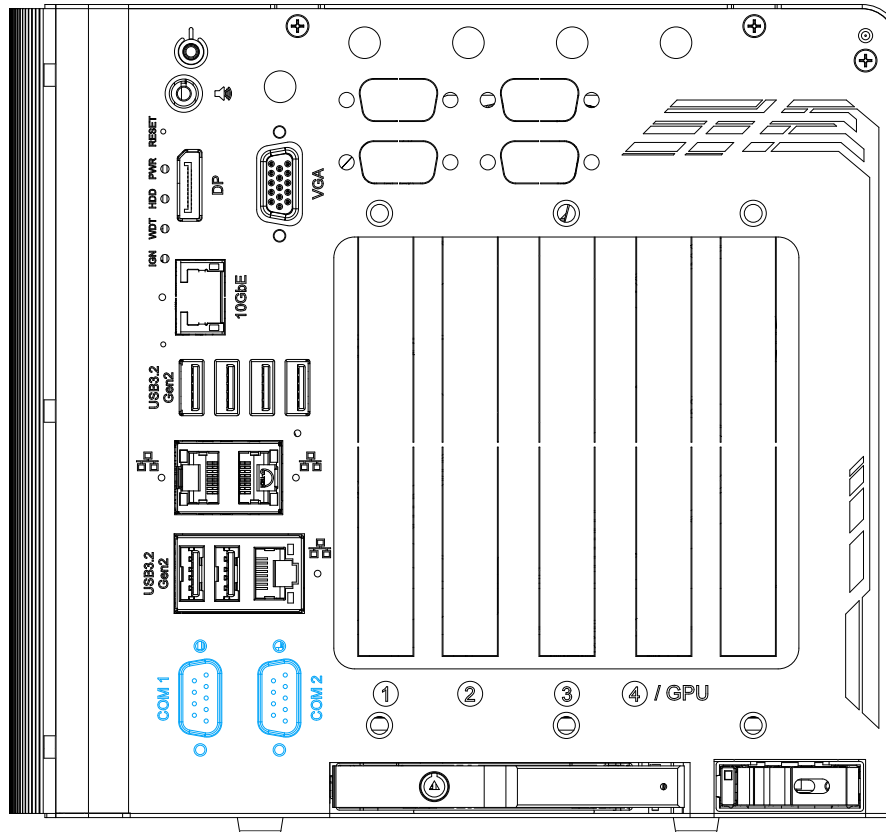
LED Color	Status	Description
Orange	Off	Ethernet port is disconnected
	On	Ethernet port is connected and no data transmission
	Flashing	Ethernet port is connected and data is transmitting/receiving

Speed LED

LED Color	Status	Description
Red or Green	Off	10 Mbps
	Green	100 Mbps
	Red	1000/ 2500 Mbps

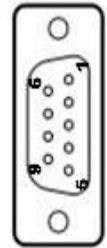
To utilize the Ethernet ports in Windows, you need to install corresponding driver for the Ethernet controller.

2.2.12 COM Port



The two COM ports are implemented using industrial-grade ITE8786 Super IO chip (-40 to 85°C) and provide up to 115200 bps baud rate.

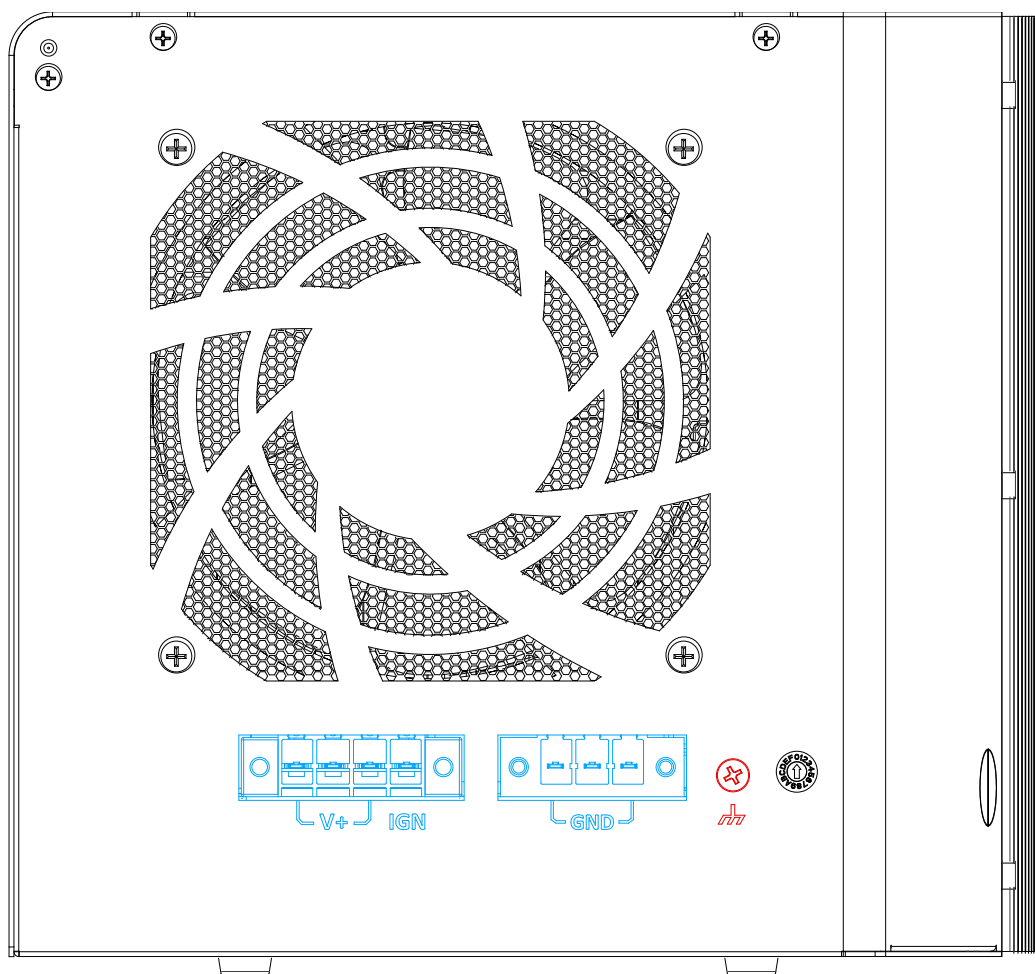
COM1 and COM2 (in **red**) are software-configurable RS-232/422/485 ports. COM3 and COM4 (in **blue**) are standard 9-wire RS-232 ports. The operation mode of COM1 and COM2 can be set in BIOS setup utility. The following table describes the pin definition of COM ports.



COM Port Pin Definition

Pin#	COM1 & COM2		
	RS-232 Mode	RS-422 Mode	RS-485 Mode (Two-wire 485)
1	DCD		
2	RX	422 TXD+	485 TXD+/RXD+
3	TX	422 RXD+	
4	DTR	422 RXD-	
5	GND	GND	GND
6	DSR		
7	RTS		
8	CTS	422 TXD-	485 TXD-/RXD-
9	RI		

2.3 Terminal Block with Ignition Control



The system accepts a wide range of DC power input from 8 to 48V via a 4-pin and 3-pin pluggable terminal block, which is fit for field usage where DC power is provided. The screw clamping mechanism on the terminal block offers connection reliability when wiring DC power. In addition to DC power input, this terminal block can also accept ignition signal input (IGN) with a grounding point (indicated in **red**) for in-vehicle applications.

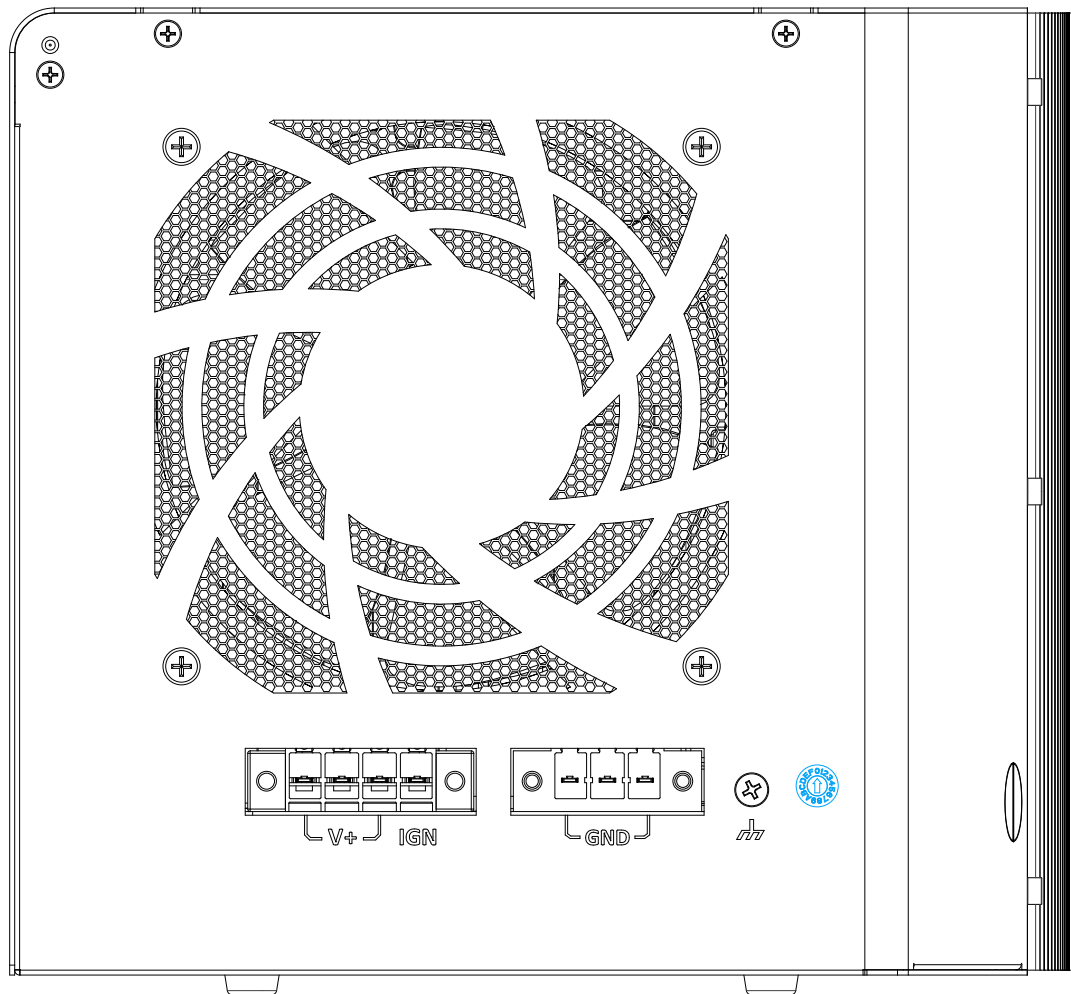
The grounding point may ease Signal Integrity (SI), Electrostatic Discharge (ESD), and Electromagnetic Compatibility (EMC) issues. The effects, however, depend on the operating environment. Therefore, there is no guaranteed benefits in connecting the point.



WARNING

Please make sure the voltage of DC power is correct before you connect it to the system. Supplying a voltage over 48V will damage the system.

2.4 Ignition Control Switch



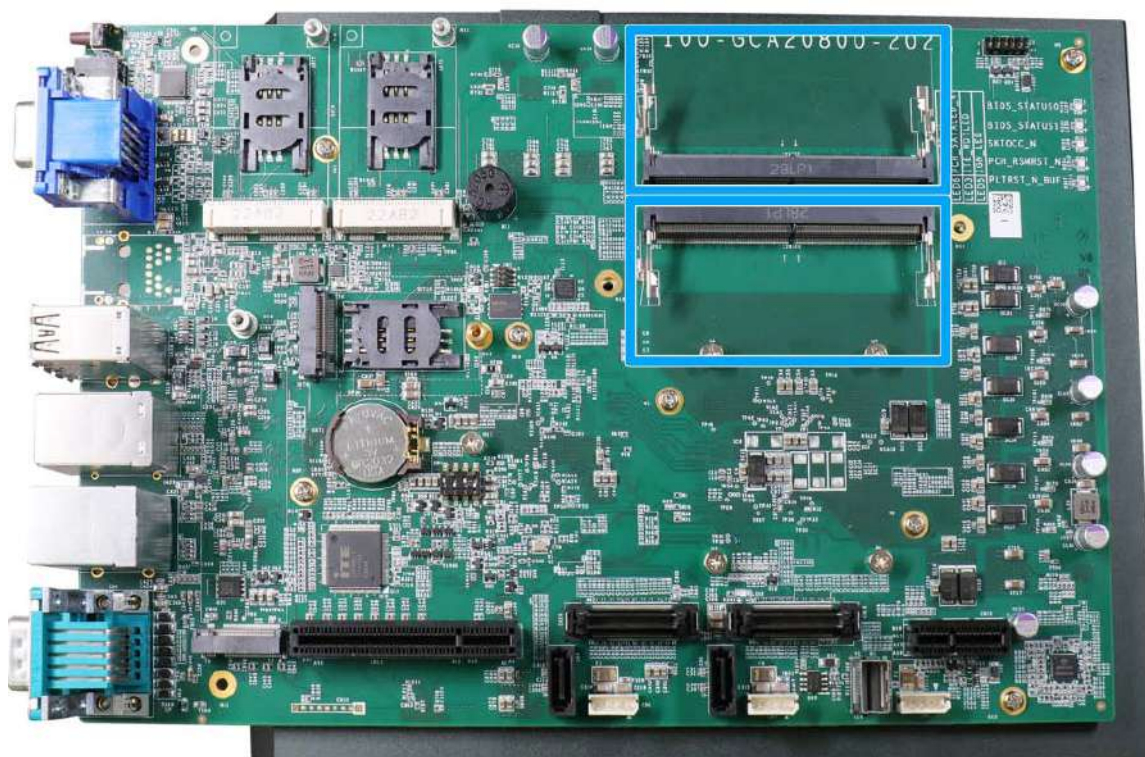
The ignition power control switch features multiple modes for pre and post ignition settings. Please refer to the section Ignition Power Control for details. Please use a flathead screwdriver to adjust the position of the ignition power control switch.

For details, please refer to the section [Ignition Power Control](#) for details

2.5 Internal I/O Functions

In addition to I/O connectors on the front panel, the system also provides internal on-board connectors, such as remote on/off control, LED status output, internal USB 2.0 ports, etc. In this section, we'll illustrate these internal I/O functions.

2.5.1 SODIMM DRAM Slot



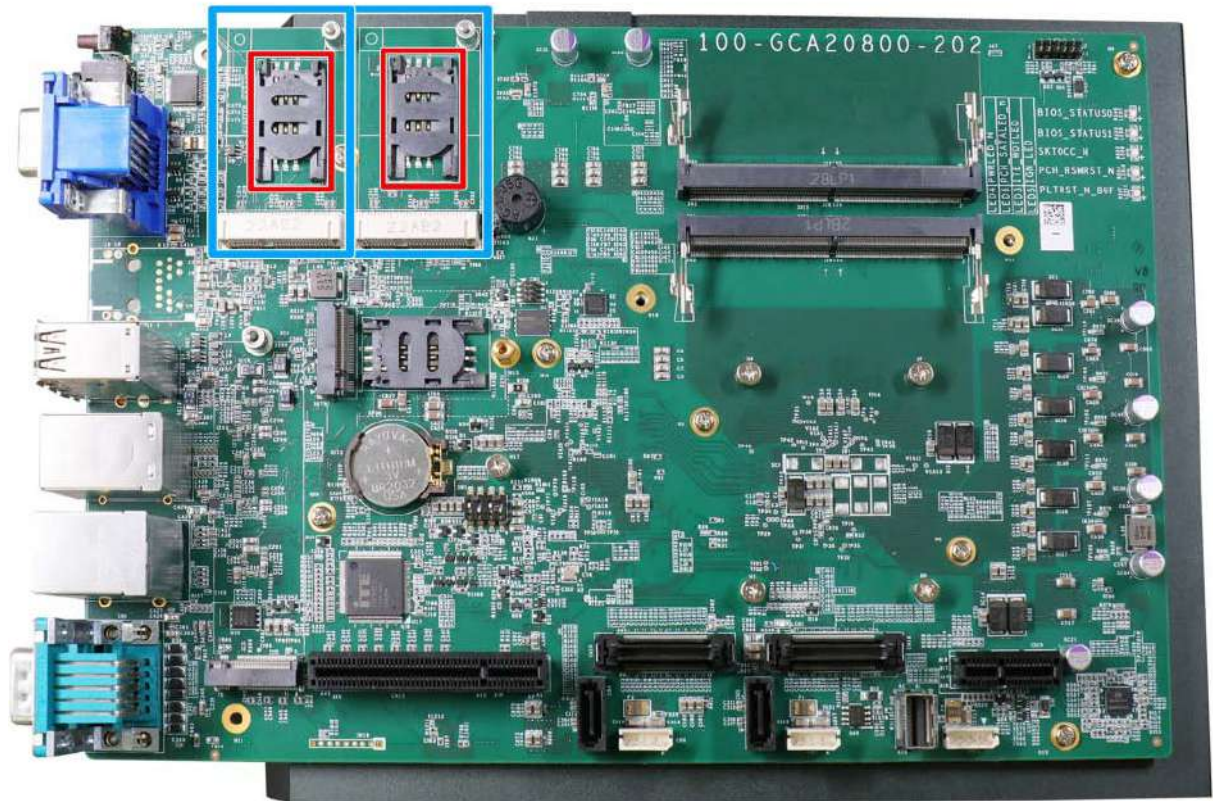
The system motherboard supports two ECC/ non-ECC SODIMM sockets for installing DDR5 memory module up to 128GB. Each slot supports single module DDR5 4800MHz SODIMM up to 64GB capacity.



NOTE

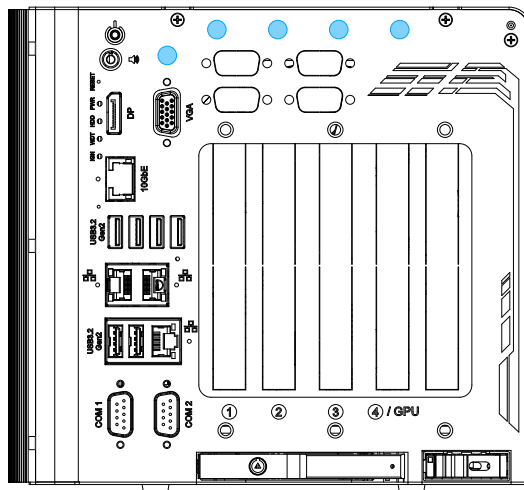
When changes are made to DRAM module(s), such as additionally install or remove and reinstall (into the same/ different slot, it will result in an approximately 30~60 seconds delay when booting up for the first time after such change(s).

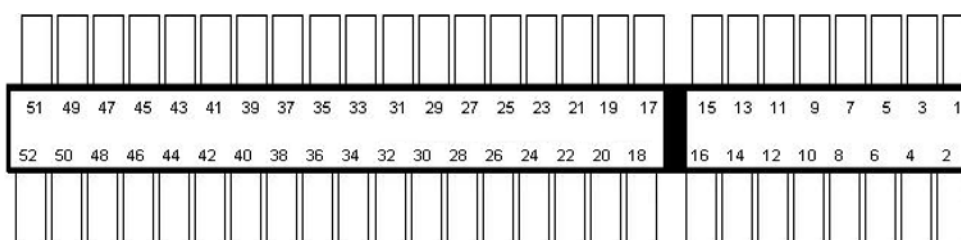
2.5.2 mini-PCle Socket & Pin Definition



The system provides two mini-PCle sockets (indicated in **blue**) that is in compliance with mini-PCle specification rev. 1.2. The mini-PCle sockets are designed with a SIM card (slot indicated in **red**) support. With a SIM card installed, your system can access the internet via your network provider's 4G/ 3G network.

For wireless (WiFi/ 4G/ 3G) communication, multiple SMA antenna apertures can be located on the IO panel.



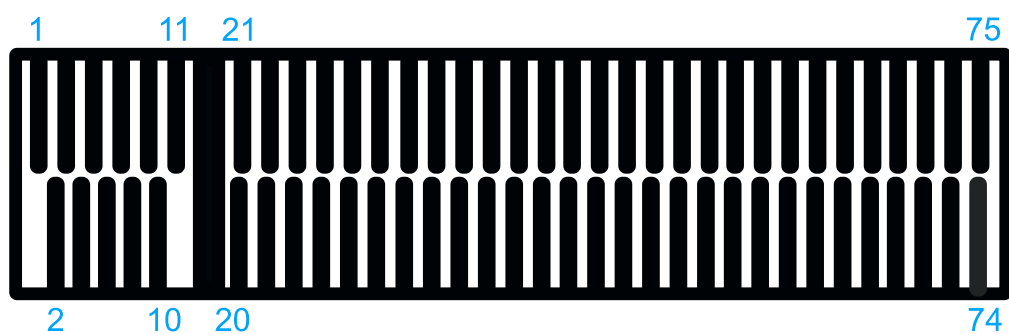
mini-PCle socket definition

Pin	Signal (mPCle)	Pin #	Signal (mPCle)
1	WAKE#	2	+3.3Vaux
3	-	4	GND
5	-	6	+1.5V
7	CLKREQ#	8	UIM_PWR
9	GND	10	UIM_DATA
11	REFCLK-	12	UIM_CLK
13	REFCLK+	14	UIM_RESET
15	GND	16	UIM_VPP
Mechanical Key			
17	Reserved* (UIM_C8)	18	GND
19	Reserved* (UIM_C4)	20	W_DISABLE#
21	GND	22	PERST#
23	PERn0	24	3.3V
25	PERp0	26	GND
27	GND	28	+1.5V
29	GND	30	SMB_CLK
31	PETn0	32	SMB_DATA
33	PETp0	34	GND
35	GND	36	USB_D-
37	GND	38	USB_D+
39	3.3V	40	GND
41	3.3V	42	-
43	GND	44	-
45	Reserved	46	-
47	Reserved	48	+1.5V
49	Reserved	50	GND
51	Reserved	52	3.3V

**WARNING**

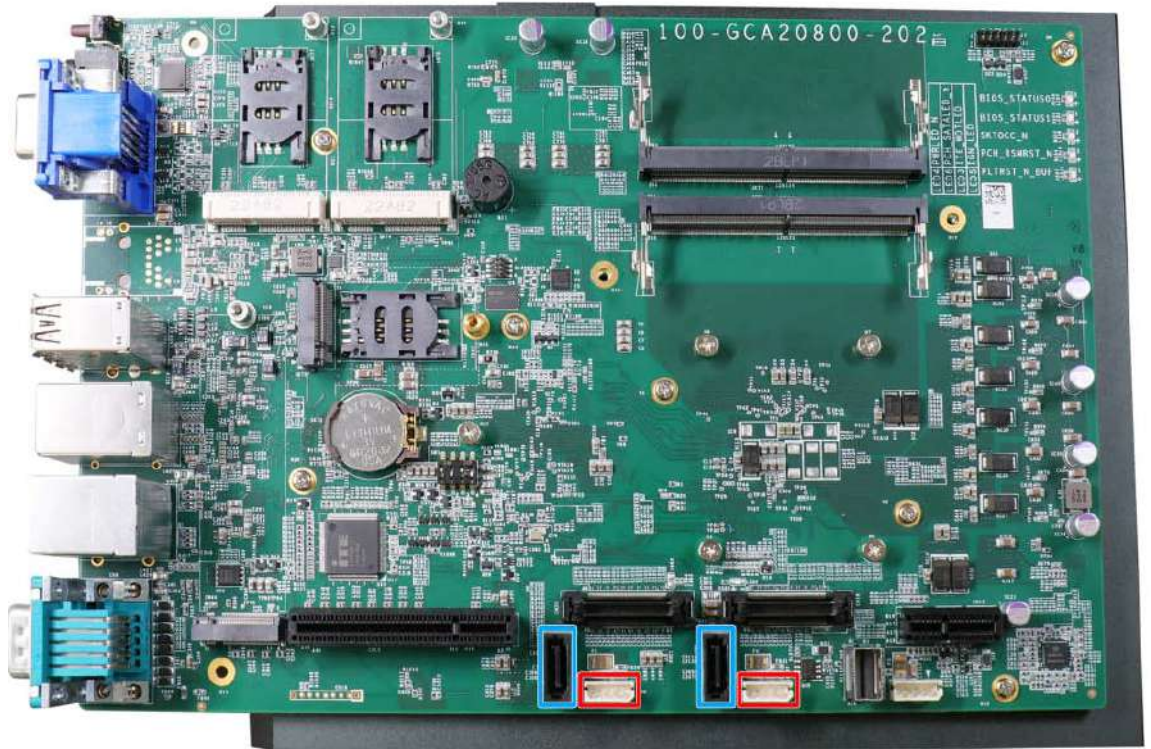
Some off-the-shelf mini-PCle 4G modules are not compliant to standard mini-PCle interface. They use 1.8V I/O signals instead of standard 3.3V I/O and may have signal conflict. Please consult with Neosys for compatibility when in doubt!

Installing an incompatible 4G module may damage the system or the module itself may be damaged.

M.2 (B Key) Slot Pin Definition

Pin #	Signal	Pin #	Signal
1	NC	2	+3V3
3	GND	4	+3V3
5	GND	6	POWER_OFF_N
7	USB_D+	8	W_DISABLE_N
9	USB_D-	10	NC
11	GND	12	-
13	-	14	-
15	-	16	-
17	-	18	-
19	-	20	NC
21	NC	22	NC
23	Pull-high +1V8	24	NC
25	NC	26	Pull-high +3V3
27	GND	28	NC
29	USB32RxN	30	M2B_SIM1_RST
31	USB32RxP	32	SIM1)CLK
33	GND	34	SIM1_DATA
35	USB32TxN	36	SIM1_PWR
37	USB32TxP	38	NC
39	GND	40	NC
41	PCIE_RxN	42	NC
43	PCIE_RxP	44	NC
45	GND	46	NC
47	PCIE_TxN	48	NC
49	PCIE-TxP	50	PLTRST_N
51	GND	52	CLKREQ_N
53	PCIE_CLKOUT_N	54	NC
55	PCIE_CLKOUT_P	56	NC
57	GND	58	NC
Mechanical Key			
67	RESET_N	68	SUSCLK_M2B
69	Pull-high +3V3SUS	70	+3V3
71	GND	72	+3V3
73	GND	74	+3V3
75	NC		

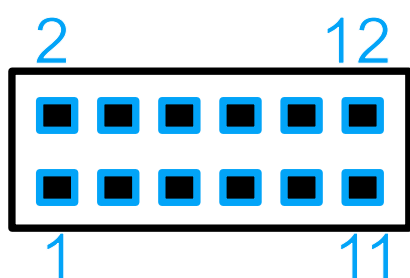
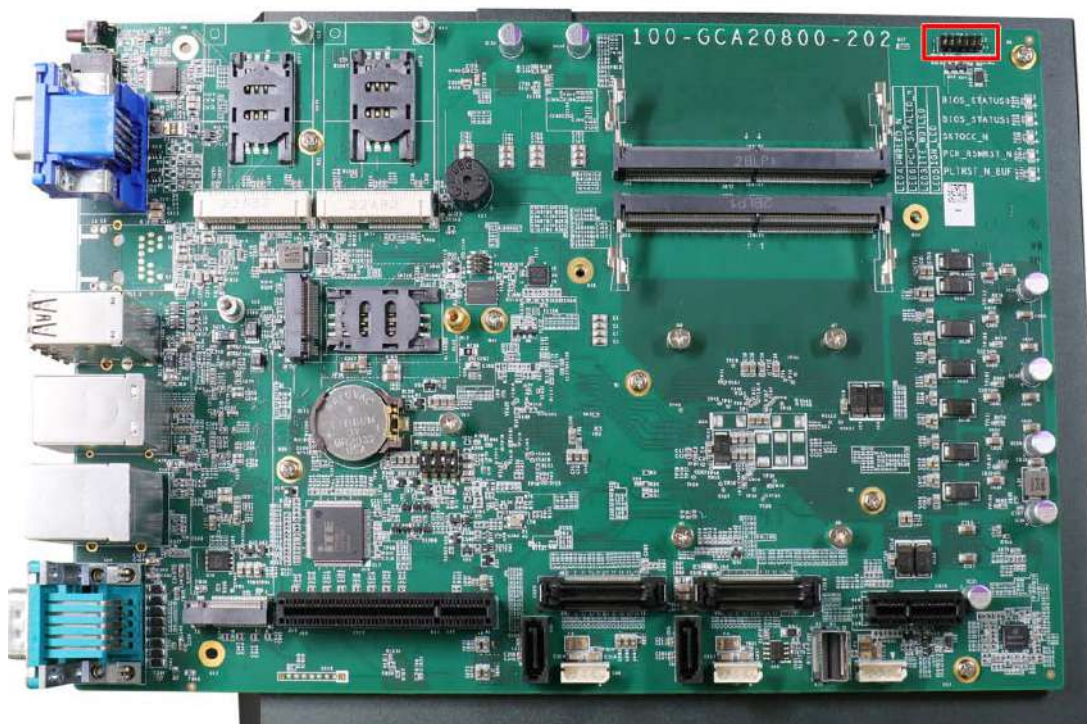
2.5.4 SATA Ports



The system provides two SATA ports which support Gen2, 3 Gb/s SATA signals. Each SATA port (indicated in **blue**) features a 7-pin SATA connector and a 4-pin power connector.

The power connector (indicated in **red**) each accommodates a 2.5" HDD/ SSD in internal HDD bracket. Standard 22-pin SATA connectors are provided with the system. You may refer to the SATA Configuration section for SATA settings.

2.5.5 Status LED Output & Remote On/ Off Control and Pin Definition



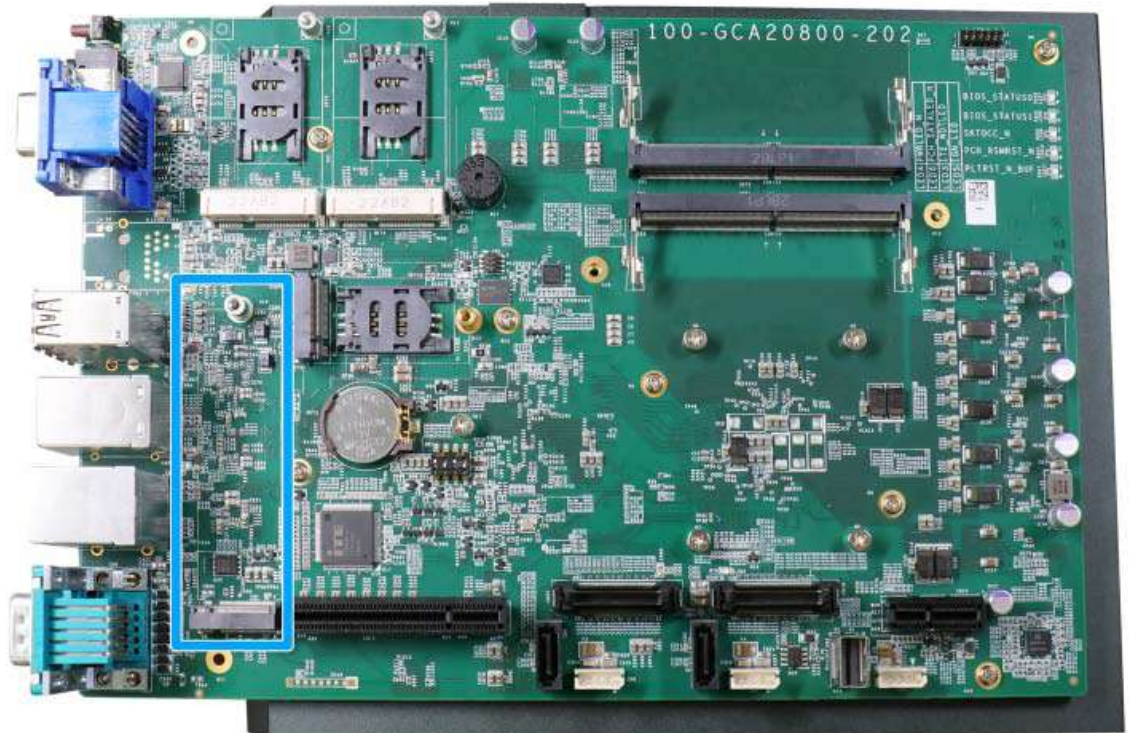
Pin#	Definition	Description
1	WDT_LED-	[Output] Watchdog timer indicator, flashing when Watchdog timer is active
2	WDT_LED+	
3	Standby Power-	[Output] Standby power indicator, on if DC power is applied and system is in S5 (standby) mode.
4	Standby Power+	
5	HDD-	[Output] Hard drive indicator, flashing when SATA hard drive is active.
6	HDD+	
7	Power-	[Output] System power indicator, on if system is turned on, off if system is turned off.
8	Power+	
9	Ctrl-	[Input] Remote on/off control, connects to an external switch to turn on/off the system (polarity is negligible).
10	Ctrl+	
11	IGN_LED-	[Output] Ignition control indicator, on if ignition control is on, off if ignition control is off.
12	IGN_LED+	

2.5.6 Internal USB Port on Extension Board



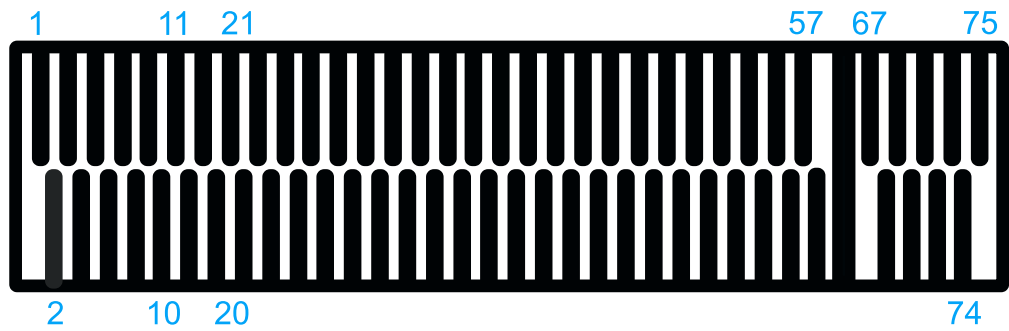
The system's daughter board has an internal USB2.0 port on the PCBA. You can utilize this USB port to connect a USB protection dongle inside the chassis of the system.

2.5.7 M.2 2280 (M Key) Slot for NVMe SSD



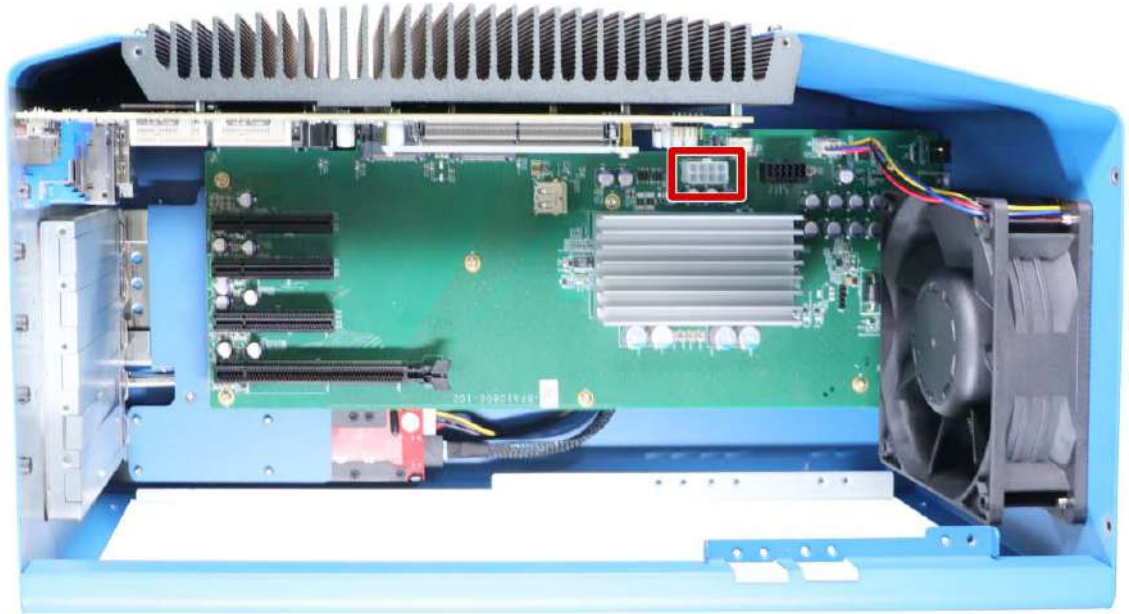
The system has a Gen4x4 PCIe M.2 2280 slot for you to install an NVMe SSD for the ultimate performance. The NVMe SSD offers noticeable performance advantages over 2.5" SSDs for smoother operating system operation and responses.

M.2 (M Key) Slot Pin Definition

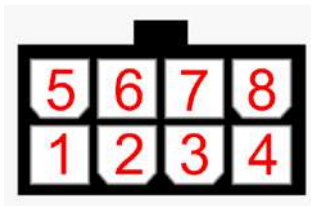


Pin #	Signal	Pin #	Signal
1	GND	2	+3V3
3	GND	4	+3V3
5	PERN3	6	-
7	PERP3	8	-
9	GND	10	DAS/DSS_N
11	PETN3	12	+3V3
13	PETP3	14	+3V3
15	GND	16	+3V3
17	PERN2	18	+3V3
19	PERP2	20	-
21	GND	22	-
23	PETN2	24	-
25	PETP2	26	-
27	GND	28	-
29	PERN1	30	-
31	PERP1	32	-
33	GND	34	-
35	PETN1	36	-
37	PETP1	38	-
39	GND	40	-
41	PERn0	42	-
43	PERp0	44	-
45	GND	46	-
47	PETn0	48	-
49	PETp0	50	PERST_N
51	GND	52	-
53	REFCLKN	54	-
55	REFCLKP	56	-
57	GND	58	-
Mechanical Key			
67	-	68	SUSCLK
69	PEDET	70	+3V3
71	GND	72	+3V3
73	GND	74	+3V3
75	GND		

2.5.8 8-pin Power Connector



The 8-pin power connector (indicated in **red**) is designed only to support power-consuming PCIe cards, such as frame grabber cards with PoE+. The power budget of the 8-pin connector is limited to 150W, which is insufficient for most modern GPU cards.



8-pin pinout

Pin No.	Signal	Pin No.	Signal
1	12V	5	GND
2	12V	6	GND
3	12V	7	GND
4	GND	8	GND



NOTE

The PCIe 8-pin power connector is NOT designed for EPS-12V.

3 System Installation

Before disassembling the system enclosure and installing components and modules, please make sure you have done the following:

- It is recommended that only qualified service personnel should install and service this product to avoid injury or damage to the system.
- Please observe all ESD procedures at all times to avoid damaging the equipment.
- Before disassembling your system, please make sure the system has powered off, all cables and antennae (power, video, data, etc.) are disconnected.
- Place the system on a flat and sturdy surface (remove from mounts or out of server cabinets) before proceeding with the installation/ replacement procedure.

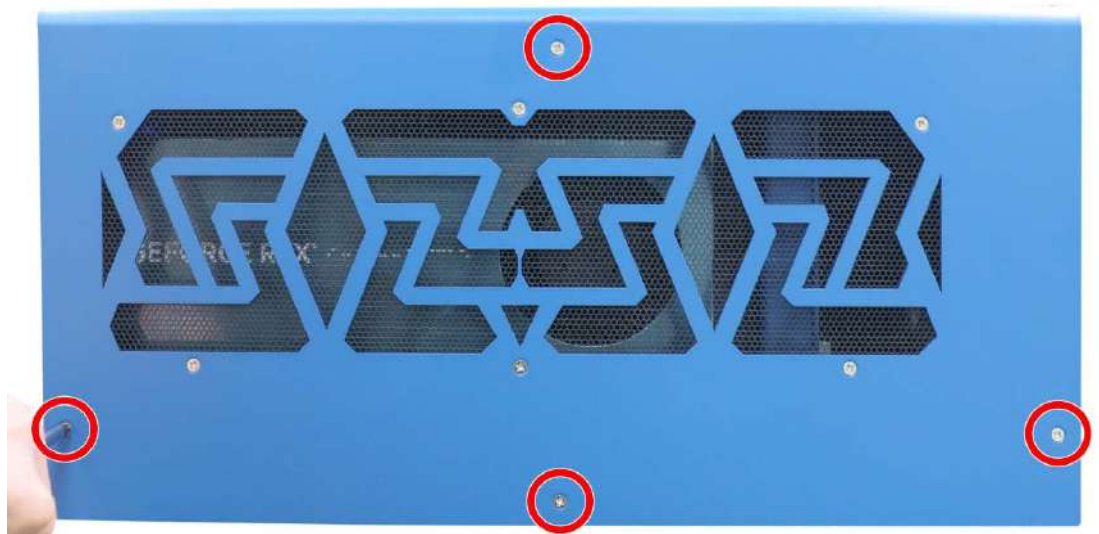
3.1 Disassembling the System

To access system internal components, the system needs to be disassembled. To disassemble the system enclosure, you need to remove the Cassette module and screws on both I/O panels.

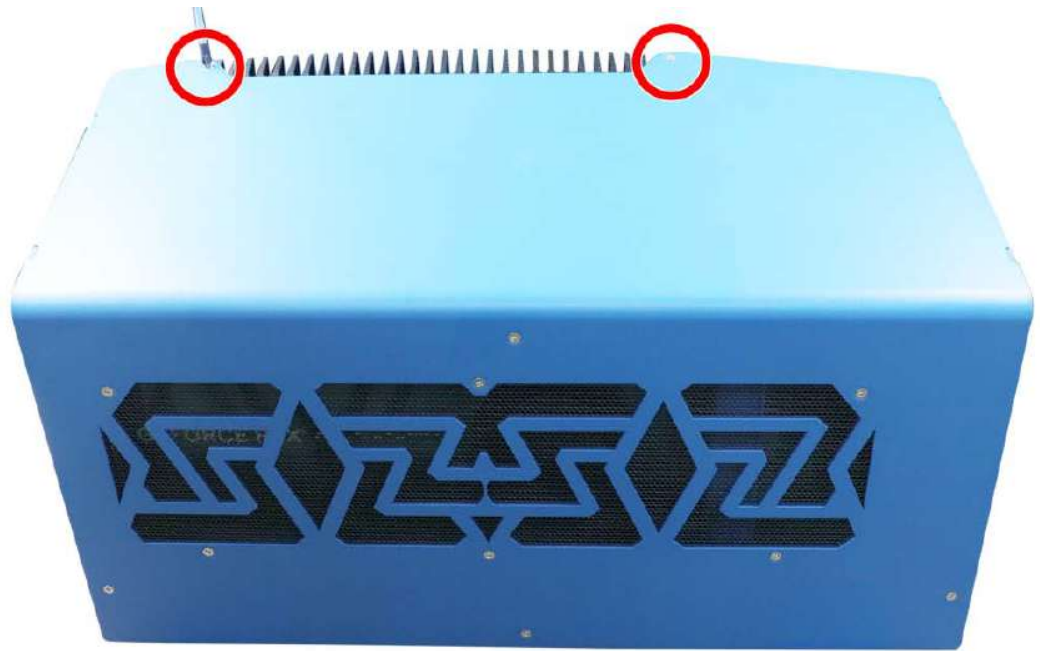
1. On the I/O panel, remove the screws indicated.



2. Remove six screws indicated on the side panel.



3. Remove two screws indicated on the top.



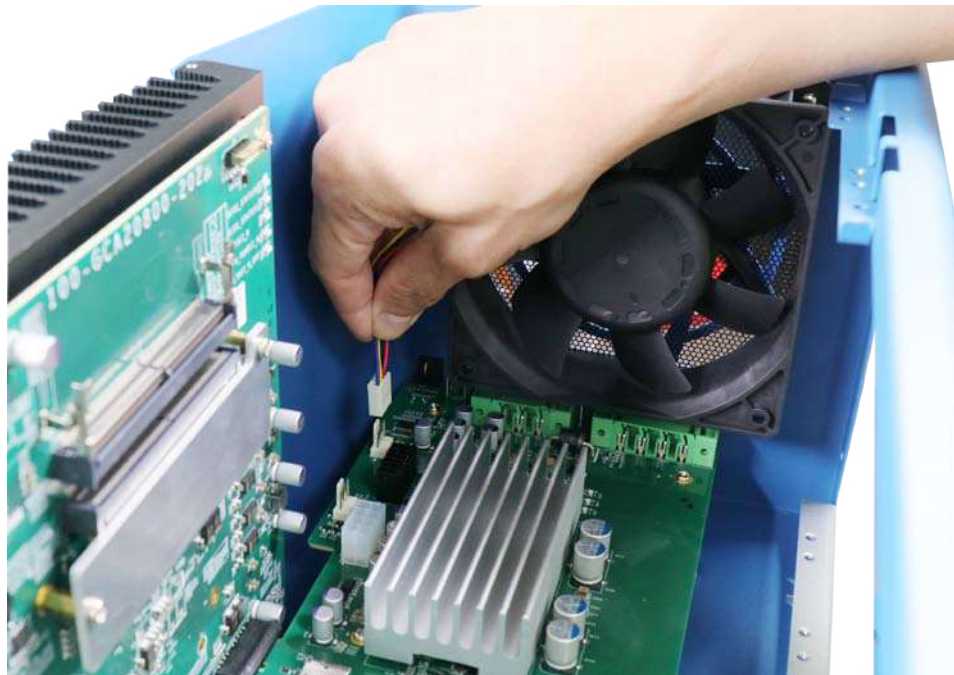
4. On the rear exhaust fan panel, remove two screws indicated in blue, and remove four screws indicated in red holding the exhaust fan in place.



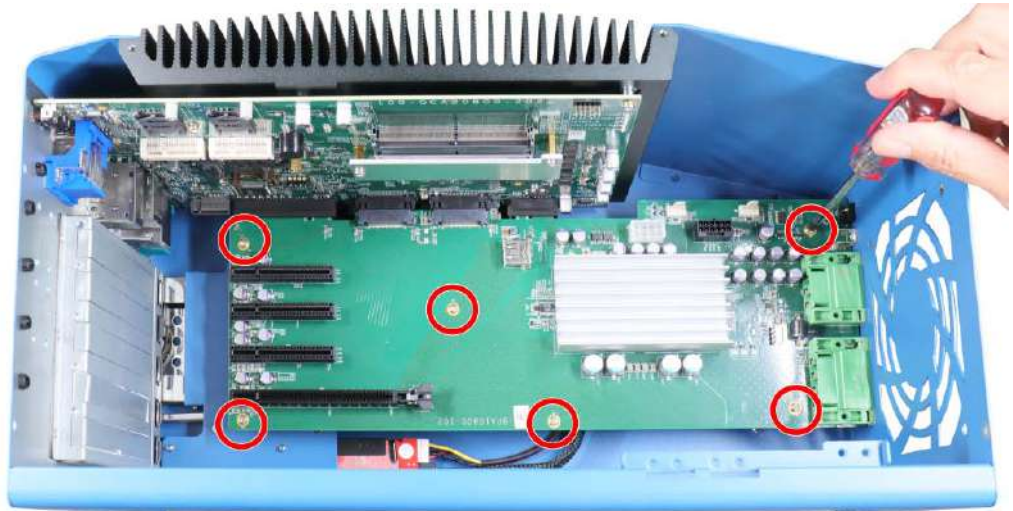
5. Gently lift the L-shape cover panel to separate it from the enclosure.



6. Disconnect the fan's 4-pin plug and gently wiggle off the exhaust fan as the rubber stands may become stuck to the vent.



7. Looking from the top, remove screws indicated and disengage the daughter-board from the motherboard.



Remove screws securing the daughterboard



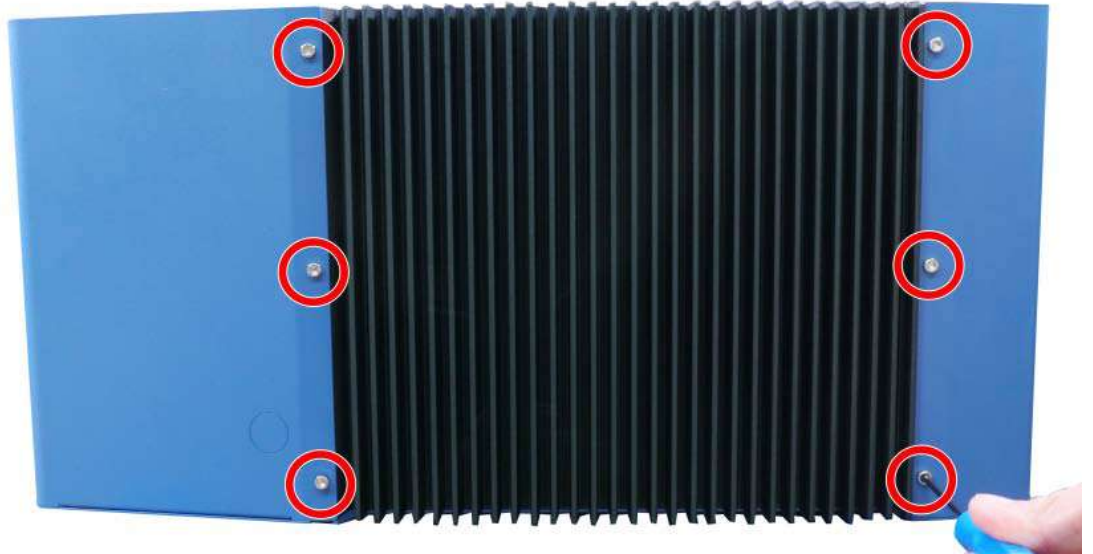
Disengage the daughterboard from the motherboard



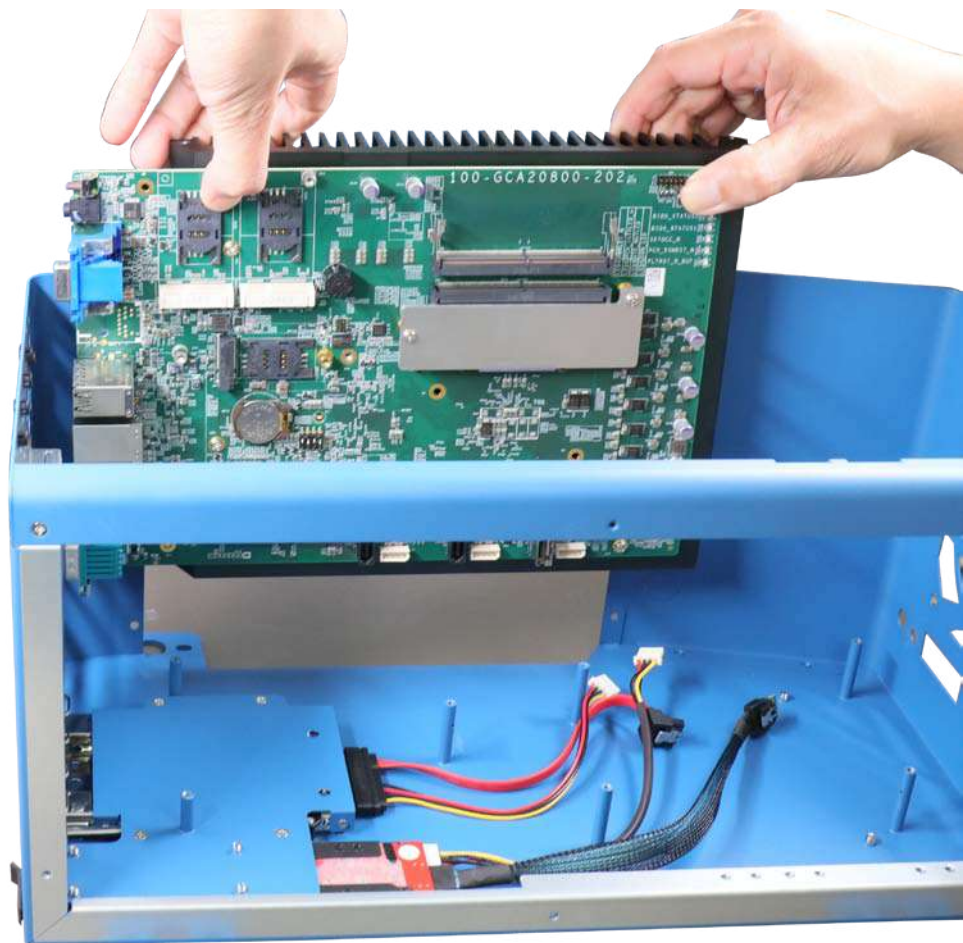
WARNING

Please disengage the daughter-board gradually as there are capacitors situated underneath the PCIe slots that may come in contact with enclosure structures when removed with excessive force.

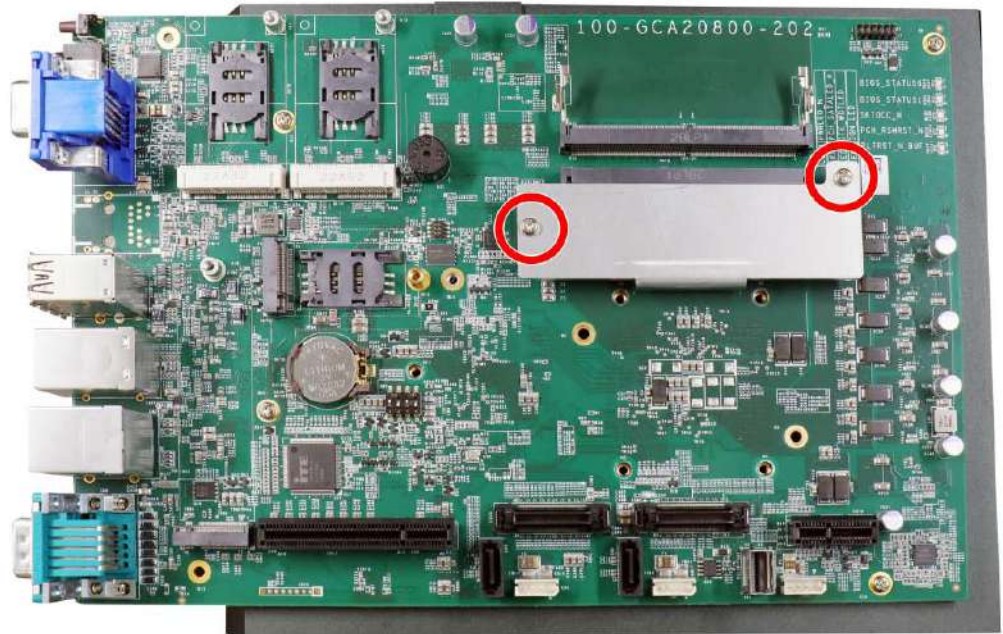
8. Remove screws indicated on the heatsink.



9. Gently lift and separate the heatsink and motherboard from the enclosure.



10. Remove the screws on the memory module's heatsink, remove the copper stands.

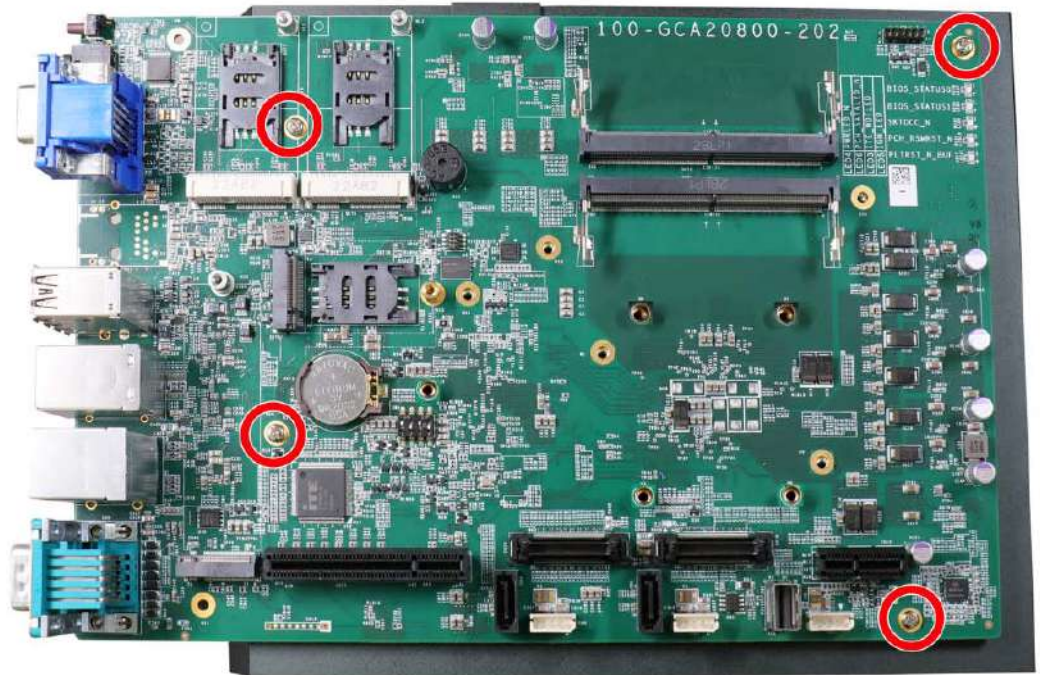


Screws on the memory module's heatsink



Remove the copper stands supporting the memory module's heatsink

11. Remove the screws indicated, and separate the motherboard from the heatsink.



Remove the screws

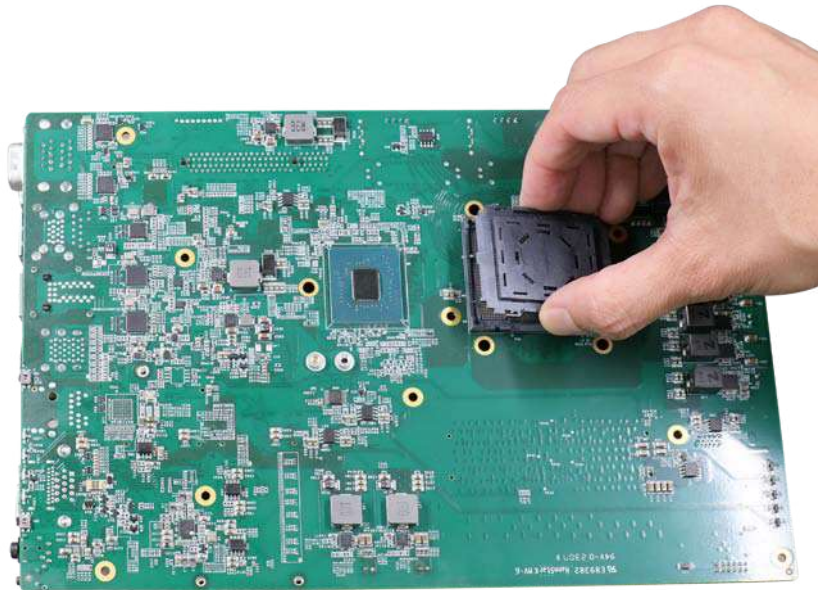


Separate the motherboard from the heatsink

3.2 Installing Internal Components

3.2.1 CPU Installation for Barebone System

1. To install the CPU, you will need to separate the heatsink and the motherboard, please refer to [Disassembling the System](#).
2. Once the motherboard has been separated from the heatsink, turn the motherboard upside-down to access the CPU socket. Gently lift and remove CPU socket



protector.



WARNING

*With the protective cover removed, please be careful when handling the motherboard.
DO NOT touch the pins in the LGA socket!*

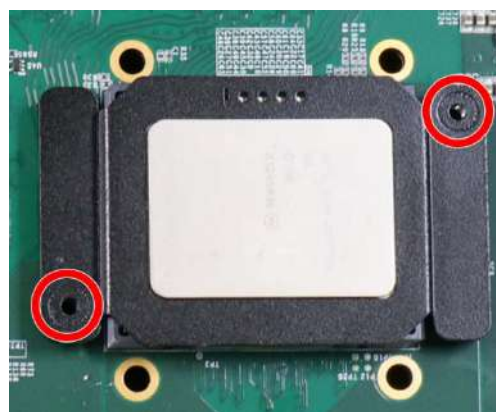
3. Remove the CPU from its container/ tray. Match the four notches on the side (indicated by the **blue arrows**) to the protrusions in the socket, gently lower the CPU into the socket. Pay attention to the seating orientation, notice there is a short side (indicated by **green lines**), and a long side (indicated by **red lines**).



4. Locate the CPU retention bracket (holder) from the accessory box. Place the retention bracket on the CPU and hold it in place. Make sure the screw holes match the CPU retention bracket's screw holes (indicated by **red circles**).

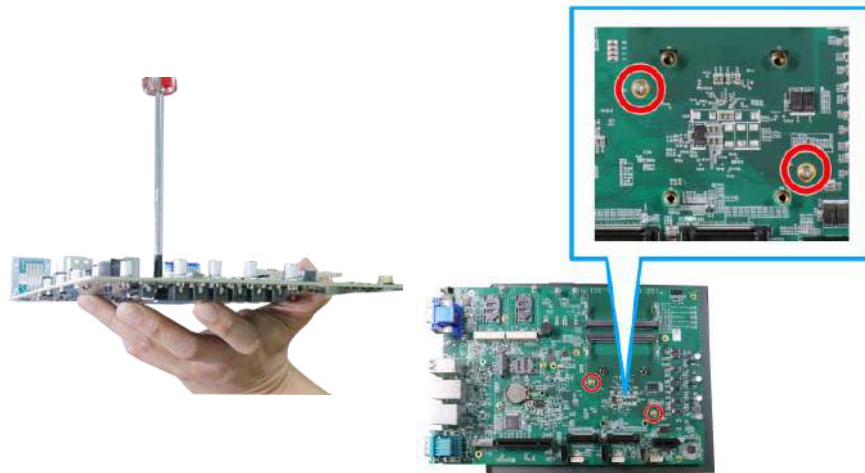


Screw holes for CPU retention bracket



Place the CPU retention bracket on while matching the screw holes

5. Turn the motherboard around and secure the CPU retention bracket by tightening two M3 P-head screws.



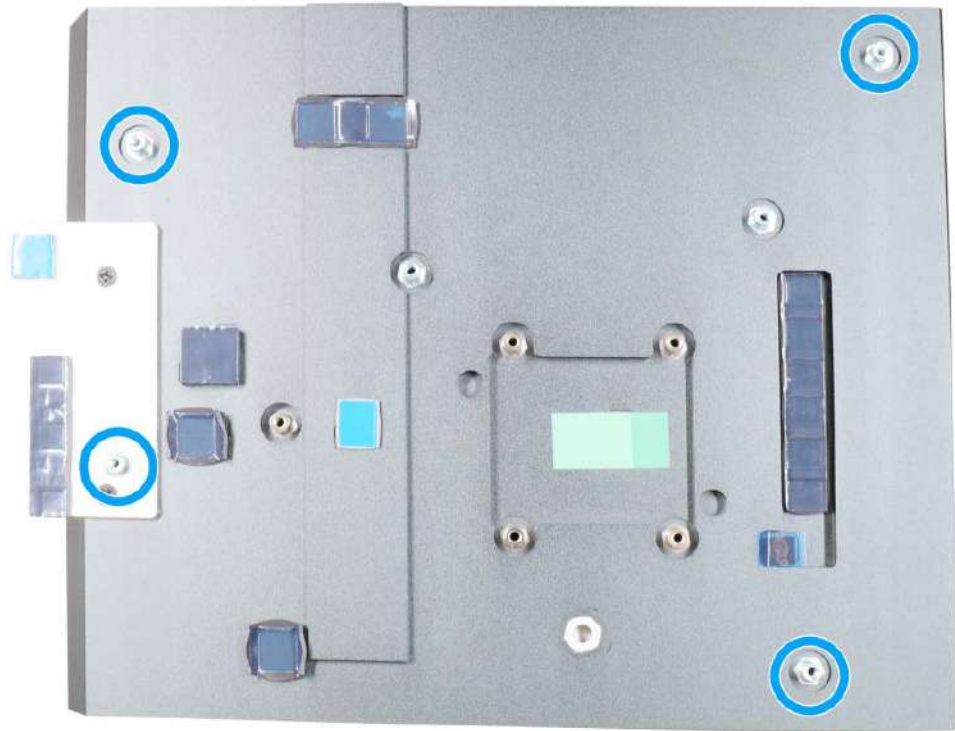
**Hold CPU retention bracket firmly
and turn the motherboard around**

Secure two M3 P-head screws

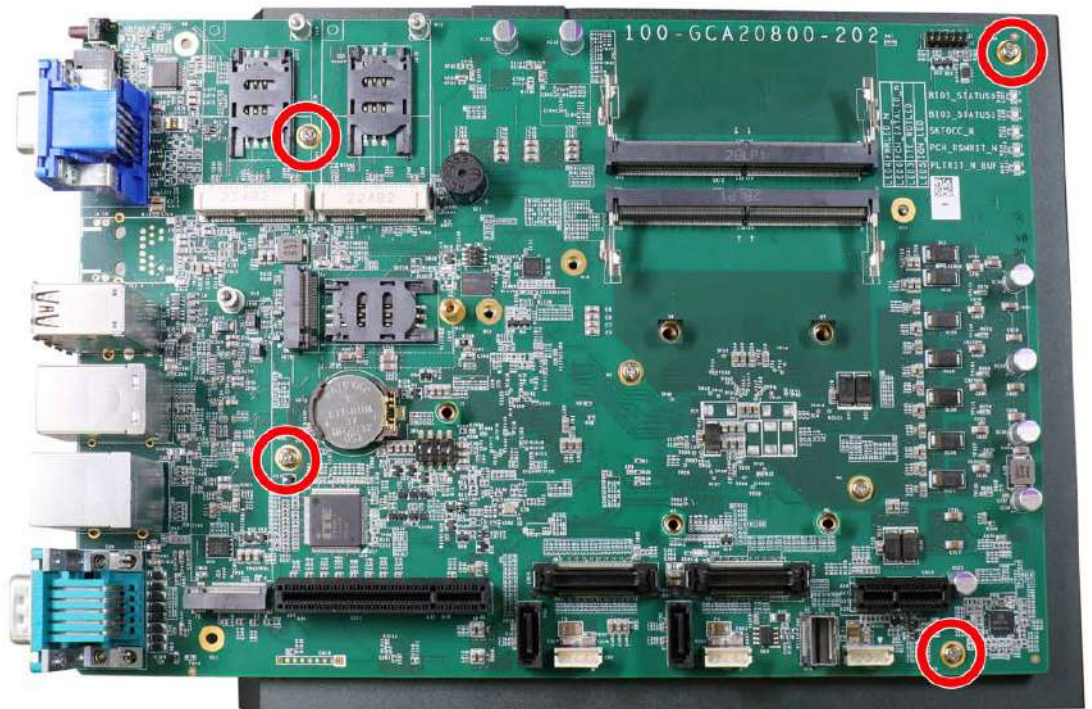
6. Remove the protector film on the heatsink.



7. With the four motherboard standoffs aligned, gently lower the motherboard onto the heatsink and secure the four screws.

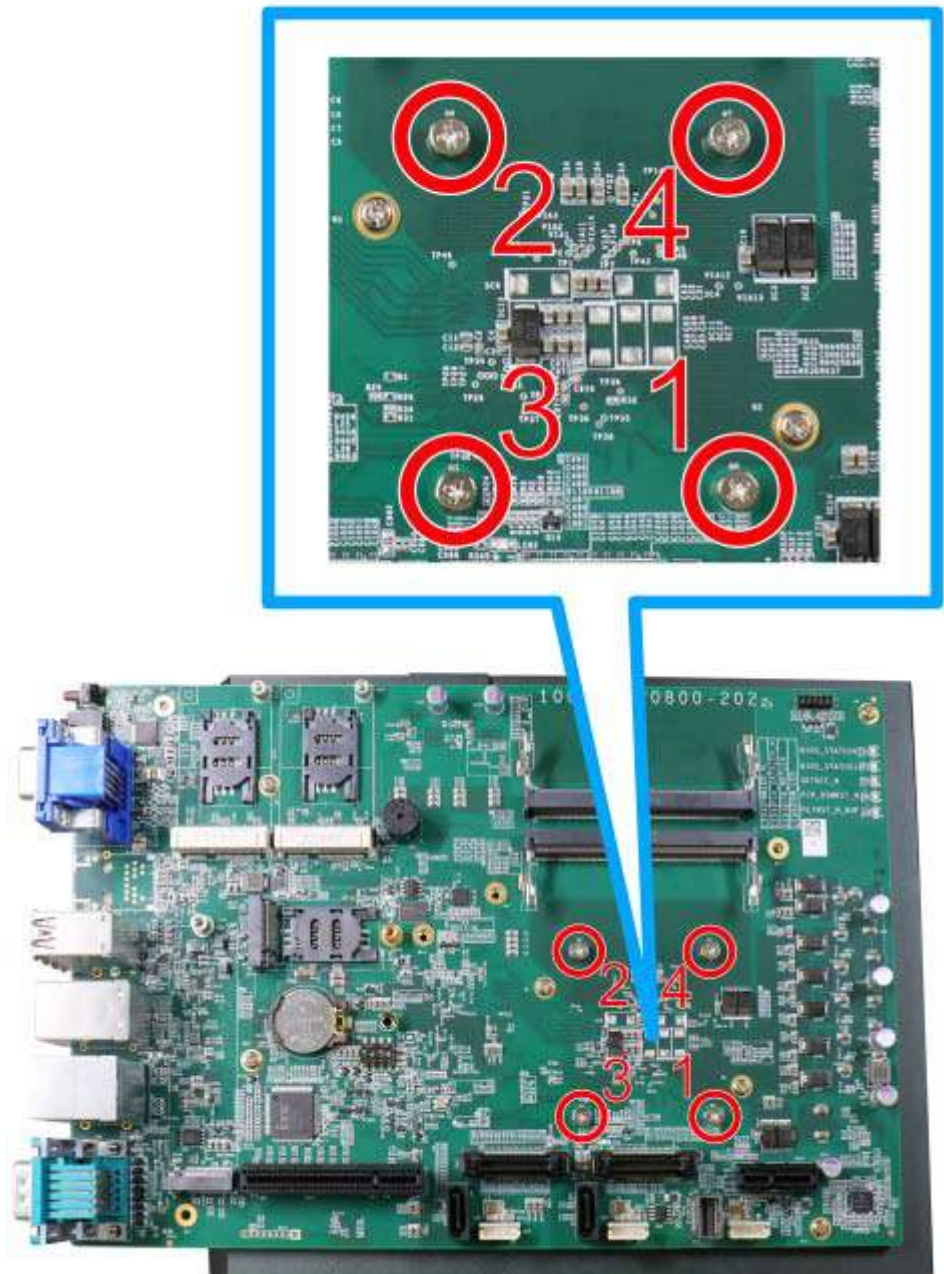


Four standoffs on the heatsink



Secure motherboard with screws

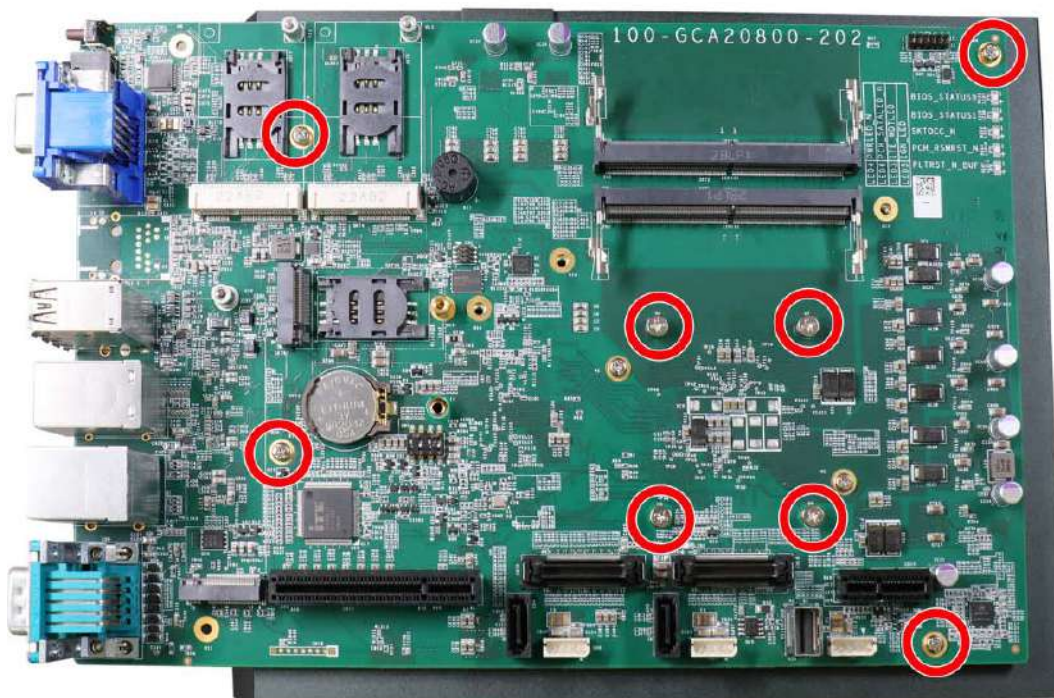
8. Once the motherboard has been installed, you're ready to secure the screws that help the heatsink apply pressure to the CPU/ chipset die. You'll want to apply even pressure to the corners by gradually tightening each screw. Please refer to the recommended order when tightening the screws.



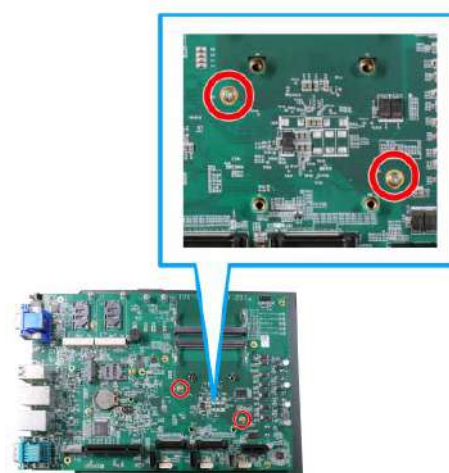
9. [Reinstall the system enclosure](#) when done.
10. If you need to install other components, please refer to respective sections.

3.2.2 Remove and Replace the Existing CPU

1. To replace the existing CPU, you will need to separate the heatsink/ motherboard from the enclosure, please refer to [Disassembling the System](#).
2. To separate the heatsink and the motherboard, remove the eight screws indicated below.



3. Gently separate the motherboard from the heatsink. With a hand on the CPU retention bracket, remove the screws indicated to remove the CPU holder from the CPU.



With a hand on the CPU retention bracket

Remove the screws to remove the CPU retention bracket

4. At this point, the CPU and retention bracket may be stuck onto the heatsink (due to the thermal pad). Please use a plastic pry tool and gently separate the CPU/ retention bracket from the heatsink.

**WARNING**

With the heatsink, CPU, and retention bracket removed, please be careful when handling the motherboard. DO NOT touch the pins in the LGA socket!

5. Gently separate the CPU from the retention bracket, and clean off any thermal pad residues on the heatsink and on the retention bracket.

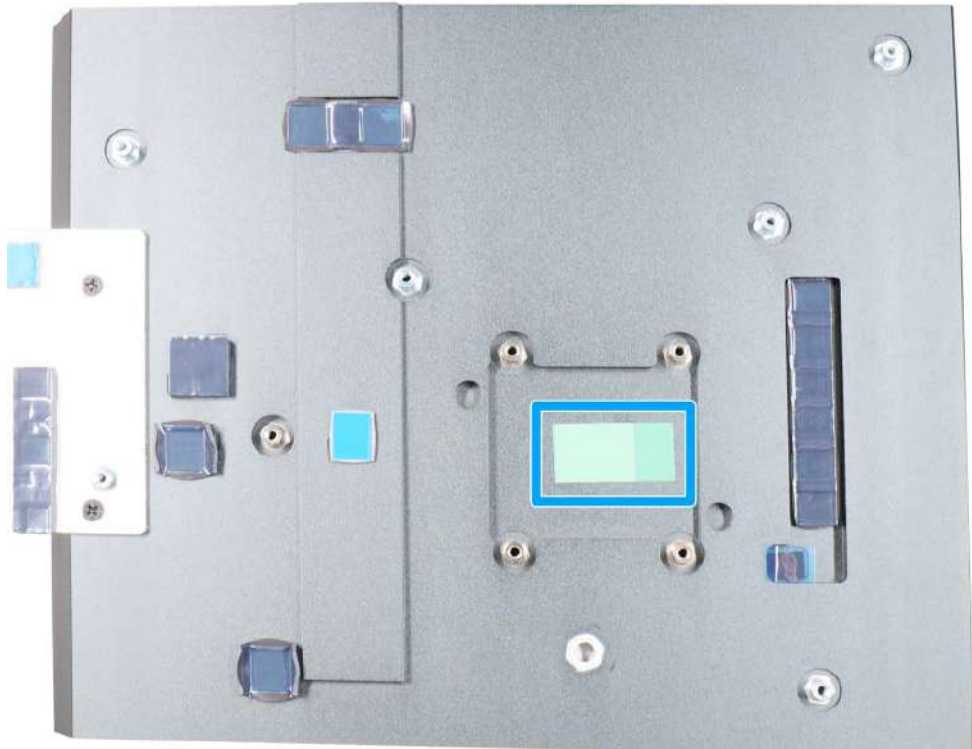


CPU retention bracket (holder)

**WARNING**

With the CPU removed, please be careful when handling the motherboard. DO NOT touch the pins in the LGA socket!

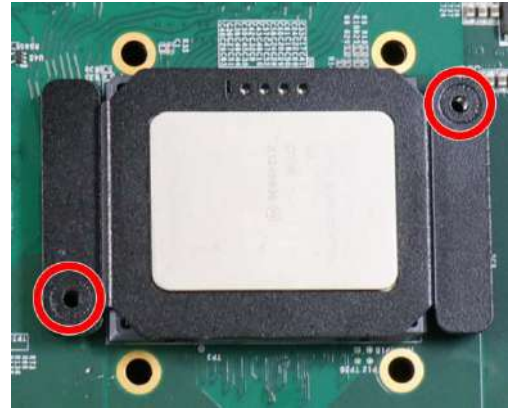
6. Place a new CPU thermal pad (indicated in blue) onto the heatsink for the new CPU.



7. Remove and clean off any thermal pad residues around the socket/ motherboard. Gently place the new CPU into the socket by matching the four notches (indicated by blue arrows) on the side to the protrusions in the socket. Pay attention to the seating orientation, notice there is a short side (indicated by green lines), and a long side (indicated by red lines).



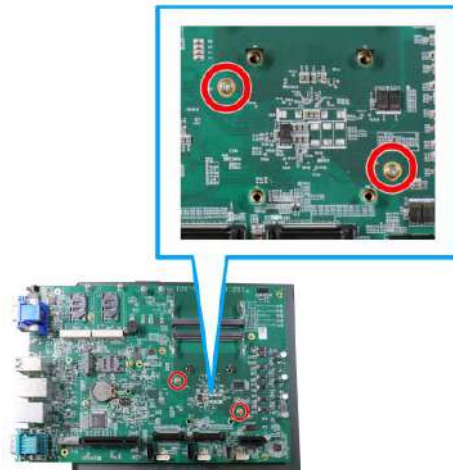
8. Make sure all thermal pad residues have been cleaned on both sides of the retention bracket. Place the CPU retention bracket (holder) on top of the CPU and hold it in place. Make sure the screw holes match the CPU retention bracket's screw holes (indicated by **red circles**).



Screw holes for CPU retention bracket

Place the CPU retention bracket on while matching the screw holes

9. Turn the motherboard around and secure the CPU retention bracket by tightening two M3 P-head screws.



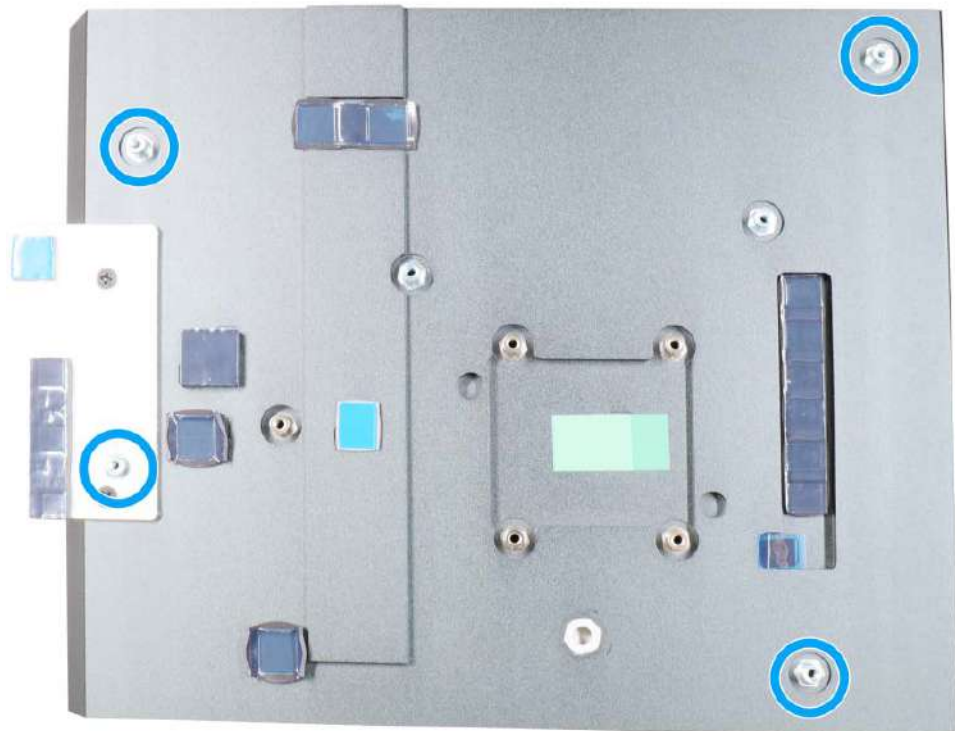
Hold CPU retention bracket firmly and turn the motherboard around

Secure two M3 P-head screws

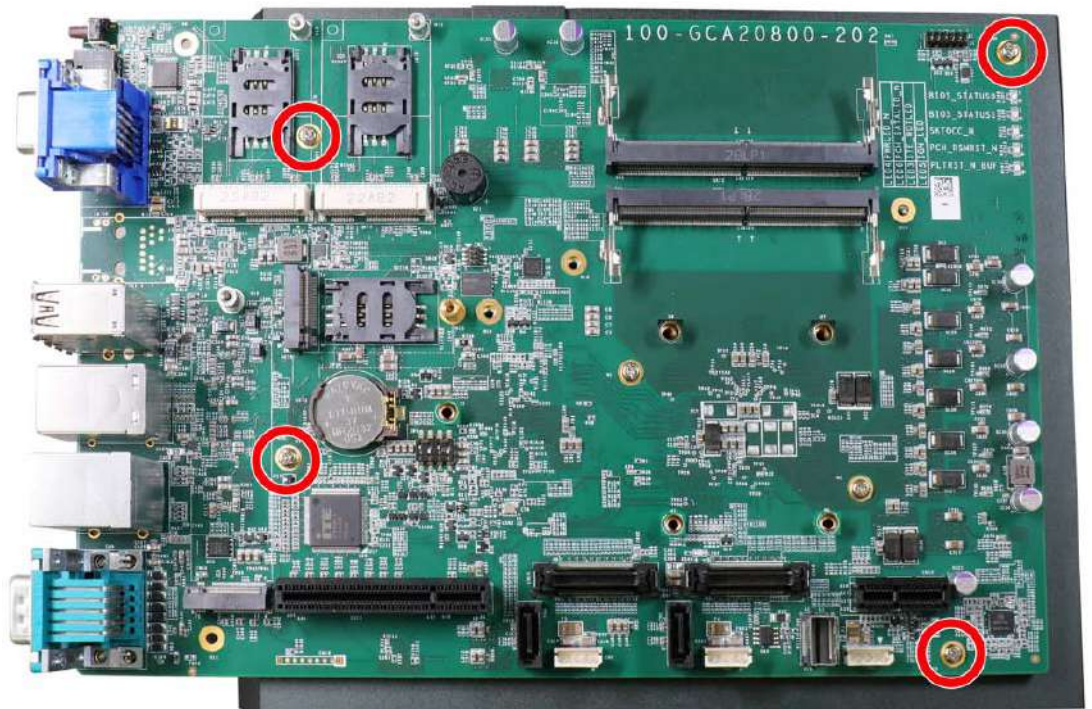
10. Remove the protector film on the heatsink.



11. With the four motherboard standoffs aligned, gently lower the motherboard onto the heatsink and secure the four screws.

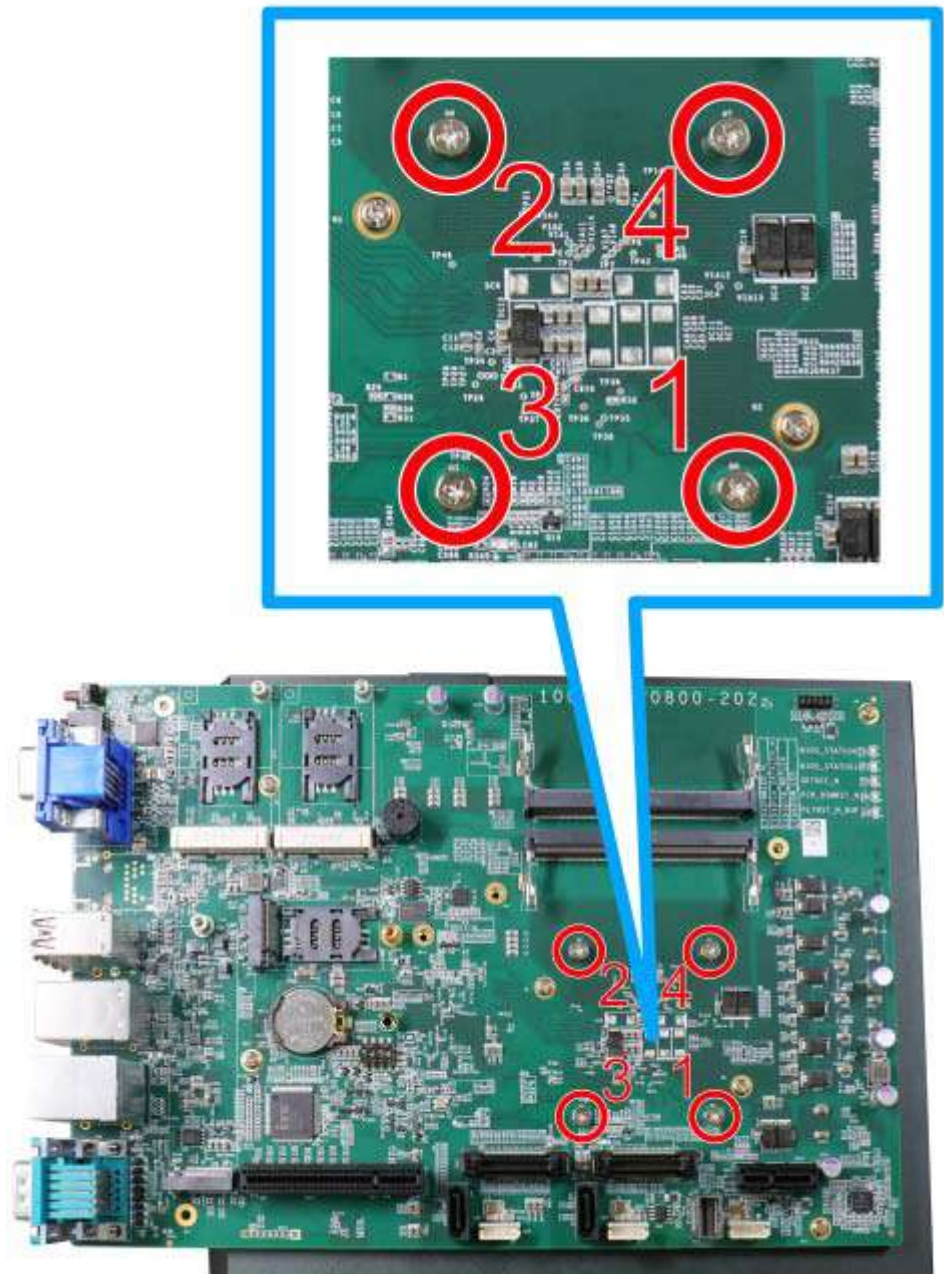


Four standoffs on the heatsink



Secure motherboard with screws

12. Once the motherboard has been installed, you're ready to secure the screws that help the heatsink apply pressure to the CPU/ chipset die. You'll want to apply even pressure to the corners by gradually tightening each screw. Please refer to the recommended order when tightening the screws.



13. [Reinstall the system enclosure](#) when done.

If you need to install other components, please refer to respective sections.

3.2.3 DRAM SO-DIMM Installation

There are two SO-DIMM memory slots (indicated in **blue**) on the motherboard that supports a total maximum of 128GB ECC/ non-ECC DDR5-4800. Please follow the procedures below to replace or install the memory modules.

1. Please refer to the section "[Disassembling the System](#)".
2. Locate the SODIMM memory module slots on the motherboard.



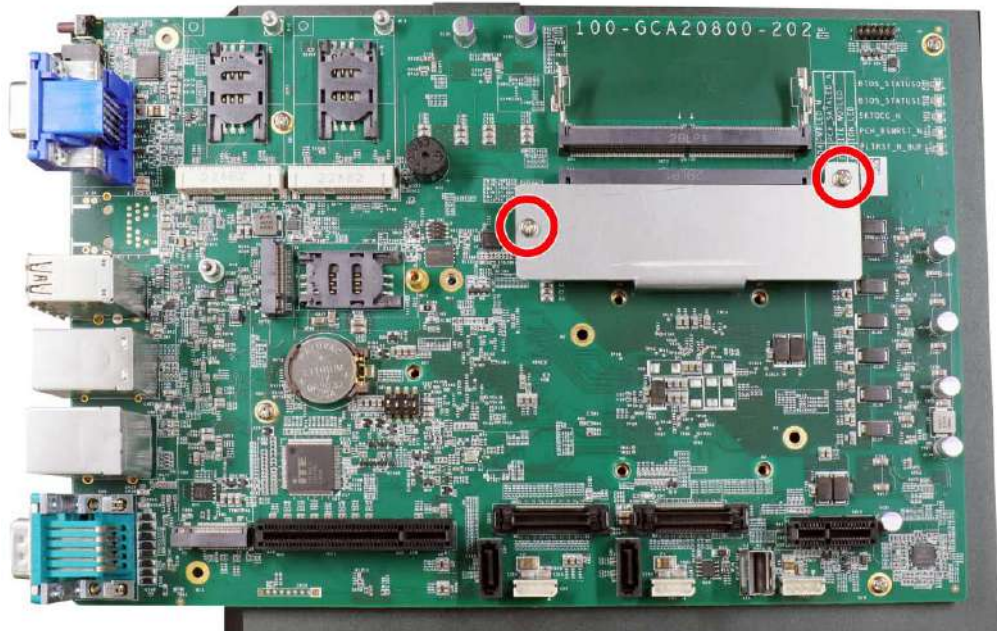
3. To install the memory module, insert gold fingers into the slot at 45-degree angle, push down on the memory module to clip the module into position.



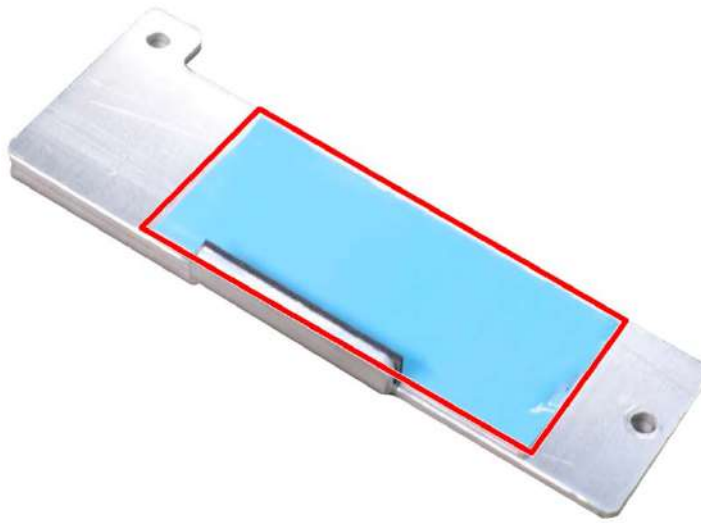
4. Push the memory module down until it is clipped-in.



5. To install the memory module at the bottom, you will need to remove the heatsink by remove the two screws.



6. Repeat steps 3 and 4 to install the module. Remove the thermal pad film protector (indicated in **red**) and reinstall the memory module's heatsink.

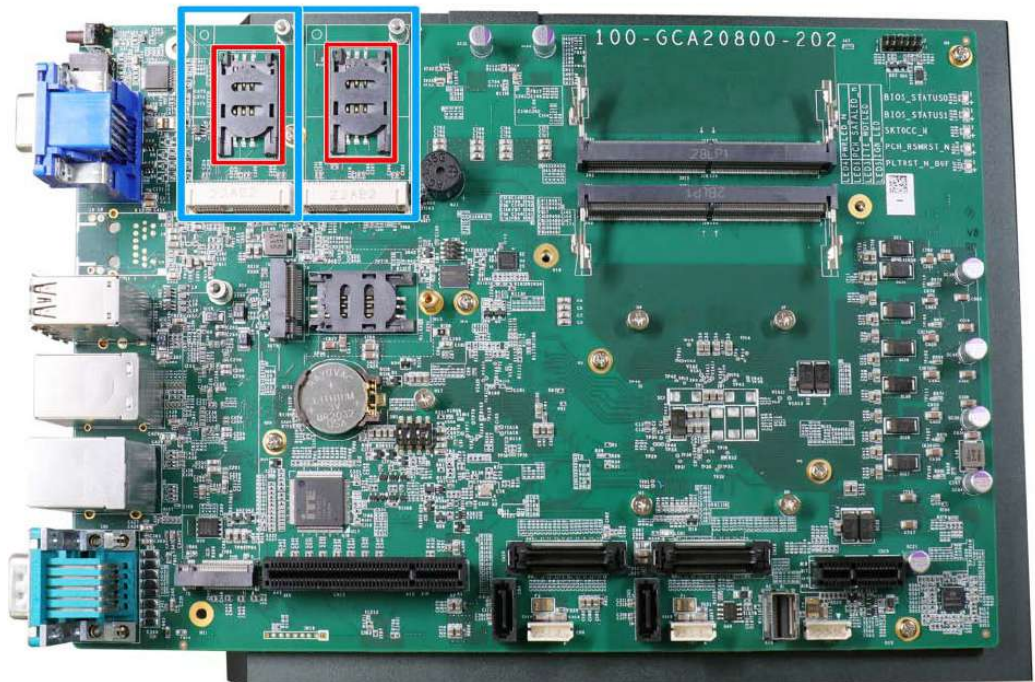


7. [Reinstall the system enclosure](#) and panel when done.
8. If you need to install other components, please refer to respective sections.

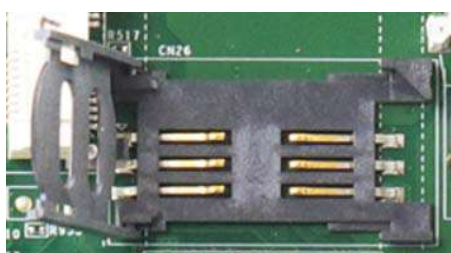
3.2.4 mPCIe Module, SIM (2FF) Card and Antennae Installation

The system has two mPCIe slots (indicated in **blue**) coupled with mini-SIM socket (indicated in **red**) for installing 3G/ 4G module. For installation, please refer to the following instructions.

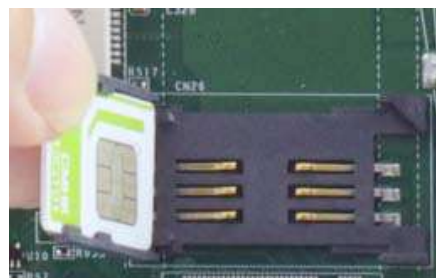
1. Please refer to the section "[Disassembling the System](#)".
2. Locate the mPCIe and Mini-SIM card slots on the motherboard.



3. Before installing the mPCIe module, you need to insert the Mini-SIM card. Slide the mini-SIM slot holder and lift the holder. Insert the mini-SIM card (pins facing up), shut the mini-SIM holder and slide it to lock the SIM card in-place.



Slide and lift SIM card holder



Insert SIM card with pins facing up

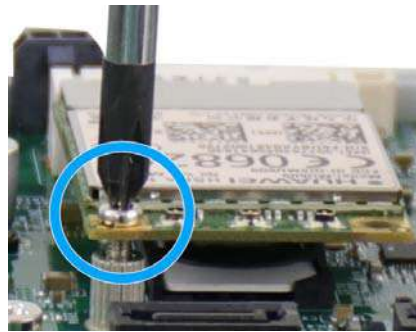
4. Secure the SIM card by sliding the holder.



5. Insert the mPCIe module on a 45 degree angle into the mPCIe slot and secure the module.



Insert on 45 degree angle

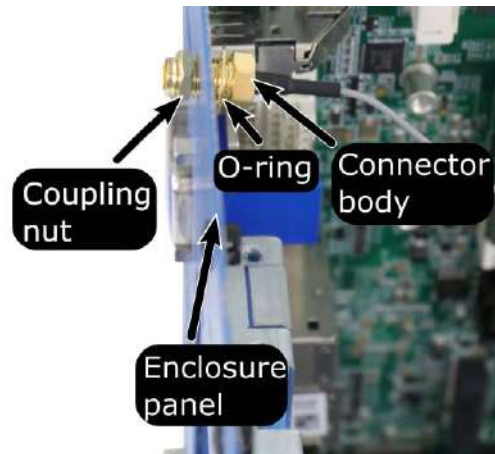


Secure the module

6. Clip on the IPEX-to-SMA cable to the module and secure the antenna to the I/O panel. Please refer to the module's manual for clip-on connection.



Clip on IPEX-to-SMA cable



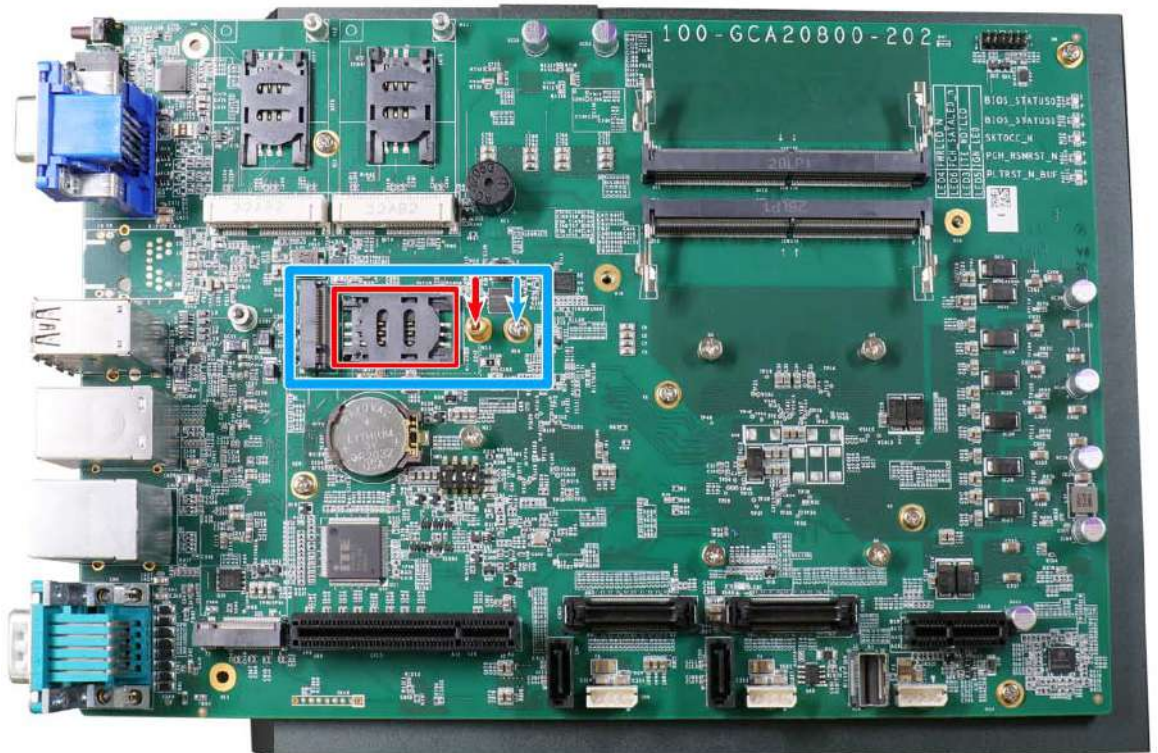
Secure antenna body to rear panel

7. Secure the external antenna to complete the installation.



8. [Reinstall the system enclosure](#) and panel when done.
9. If you need to install other components, please refer to respective sections.

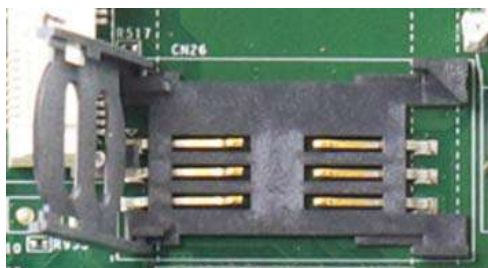
3.2.5 M.2 2242/ 3052 (B Key) Module and SIM (2FF) Card Installation



The system has an M.2 2242/ 3052 slot (indicated in **blue rectangle**) with a 5G/ 4G SIM slot (indicated in **red rectangle**). A copper standoff is provided for you to secure onto the motherboard into the **red arrow** location for an M.2 2242 module, or into the **blue arrow** location for an M.2 3052 module. By installing a 5G or 4G M.2 module and SIM card, you can access the internet via the provider's network.

The M.2 slot also accepts NVMe, CAN bus and COM port module. For installation, please refer to the following instructions.

1. Please refer to the section "[Disassembling the System](#)".
2. If you are installing an M.2 5G/4G module, you need to insert the SIM card first. Slide the SIM slot holder and lift the SIM card holder. Insert the SIM card (pins facing up), shut the SIM holder and slide it to lock the SIM card in-place.



Slide and lift SIM card holder



Insert SIM card with pins facing up

- Secure the SIM card by sliding the holder.



- Insert the module on a 45 degree angle, gently press down and secure the module with an M2.5 P-head screw



Insert on 45 degree angle

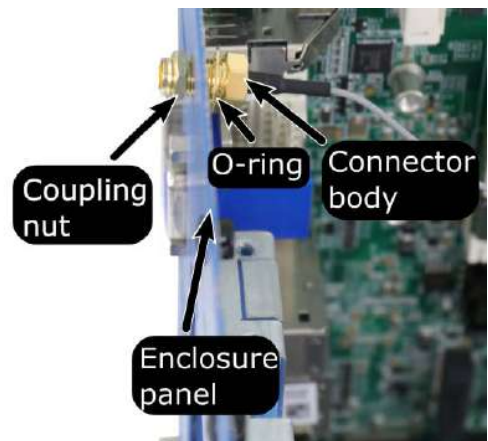


Secure the module

- Clip on the IPEX-to-SMA cable to the module and secure the antenna to the front or rear panel. Please refer to the module's manual for clip-on connection.



Clip on IPEX-to-SMA cable



Secure antenna body to rear panel

6. Secure the external antenna to complete the installation.

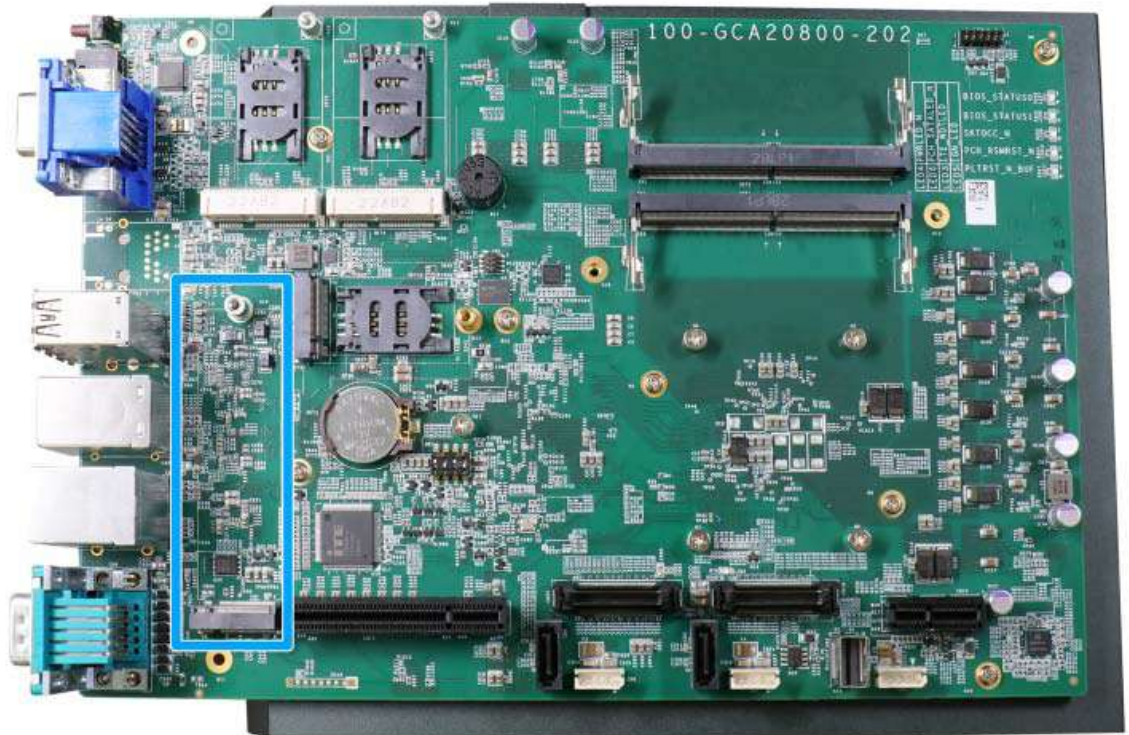


7. [Reinstall the system enclosure](#) and panel when done.
8. If you need to install other components, please refer to respective sections.

3.2.6 M.2 (M Key) 2280 NVMe SSD Installation

The system has a x4 PCIe M.2 (M key) 2280 slot for you to install an NVMe SSD for the fast read/ write performances. An NVMe SSD offers exceptional performance over 2.5" SSDs for smoother operating system operations. For installation, please refer to the following instructions.

1. Please refer to the section "[Disassembling the System](#)", you may not need to completely dismantle the system to gain access to the M.2 slot.
2. Locate the M.2 2280 slot on the motherboard



3. Insert the module on a 45 degree angle.



4. Gently press down and secure the module with an M2.5 P-head screw.



5. [Reinstall the system enclosure](#) and panel when done.
6. If you need to install other components, please refer to respective sections.

3.2.7 Graphics Card Installation



WARNING

To reduce the risk of damage, **DO NOT** remove the graphics card from the antistatic bag before it is ready to be installed into the Cassette module!

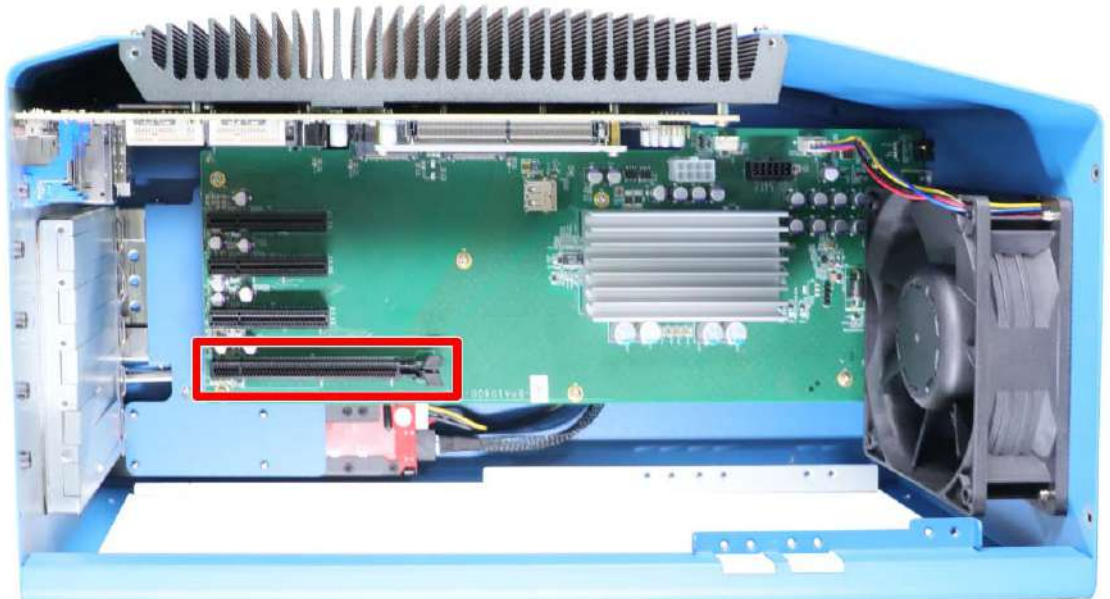


NOTE

For installation compatibility, please consult with Neousys before purchasing a graphics card.

Nuvo-10108GC can support up to an NVIDIA graphics cards up to 350W. The placement of the rear exhaust fan creates a sealed wind tunnel to bring in cold air to the graphics cards and expels hot air to offer extreme system stability and reliability. To install a PCIe graphics card, please refer to the following procedure:

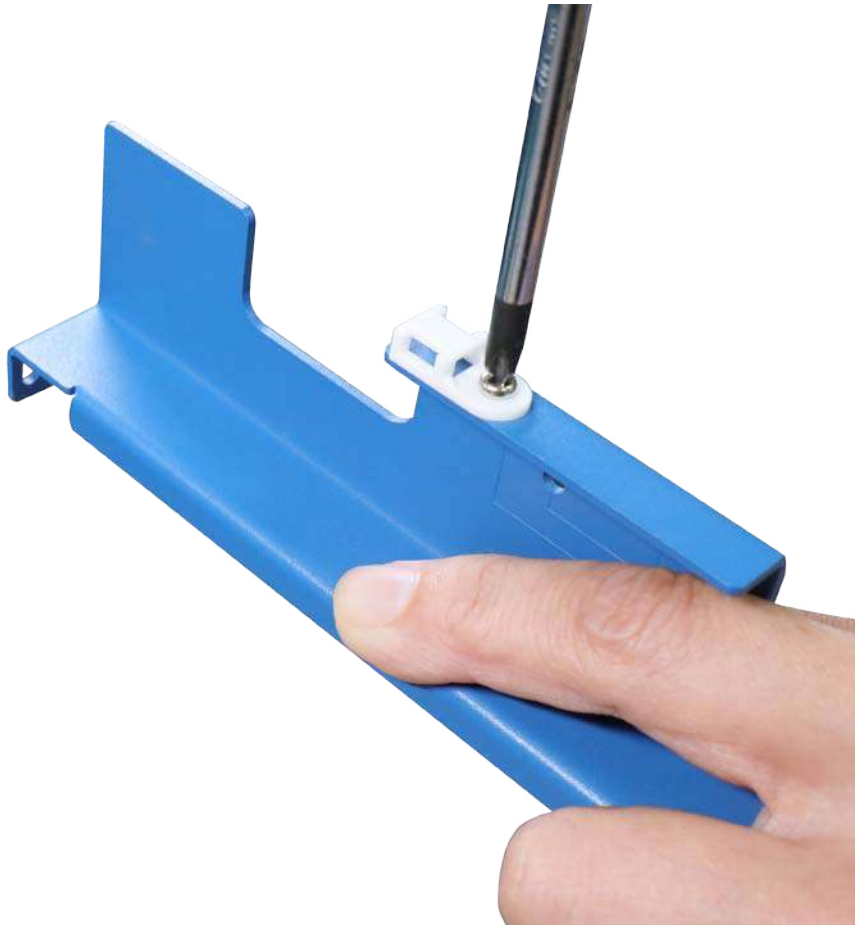
1. Please refer to the section "[Disassembling the System](#)".
2. Locate the PCIe x16 slot on the daughter board (indicated in **red**).



3. Remove the corresponding enclosure bezel(s) to the PCIe slot you wish to install to.



4. Take out the graphics card dedicated bracket and cable and attach the cable sorting peg.



5. Remove the graphics card from the antistatic bag, and attach the dedicated bracket to the end of the graphics card by securing the screws indicated. Note the orientation of the installed bracket, the screw holes (indicated in **red**) should be secured to the top of the enclosure while the screw holes (indicated in **blue**) should be secured to the enclosure along the bottom.

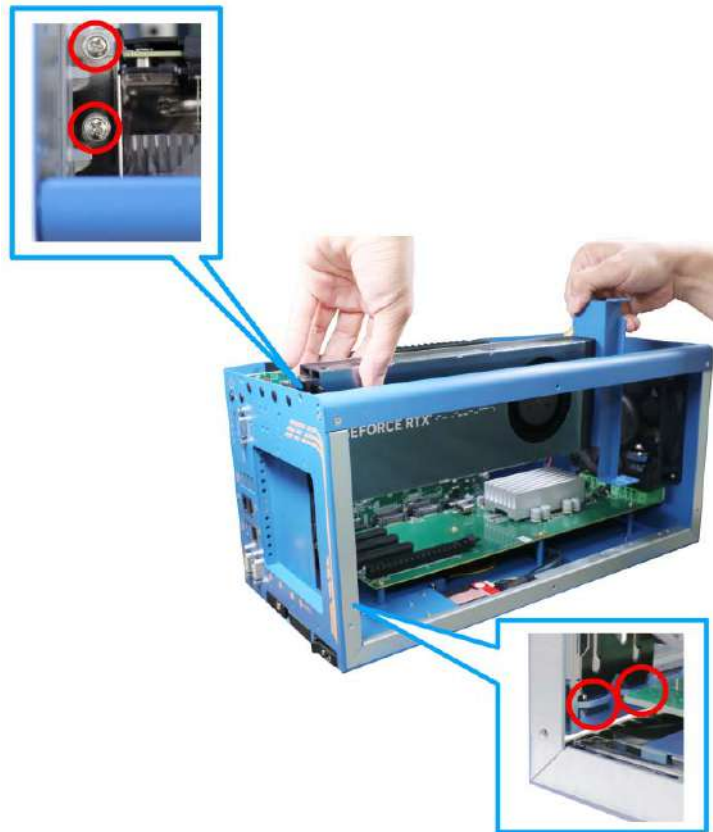


Compatible NVIDIA RTX 40/ 30 series MSI RTX 5070/ 5070 Ti/ 5080 Ventus

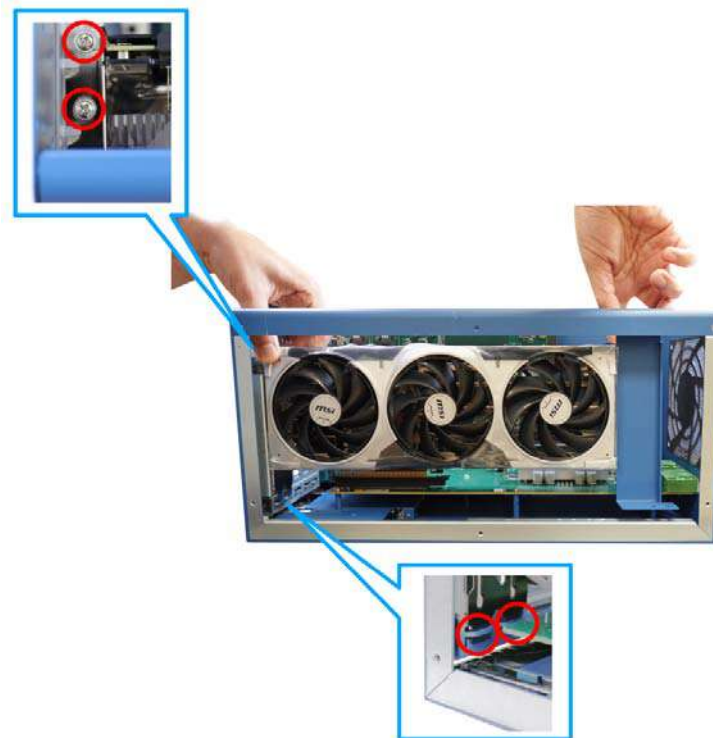
6. Attach the RTX 40/ 30 series graphics card's power cable.



7. Gently lower the graphics card into the PCIe slot while ensuring the gold-fingers are inserted, the graphics card panel is properly inserted and secured with screws.

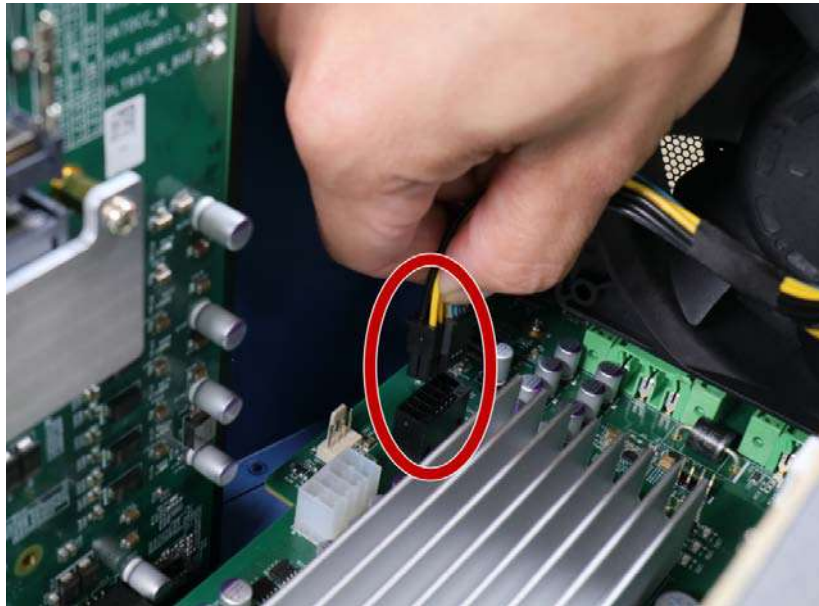


Compatible RTX 40/ 30 series

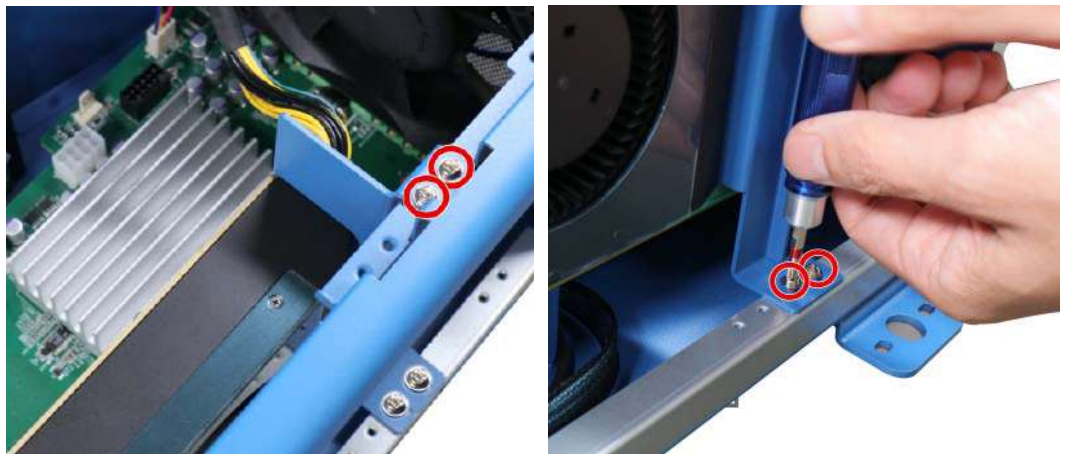


MSI RTX 5070/ 5070 Ti/ 5080 Ventus

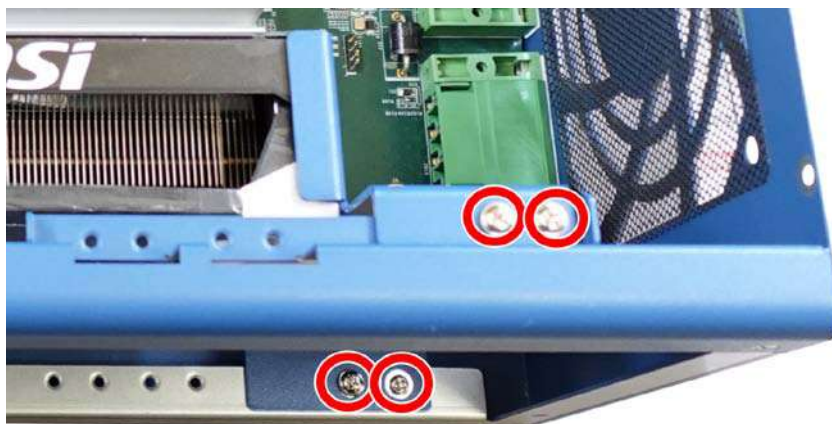
8. Connect the graphics card's 12-pin power cable to the daughter board (indicated in **red**).



9. Secure the dedicated GPU bracket to the enclosure frame at the top and the bottom.

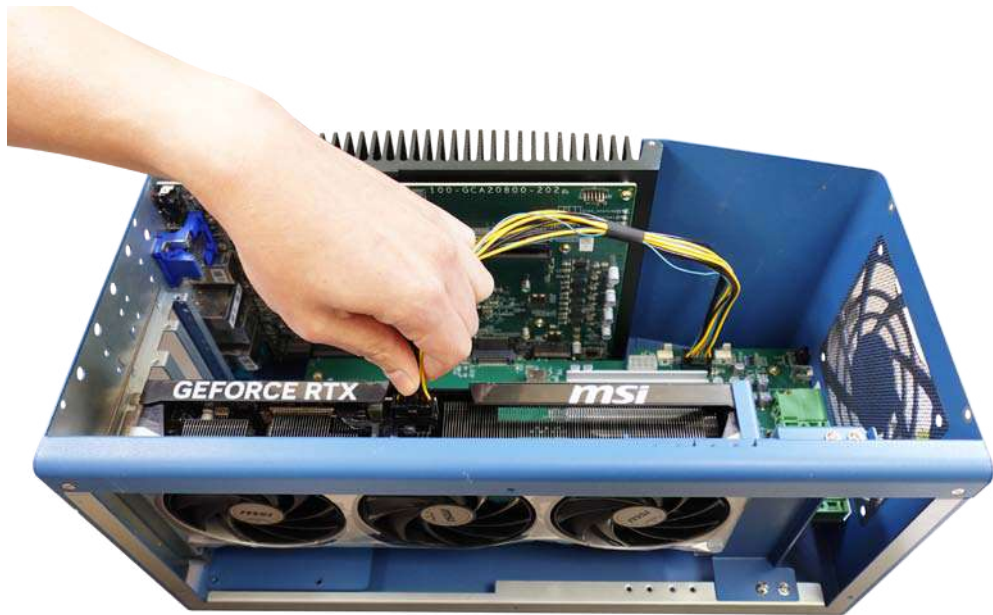


Compatible RTX 40/ 30 series



MSI RTX 5070/ 5070Ti/ 5080 Ventus

10. Plug in the RTX 5070/ 5070 Ti/ 5080 Ventus graphics card's power cable.



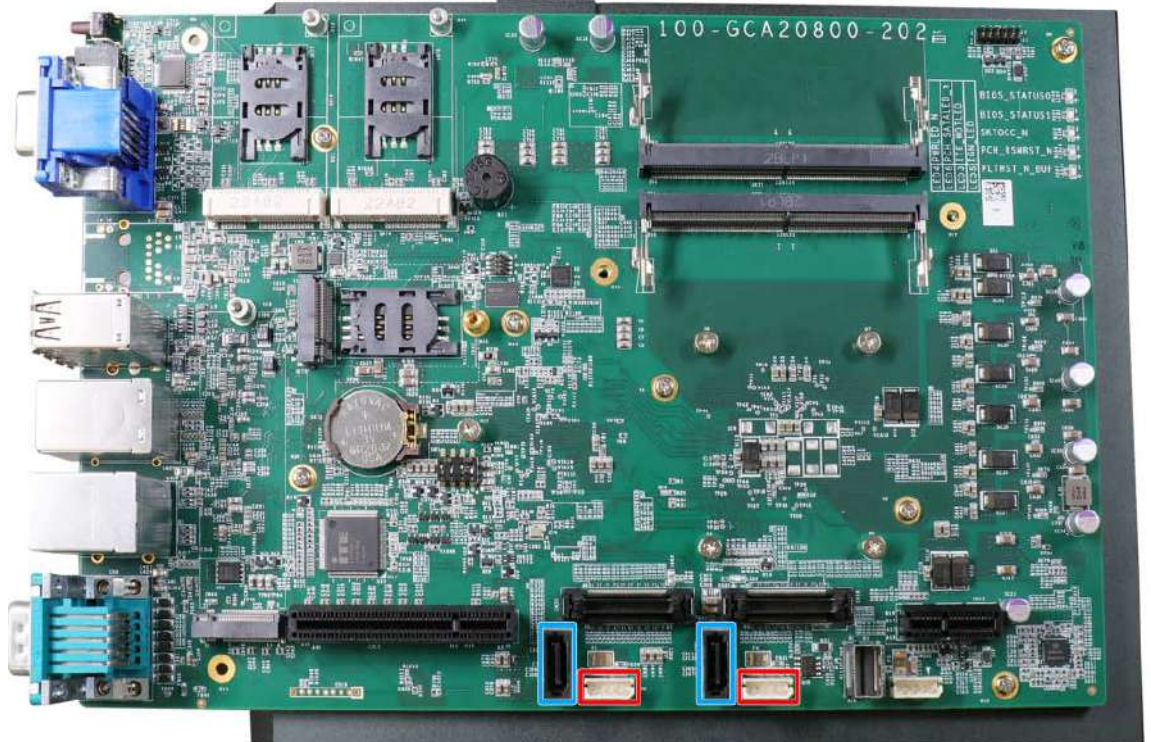
11. [Reinstall the enclosure](#) and panel when done.
12. If you need to install other components, please refer to respective sections.

3.2.8 HDD/ SSD Installation



NOTE

The system's easy-swap tray supports up to 7mm 2.5inch SSD/ HDD specifications.

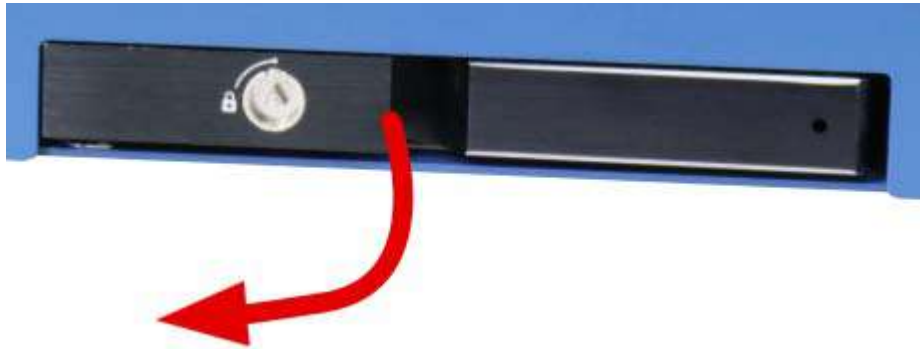


The system has two SATA ports (indicated in **blue**) and two four pin power connectors (indicated in **red**). Only one of the SATA and power connector will be connected to the front-accessible tray, so users only need to install the HDD/ SSD to the easy-swap tray. Please refer to the following instructions on how to install a 2.5" SATA HDD/SSD.

1. The easy-swap tray is situated at the bottom of the enclosure.



2. You may insert and install the HDD/ SSD without disassembling the enclosure. Simply lift to spring open the lever to gain access to the hot-swap slot.

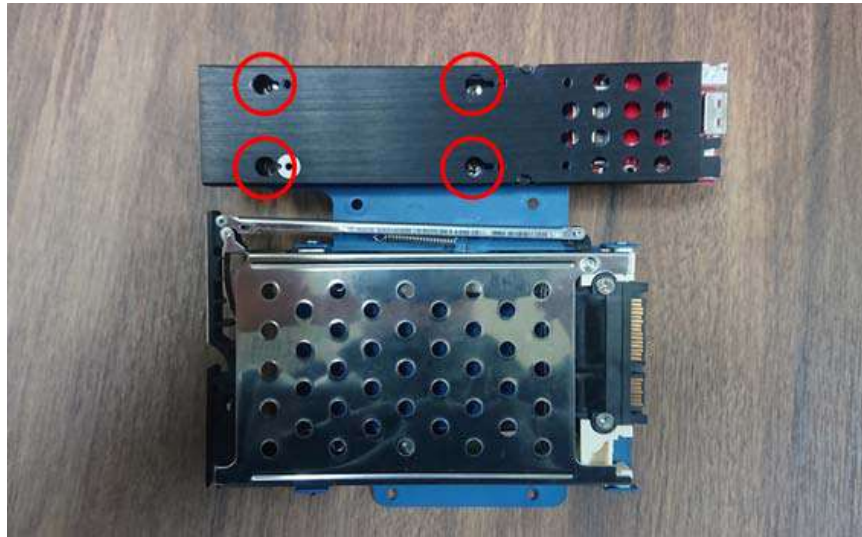


3. Insert the HDD/ SSD (with labels facing up) and the SATA connector end towards the slot, insert it 3/4 of way in and use the lever to fully push the HDD/ SSD into the slot. You should hear a click sound to ensure the HDD/ SSD is properly inserted and engaged.

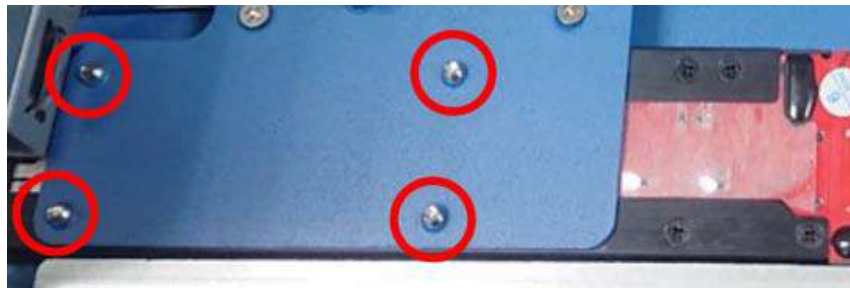


4. If you need to install other components, please refer to respective sections.

3. Turn the bracket upside down and secure the tray's chassis onto the bracket by inserting screws inside-out.

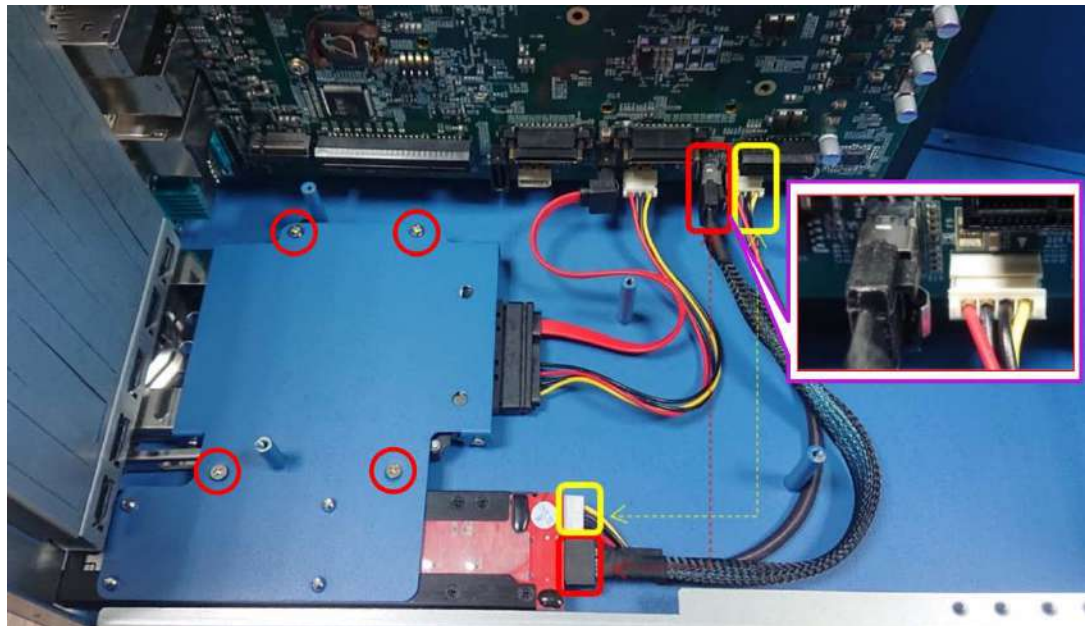


Insert and secure screws from inside



Screws secured inside-out

4. Place the bracket back into the enclosure by securing the screws (indicated in **red circles**) and connect the cables (indicated in **red/ yellow rectangles**).



5. [Reinstall the enclosure](#) and panel when done.
6. If you purchased the NVMe kit, the tray should be already inserted into the chassis. Lift the lever in the direction indicated to pull the tray out of the chassis.



7. Once you have the access to the tray, pinch the two knobs and gently lift the top cover.



8. Insert the NVMe SSD module on a 45° angle and secure with a screw.



Insert on a 45° angle



Secure with a screw

9. Remove the thermal pad protection film.



10. Place the cover back onto the tray, the cover should click-in.



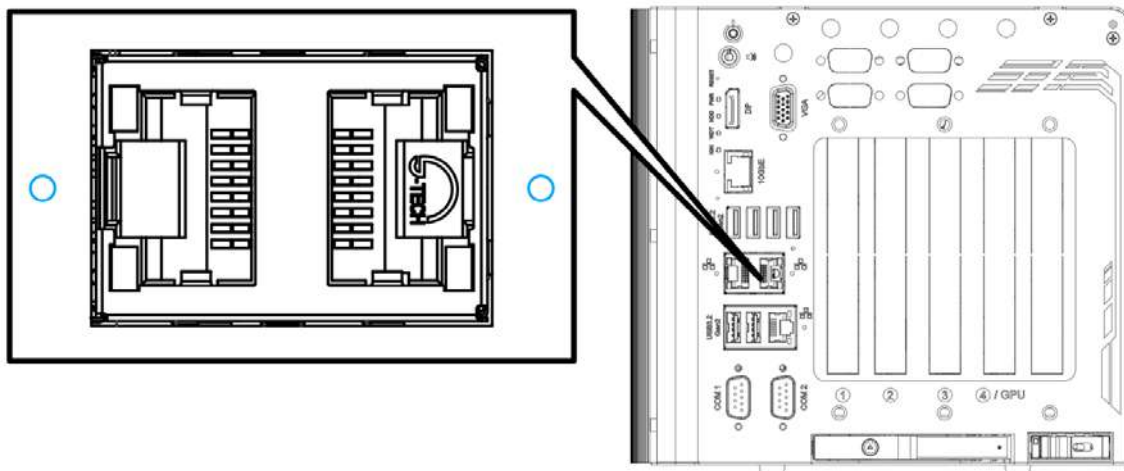
11. Insert the tray with the installed NVMe SSD back into the enclosure, and push the lever back in to complete the installation. The tray is also lockable with the provided key when you purchase this optional kit.



If you need to install other components, please refer to respective sections

3.2.10 Ethernet Port Screw-lock

The system's RJ45 Ethernet ports have panel screw holes (indicated in **blue**) for a firm cable connection.



1. To install and make use to the panel screw hole connection, you must acquire cables with screws shown in the illustration below.

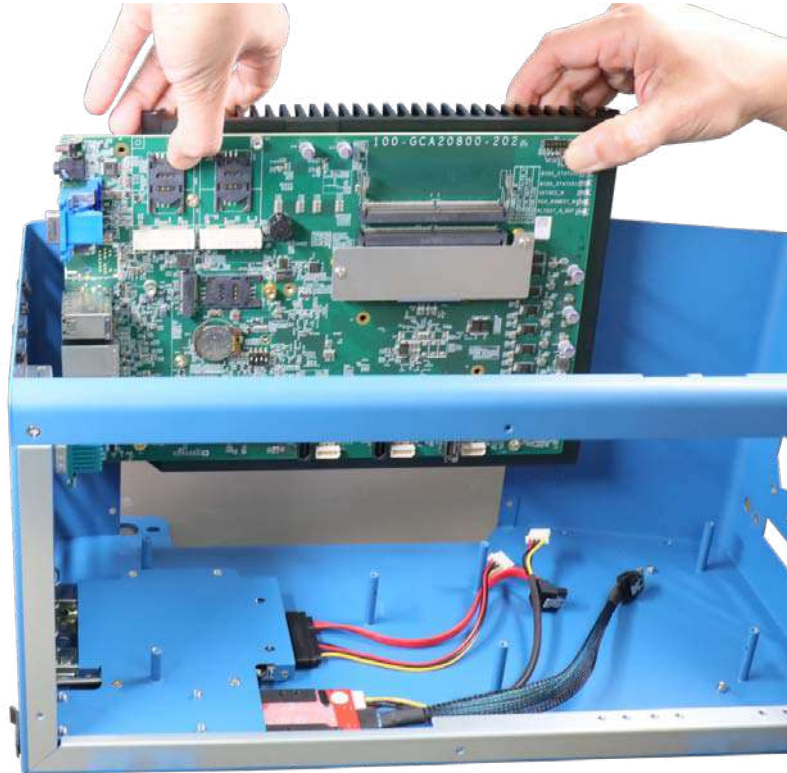


2. Simply insert the RJ45 connector into the RJ45 port and secure the top and bottom screws using your fingers or a screw driver.

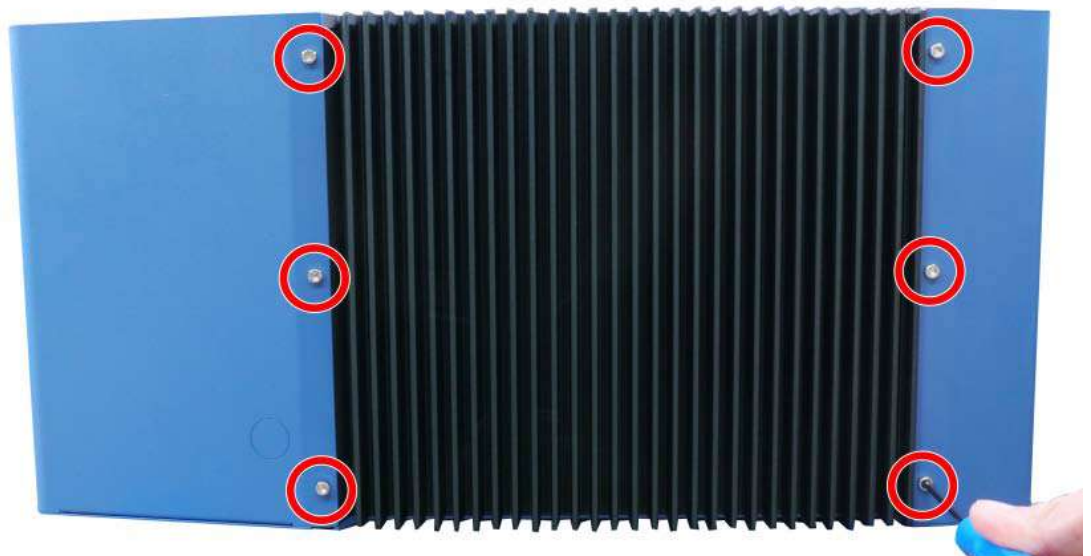


3.3 Installing the System Enclosure

1. Once you have installed all the modules and components onto the motherboard.
Re-install the motherboard/ heatsink with the enclosure by securing the screws indicated.



Re-insert the motherboard/ heatsink

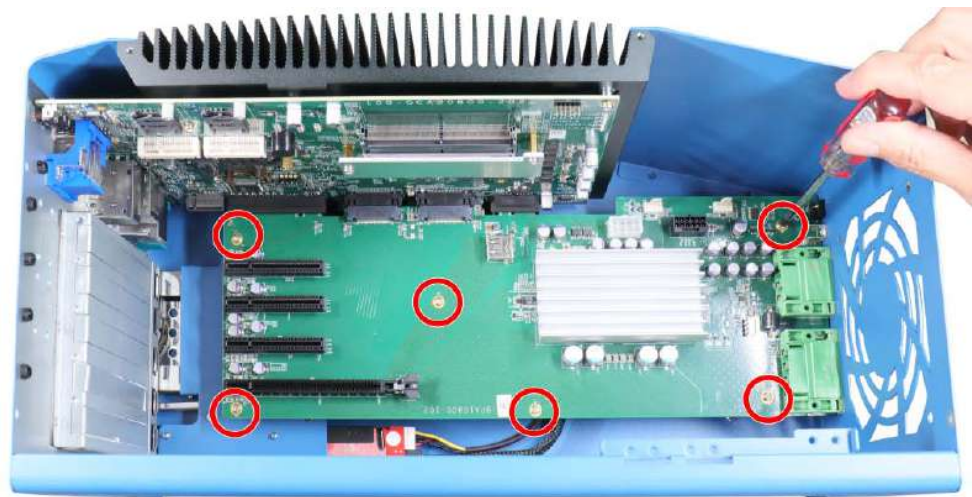


Secure with screws

2. Install the daughterboard and secure it with the screws indicated.

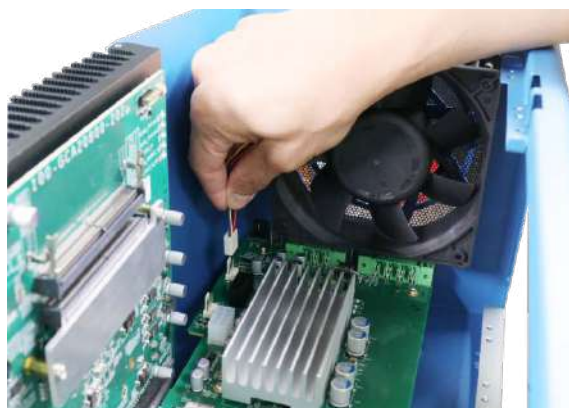


Install the daughterboard



Secure the daughterboard

3. Connect the fan's 4-pin power cable onto the daughterboard and secure the fan.



Connect the 4-pin cable



Secure the fan

4. Place the L-shape panel onto the enclosure.

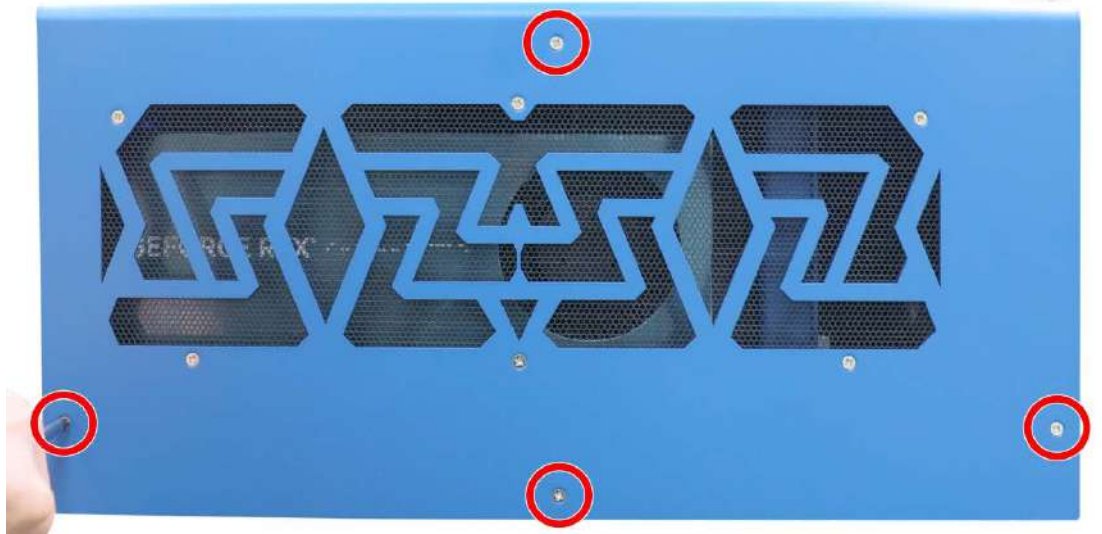


Place L-shape side panel onto the enclosure

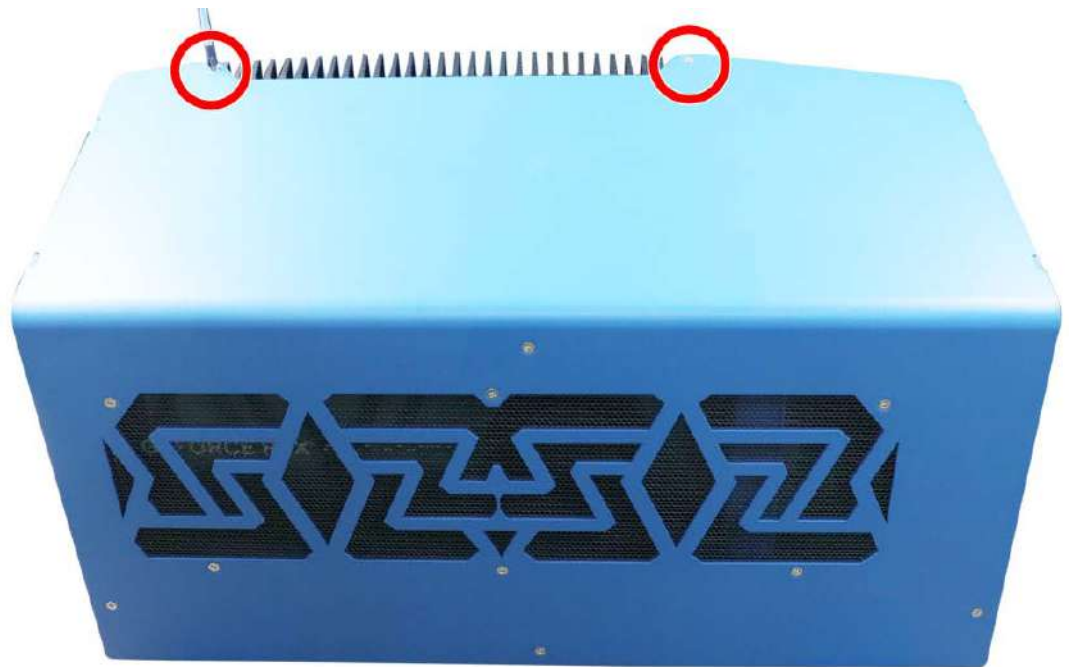
5. Secure the screws indicated on the I/O panel.



6. Secure the screws indicated on the side panel.



7. Secure the screws indicated on the top of the enclosure.



8. Secure the two screws indicated on the rear panel to complete the enclosure installation process.



3.4 Mounting and Anti-vibration Damping Bracket Installation

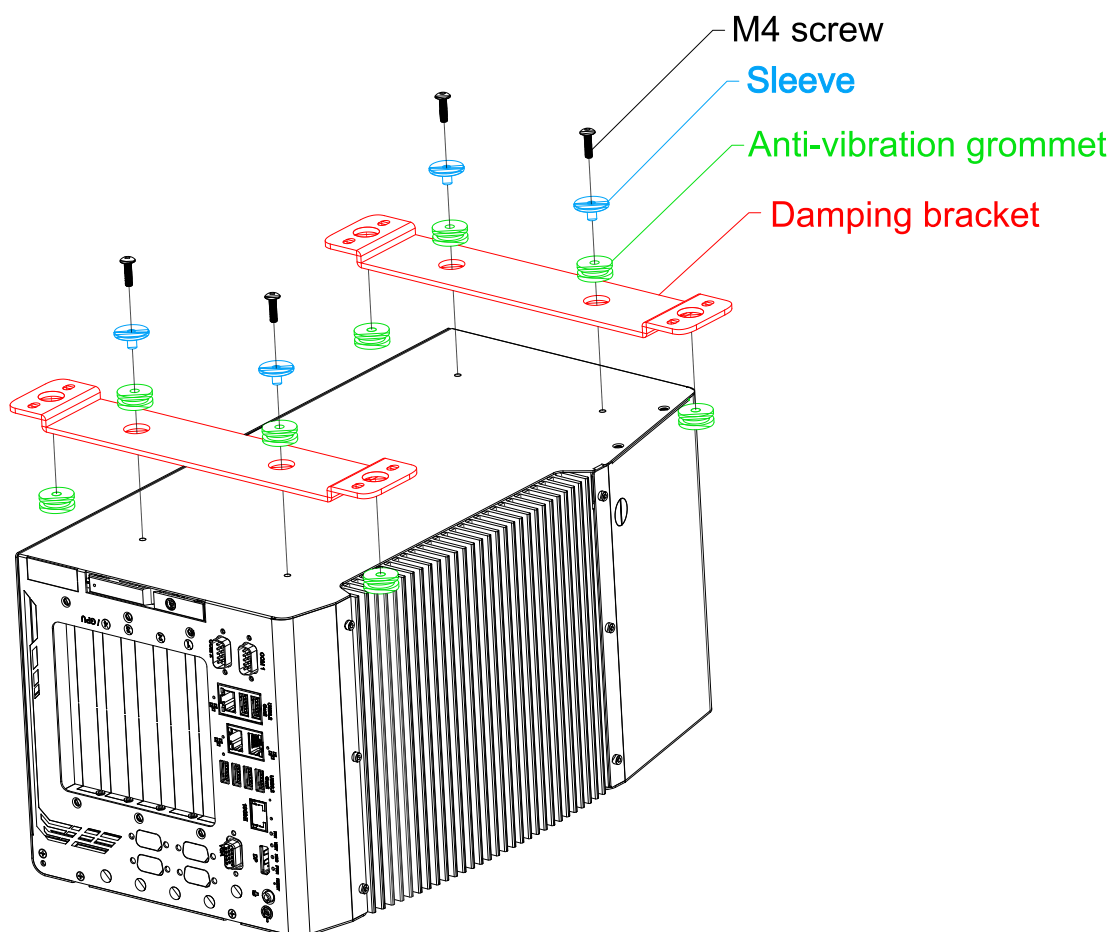


NOTE

You will need to remove the four (4) rubber stands at the bottom of the enclosure if they have been attached.

The damping bracket offers superior operating vibration resistance up to 1Grms with HDD or up to 5Grms with SSD. Please refer to the Nuvo-8108GC exploded illustration below on installing damping bracket. The damping brackets and screws can be found in the accessory box.

1. Take out the **anti-vibration damping brackets**, M4 screws, **sleeves** and **anti-vibration grommets** from the accessory box. Insert the M4 screws into the sleeves and through the anti-vibration grommets to secure the brackets to the system.



2. Place the system on top of a flat horizontal surface and secure it with screws.

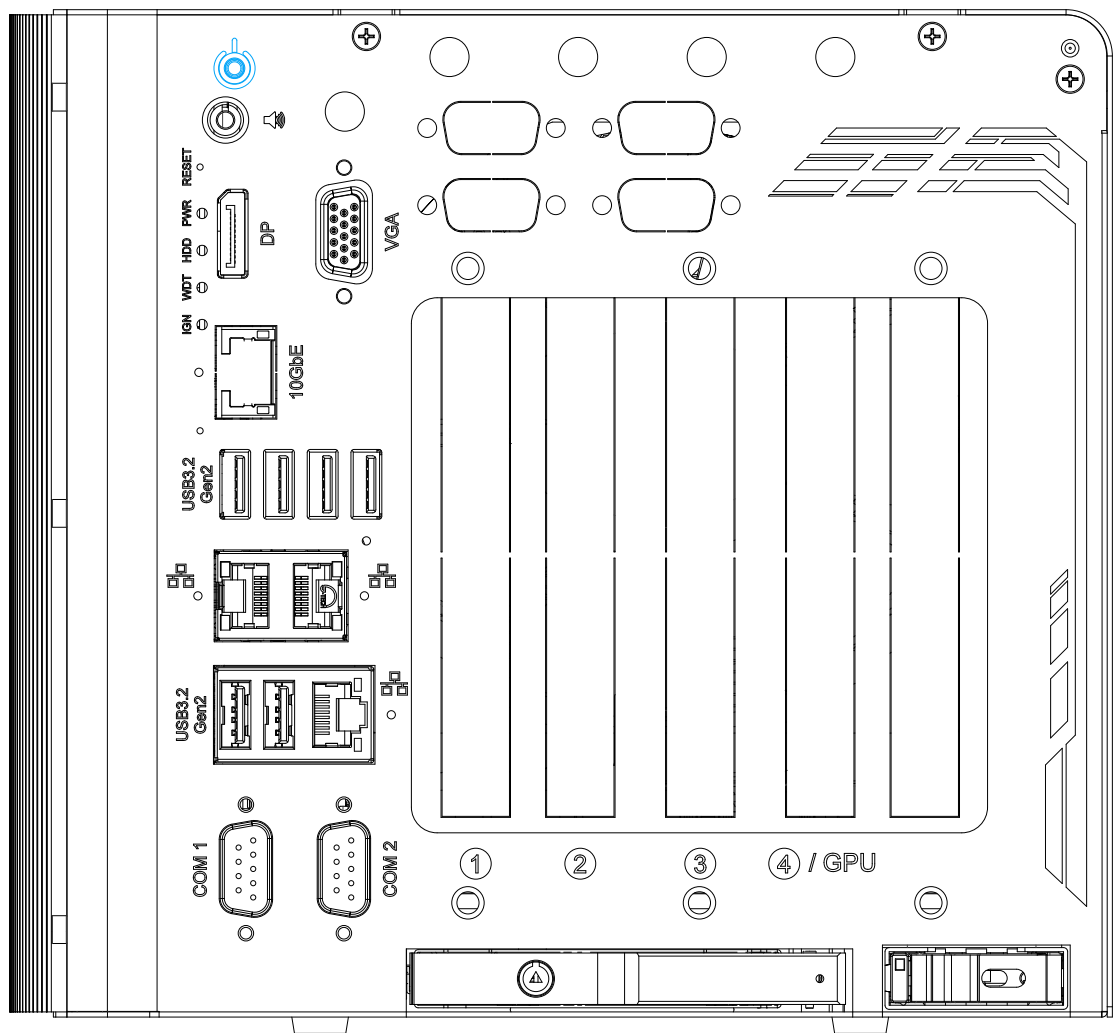
3.5 Powering On the System

There are three methods to power on the system

- Pressing the power button
- Sending a LAN packet via Ethernet (Wake-on-LAN)
- Powering on via ignition control (please refer to [Ignition Control](#) section)

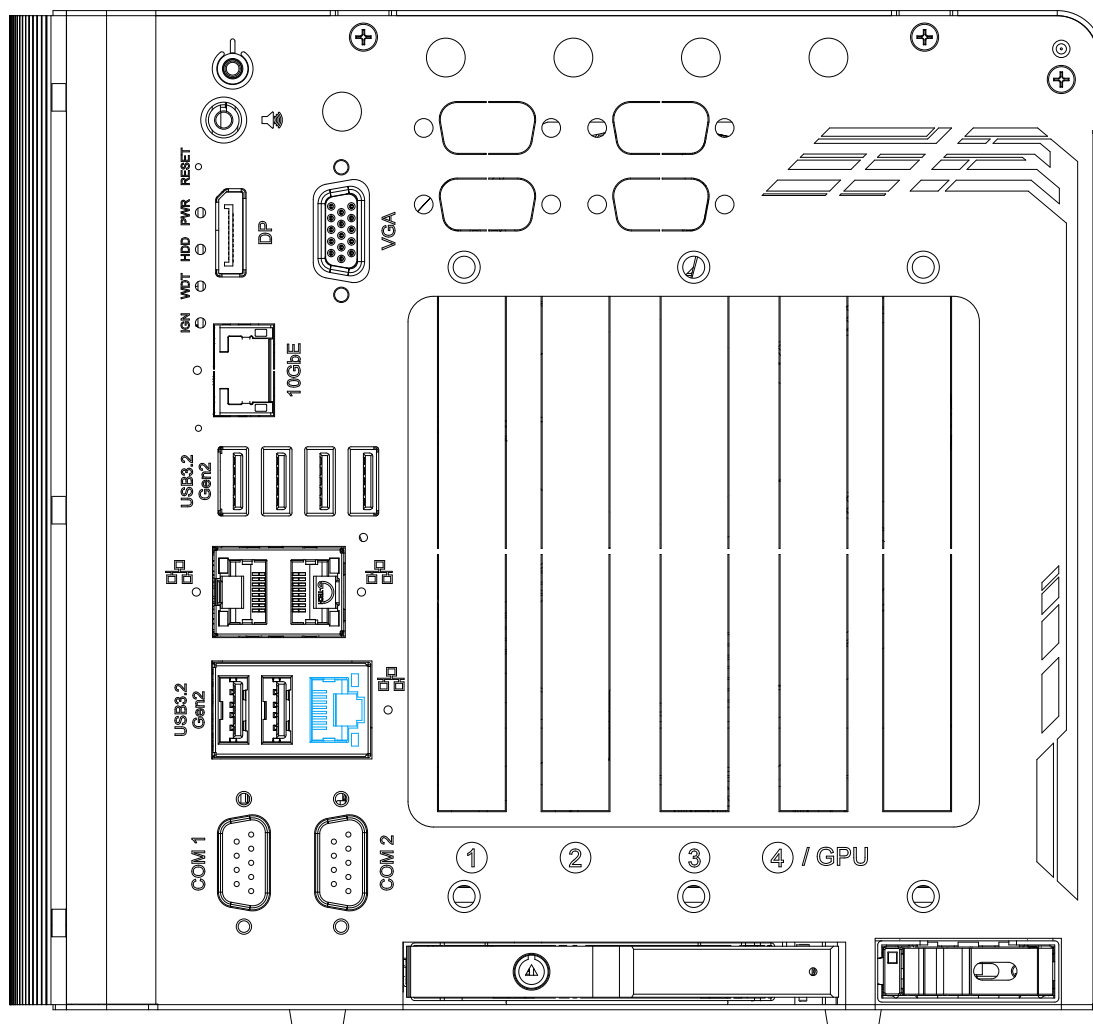
3.5.1 Powering On Using the Power Button

This is the simplest way to turn on your system. The power button is a non-latched switch and behaves as the ATX-mode on/off control. With DC power connected, pushing the power button will turn on the system and the PWR LED indicator will light up. Pushing the button when system is on will turn off the system. If your operating system supports ATX power mode (i.e. Microsoft Windows or Linux), pushing the power button while the system is in operation will result in a pre-defined system behavior, such as shutdown or hibernation.



3.5.2 Powering On Using Wake-on-LAN

Wake-on-LAN (WOL) is a mechanism to wake up a computer system from a S5 (system off with standby power) state via issuing a magic packet. The system's Wake-on-LAN compatible GbE port is shown below.



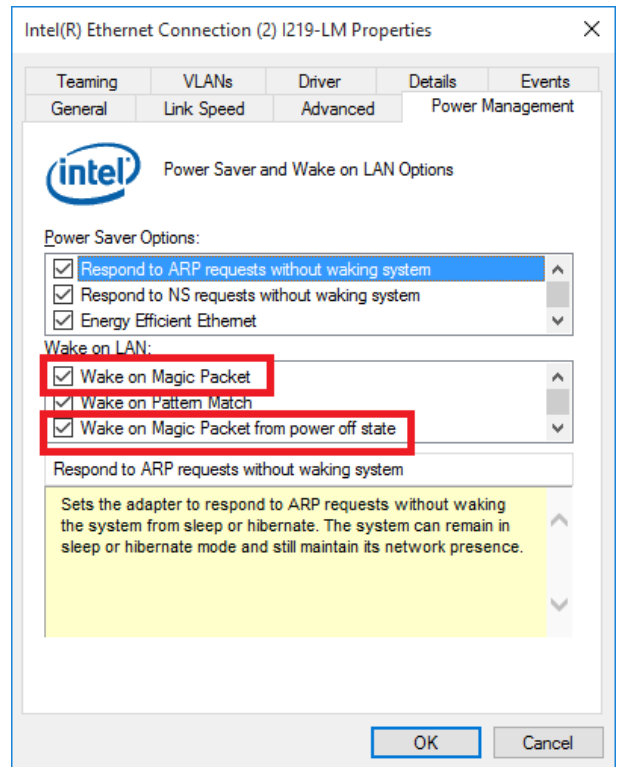
NOTE

Please make sure the Intel chipset and Ethernet driver has been properly installed prior to setting up WOL function.

To enable WOL function, please set up WOL settings in the BIOS and in the operating system by follow the steps described below.

1. When the system boots up, press F2 to enter BIOS setup utility.
2. Go to the **[Power]>[Wake On LAN]** and set it to **[Enabled]**.
3. Press F10 to **"Save changes and exit BIOS"** and allow the system boot into the operating system.

4. Once booted into the Windows system, press "**Windows key + E**", right-click on "**Network>Properties>Change adapter settings**". Locate and double-click on the adapter Intel® I219 Gigabit Network Connection, click on **Configure...**
5. Click on the **Power Management** tab and check the following options. Click on OK when done.

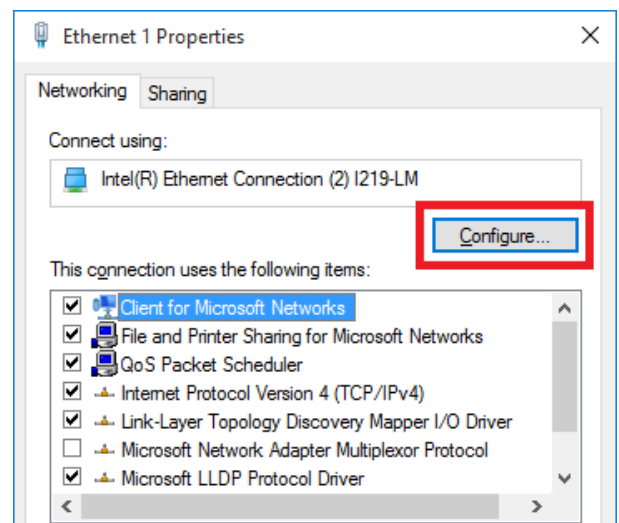


Magic Packet

The magic packet is a broadcast frame containing anywhere within its payload 6 bytes of all 255 (FF FF FF FF FF FF in hexadecimal), followed by sixteen repetitions of the target computer's 48-bit MAC address.

For example, NIC's 48-bit MAC Address is 78h D0h 04h 0Ah 0Bh 0Ch
 DESTINATION SOURCE MISC
 FF FF FF FF FF FF

78 D0 04 0A 0B 0C	78 D0 04 0A 0B 0C
78 D0 04 0A 0B 0C	78 D0 04 0A 0B 0C
78 D0 04 0A 0B 0C	78 D0 04 0A 0B 0C
78 D0 04 0A 0B 0C	78 D0 04 0A 0B 0C
78 D0 04 0A 0B 0C	78 D0 04 0A 0B 0C
78 D0 04 0A 0B 0C	78 D0 04 0A 0B 0C
78 D0 04 0A 0B 0C	78 D0 04 0A 0B 0C
78 D0 04 0A 0B 0C	78 D0 04 0A 0B 0C
78 D0 04 0A 0B 0C	78 D0 04 0A 0B 0C
MISC	CRC



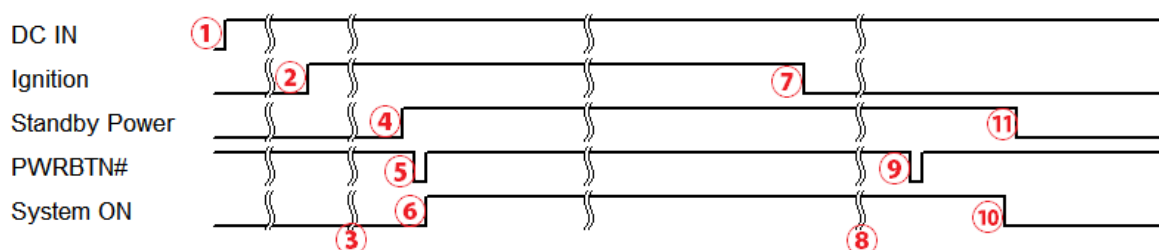
There are some free tools available on Internet that can be used to send a magic packet. Please refer to the following link to understand more about [Magic Packet](#).

3.6 Ignition Power Control

The ignition power control module for in-vehicle applications is a MCU-based implementation that monitors the ignition signal and reacts to turn on/off the system according to predefined on/off delay. Its built-in algorithm supports other features such as ultra-low power standby, battery-low protection, system hard-off, etc. In this section, we'll illustrate the principle of ignition power control and operation modes.

3.6.1 Principles of Ignition Power Control

The basic concept of ignition power control module is to control the timing correlation between ignition signal and system power status. A typical timing correlation is described in following diagram.



1. When DC power is supplied to the system, MCU starts to periodically detect ignition signal.
Note that only MCU is working at this moment and the overall power consumption is less than 2 mW.
2. Ignition signal is active (both 12VDC and 24VDC ignition signals are accepted).
3. MCU starts to count a pre-defined power-on delay.
4. Once power-on delay expired, MCU turns on necessary standby power for the system (3.3VSB & 5VSB).
5. A PWRBTN# pulse is then issued to turn on the system (equivalent to one pressing the power button on the front panel).
6. The system is booting and becomes operational.
7. After a period of time, the ignition signal becomes inactive.
8. MCU starts to count a pre-defined power-off delay.
9. Once power-off delay expired, another PWRBTN# pulse is issued to perform a soft-off for the system (ex. a normal shutdown process for Windows system).
10. The system is completely shut down.
11. As MCU detects system is off, it turns off the standby power for the system, and operates in low power mode again (< 2mW power consumption).

3.6.2 Additional Features of Ignition Power Control

In addition to the typical timing correlation, the ignition power control module offers additional features to provide additional reliability for in-vehicle applications.

1. Low battery detection

The ignition power control module continuously monitors the voltage of DC input when the system is operational. If input voltage is less than 11V (for 12VDC input) or less than 22V (for 24VDC input) over a 60-second duration, it will shut down the system automatically.

2. Guarded power-on/ power-off delay duration

If ignition signal goes inactive during the power-on delay duration, the ignition power control module will cancel the power-on delay process and go back to idle status. Likewise if ignition signal goes active during the power-off delay duration, the ignition power control module will cancel the power-off delay process and keep the system running.

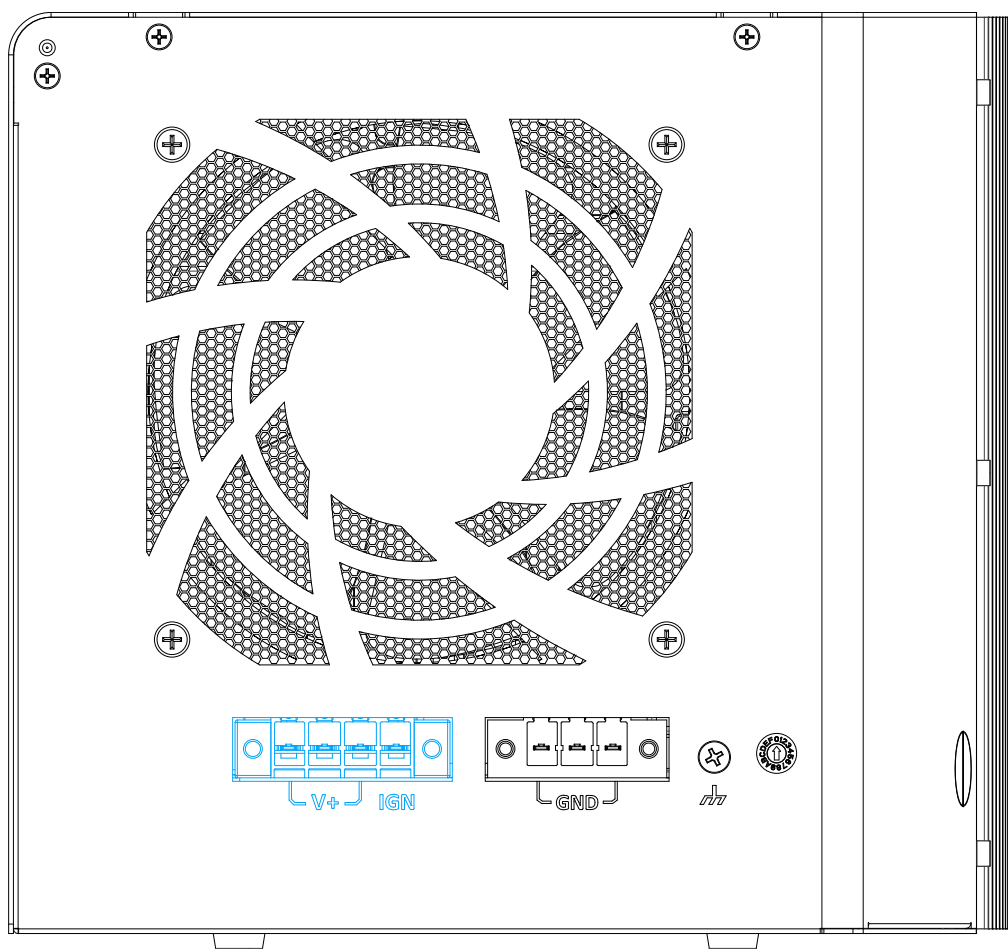
3. System hard-off

In some cases, system may fail to shutdown via a soft-off operation due to system/application halts. The ignition power control module offers a mechanism called "hard-off" to handle this unexpected condition. By detecting the system status, it can determine whether the system is shutting down normally. If not, the ignition power control module will force cut-off the system power 10 minutes after the power-off delay duration.

4. Smart off-delay

The ignition power control module offers two modes (mode 13 & mode 14) which have very long power-off delay duration for applications require additional off-line time to process after the vehicle has stopped. In these two modes, the ignition power control module will automatically detect the system status during the power-off delay duration. If the system has shutdown (by the application software) prior to power-off delay expiring, it will cut off the system power immediately to prevent further battery consumption.

3.6.3 Wiring Ignition Signal



To have ignition power control for in-vehicle usage, you need to supply IGN signal to the system. The IGN input is located on the 4-pin pluggable terminal block (shared with DC power input). Below is the typical wiring configuration for in-vehicle applications.

1. Connect car Battery+ line (12V for sedan, 24V for bus/truck) to V+.
2. Connect car Batter-/ GND line to GND.
3. Connect ACC line to IGN.



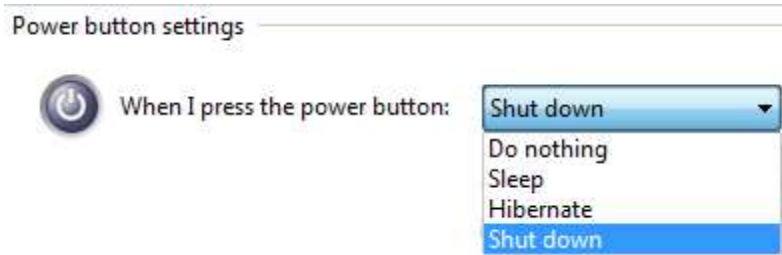
WARNING

Please make sure your DC power source and IGN signal share the same ground.

IGN input accepts 8~48VDC. Supply a voltage higher than 48VDC may damage the system.

3.6.4 Configure your Windows system

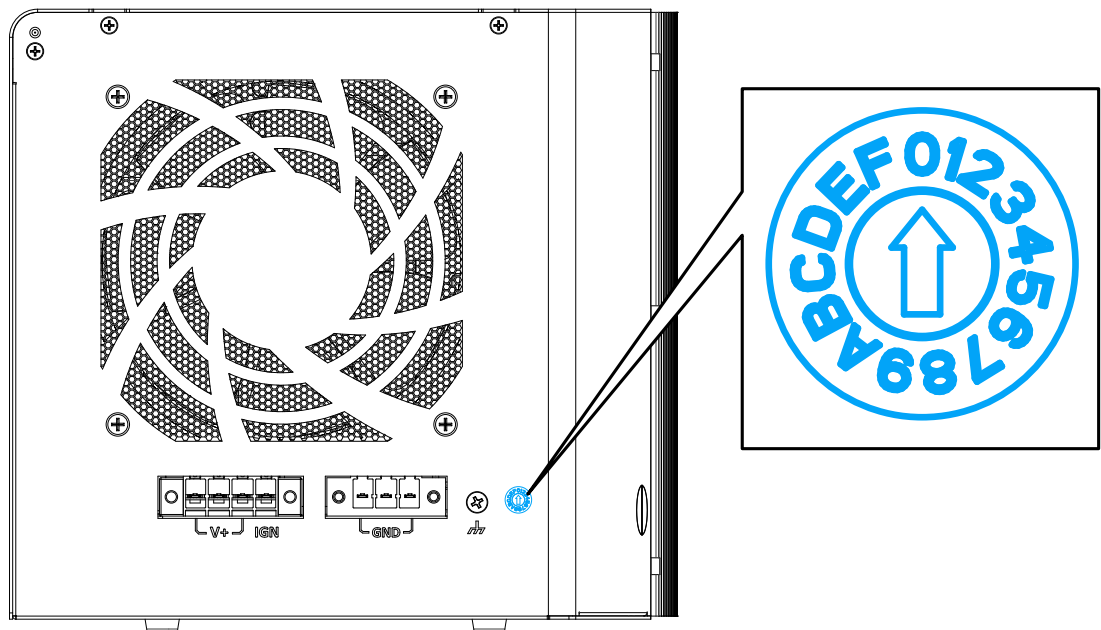
When applying ignition power control to your system, please make sure you've configured your Windows system to initiate a shutdown process when pressing the power button. By default, Windows 10 goes to sleep (S3) mode when power button is pressed. As sleep (S3) is not a complete shutdown behavior, the ignition control function does not recognize the finish of a normal shut down process and thus users will encounter a system hard-off (power cut-off after 10 minutes). Please configure "When I press the power button" to "Shut down" in your Windows system settings.



3.6.5 Operation Modes of Ignition Power Control

You can use the rotary switch to configure the operation mode. The system offers 16 (0~15) operation modes with different power-on/power-off delay configurations.

When rotary switch is set to mode 15 (0xF), the ignition power control is set to executed according to parameters configured in BIOS setup menu, which allows richer combination of power-on/ power-off delay and more detailed control parameters.



- **Mode 0**

Mode 0 is the ATX mode without power-on and power-off delay. User can only use the power button on the front panel to turn on or turn off the system.

Mode	Power-on Delay	Power-off Delay	Hard-off Timeout
0	N/A	N/A	N/A

- **Mode 1**

Mode 1 is AT mode without power-on and power-off delay. The system automatically turns on when DC power is applied. A retry mechanism is designed to repeat the power-on cycle if the system fails to boot up.

Mode	Power-on Delay	Power-off Delay	Hard-off Timeout
1	N/A	N/A	N/A

- **Mode 2**

Mode 2 is designed to have a very minor power on/ off delay of 160ms for applications that requires the system to start up almost at the same as the rest of the equipment it is working in collaboration with.

Mode	Power-on Delay	Power-off Delay	Hard-off Timeout
2	160ms	160ms	10 minutes

- **Mode 3 ~ Mode 12**

Mode 3 ~ Mode 12 have various power-on delay and power-off delay. Each mode supports a hard-off timeout of 10 minutes.

Mode	Power-on Delay	Power-off Delay	Hard-off Timeout
3	10 seconds	10 seconds	10 minutes
4	10 seconds	1 minute	10 minutes
5	10 seconds	5 minutes	10 minutes
6	30 seconds	1 minute	10 minutes
7	30 seconds	5 minutes	10 minutes
8	30 seconds	10 minutes	10 minutes
9	3 minutes	1 minute	10 minutes
10 (A)	3 minutes	10 minutes	10 minutes
11 (B)	3 minutes	30 minutes	10 minutes
12 (C)	10 minutes	30 minutes	10 minutes

- **Mode 13 (D) / Mode 14 (E)**

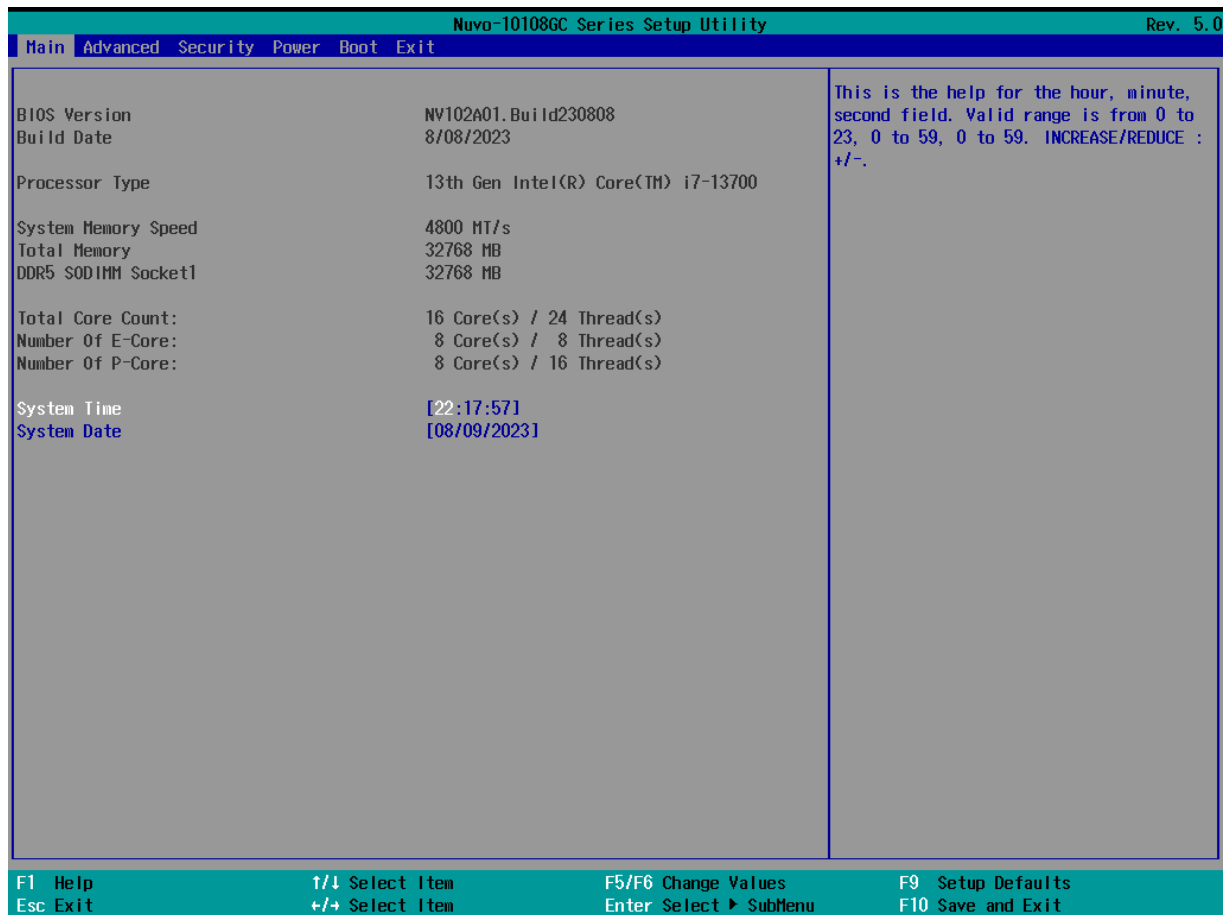
Mode 13 and Mode 14 are ignition power control modes with very long power-off delay. Both modes support the feature of “smart off-delay”, which automatically detect system status during power-off delay duration and cut off system power if system is off in prior to power-off delay expired.

Mode	Power-on Delay	Power-off Delay	Hard-off Timeout
13 (D)	30 seconds	2 hours	10 minutes
14 (E)	3 minutes	2 hours	10 minutes
15 (F)	Reserved		

4 System Configuration

4.1 BIOS Settings

The system is shipped with factory-default BIOS settings meticulously programmed for optimum performance and compatibility. In this section, we'll illustrate some of BIOS settings you may need to modify. Please always make sure you understand the effect of change before you proceed with any modification. If you are unsure of the function you are changing, it is recommended to change one setting at a time to see its effect(s).

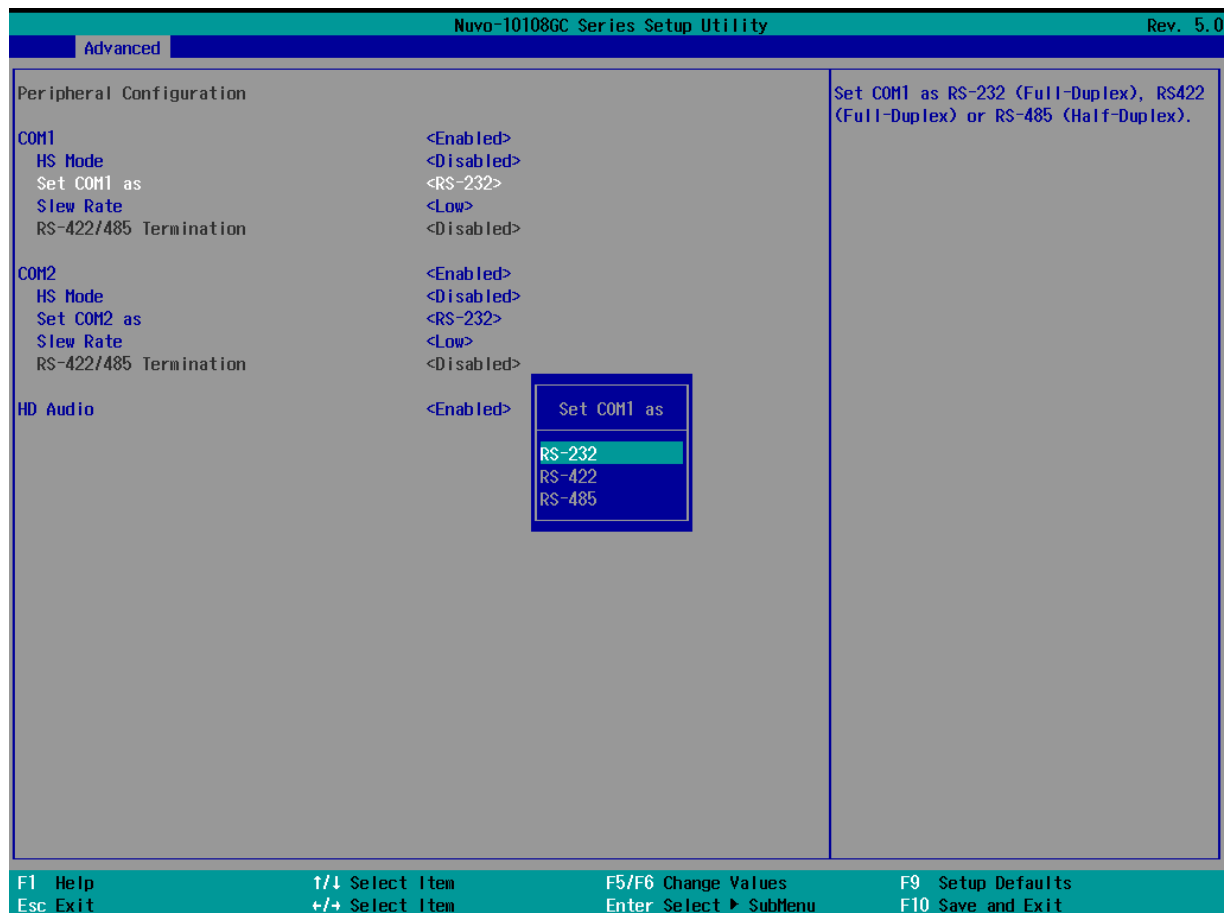


NOTE

Not all BIOS settings will be discussed in this section. If a particular setting/ function you are after requires specific BIOS settings but is not discussed in this section, please contact Neusys Technical Support staff.

4.1.1 COM Port Configuration

The system's [COM1/ COM2](#) ports support RS-232 (full-duplex), RS-422 (full-duplex) and RS-485 (half-duplex) mode. You can set the COM1 operating mode via BIOS settings. Another option in BIOS called “*Slew Rate*” defines how sharp the rising/falling edge is for the output signal of COM1. For long-distance RS-422/ 485 transmission, you may set the “*Slew Rate*” option as “High” to improve signal quality. For RS-422/485 communication, the “*RS-422/ 485 Termination*” option determines whether to enable/disable internal termination of RS-422/ 485 transceiver according to your wiring configuration (e.g. with or without external termination).

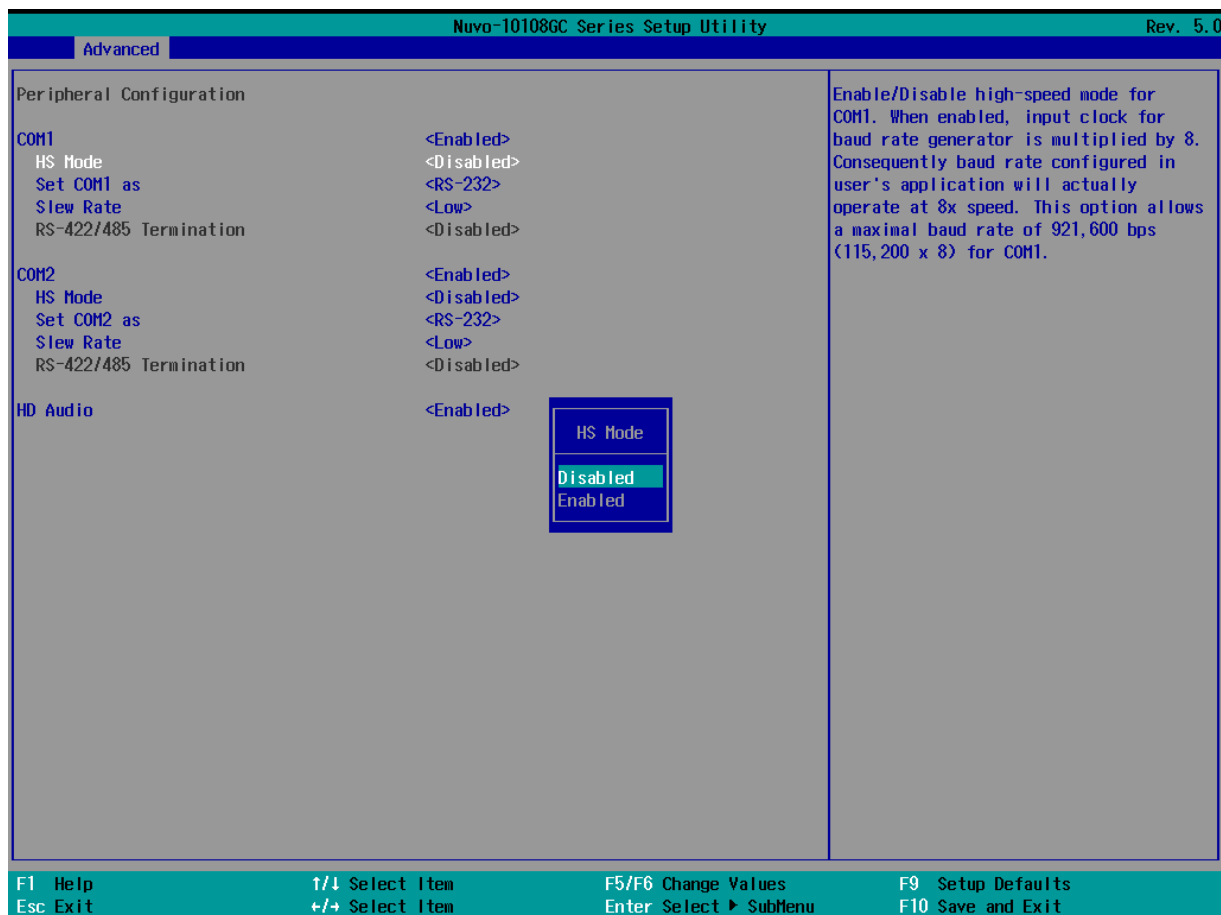


To set COM port operating mode:

1. Press **F2** when the system boots up to enter the BIOS setup utility.
2. Go to **[Advanced] → [Peripheral Configuration]**.
3. Set the **[Set COM1 Mode as]** option to the desired mode.
4. Once set, press **F10** to save setting and exit.

4.1.2 COM Port High Speed Mode

The high speed mode of each COM port effectively allows for the port's baud rate generator to operate at 8x the speed with an effective baud rate of 921,600 bps (115,200 x 8). Please refer to the following instructions on how to enable the high speed mode for your COM port (COM1 used as an example).

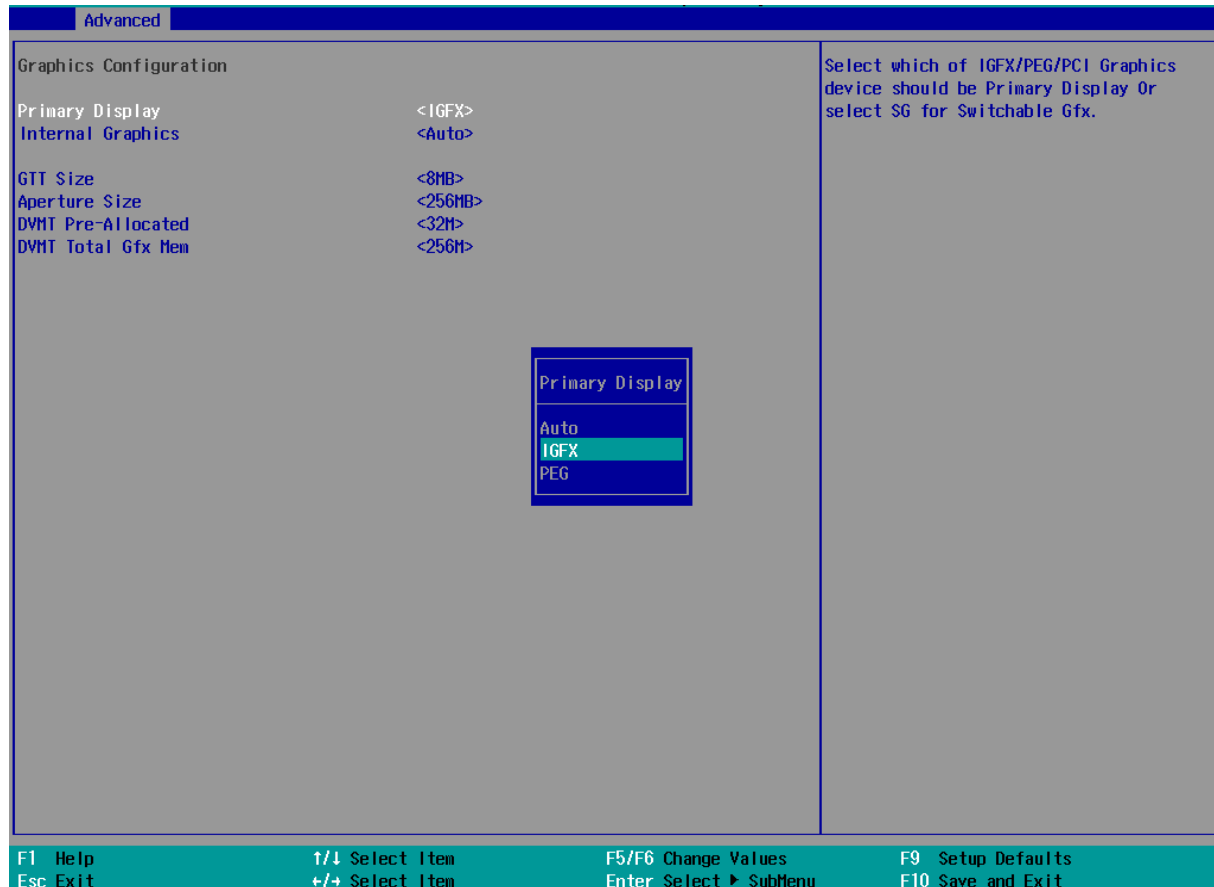


To set COM port high speed mode:

1. Press **F2** when the system boots up to enter the BIOS setup utility.
2. Go to **[Advanced] > [Peripheral Configuration]**.
3. Enable or set the **[Set COM1 Mode as]** option to the desired mode.
4. Highlight **[HS Mode]** and press ENTER to bring up options, highlight **[Enable]** and press ENTER.
5. Once set, press **F10** to save setting and exit.

4.1.3 Primary Display

This setting offers display output selection. Users can choose between Auto (auto detection), IGFX (integrated graphics card on CPU where applicable) or PEG (PCIe graphics card).

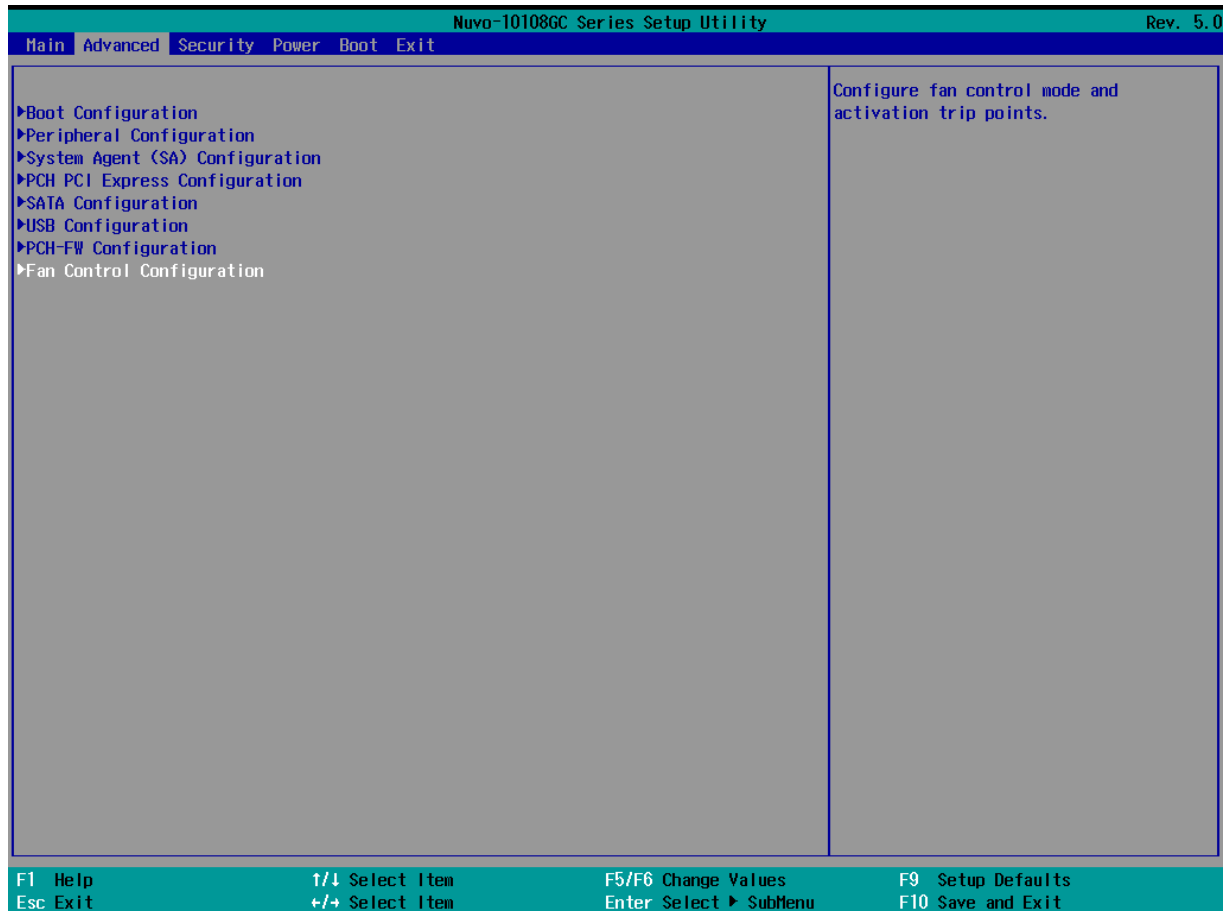


To set the primary display:

1. When system boots up, press F2 to enter BIOS setup utility.
2. Go to **[Advanced] > [System Agent (SA) Configuration] > [Graphics Configuration] > [Primary Display]** and press ENTER.
3. Use the arrow key to select your primary display settings: Auto/ IGFX/ PEG and press Enter to make your selection.
4. When done, press F10 to "Exit Saving Changes"

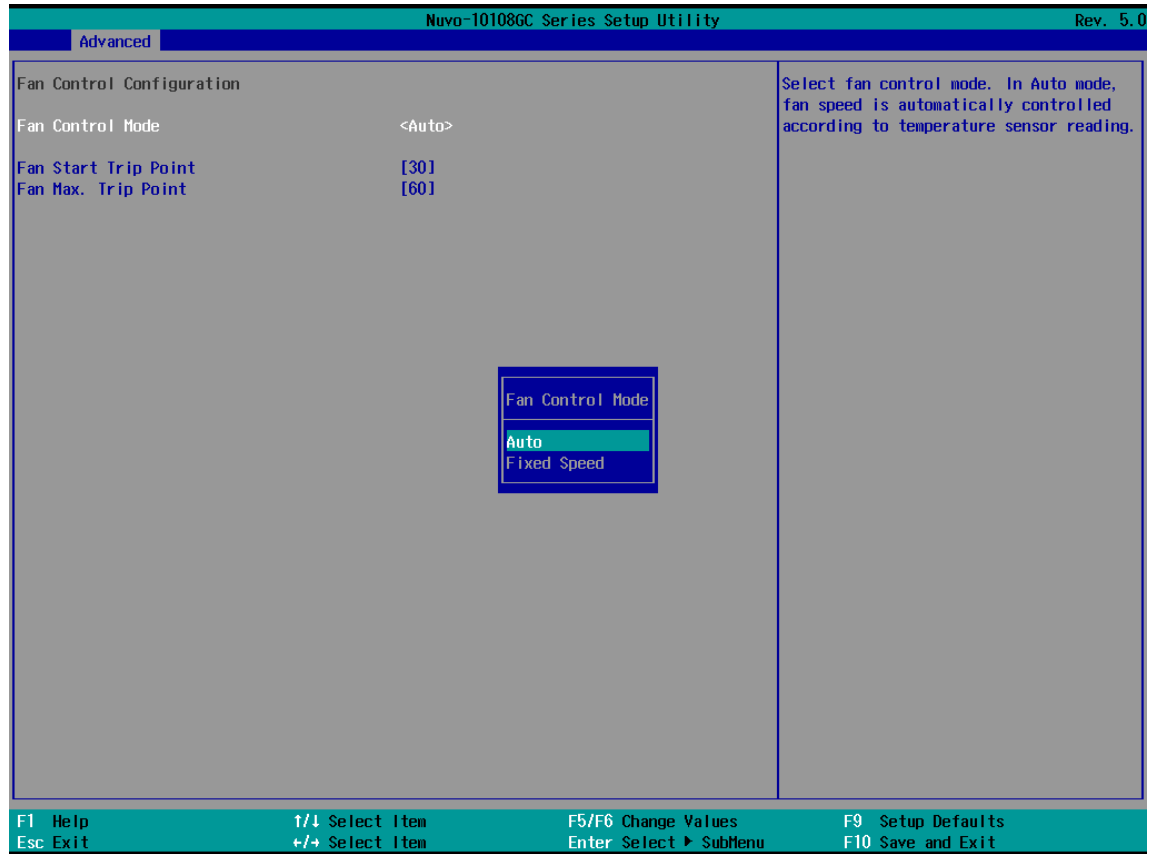
4.1.4 Fan Control Configuration

The fan control configuration allows users to set the fan operation mode to auto or fixed speeds operation. The auto mode configuration also offers minimum temperature setting to trigger the fan and the maximum temperature setting before the fan operates at 100% rotation speed.



To set Fan Control Configuration to Auto mode:

1. When system boots up, press F2 to enter BIOS setup utility.
2. Go to **[Advanced]** > **[Fan Control Configuration]** and press ENTER.
3. To set auto fan control, highlight **[Fan Control Mode]** and press ENTER, highlight **[Auto]**



4. Use the up/ down arrow keys to highlight Fan Start Trip Point or Fan Max. Trip Point and press ENTER, a window appears and you may enter the temperature in degree Celsius.
 - **Fan Start Trip Point:** The minimum temperature which the fan being to operate
 - **Fan Max. Trip Point:** The maximum temperature where the fan begins to operate at 100% rotation speed

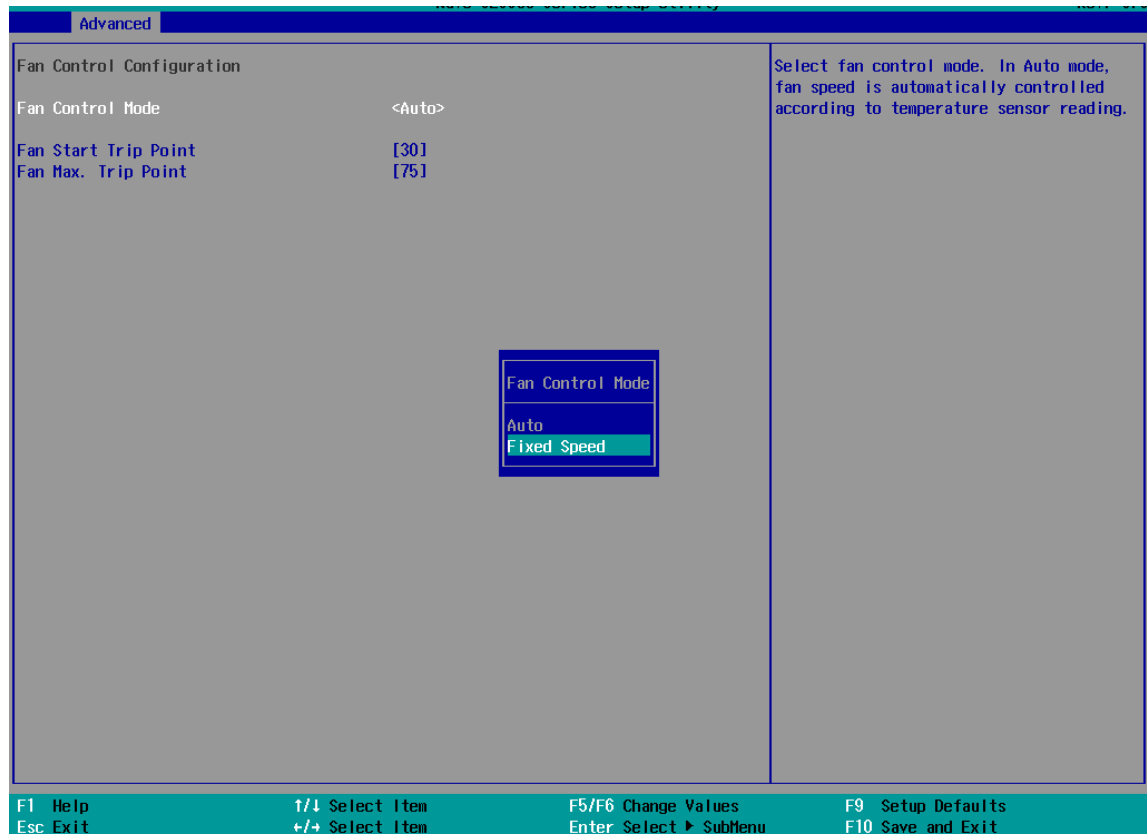
The screenshot displays the 'Advanced' setup menu for the Nuvo-10108GC Series. The title bar reads 'Nuvo-10108GC Series Setup Utility' and 'Rev. 5.0'. The 'Advanced' tab is selected. The main area is titled 'Fan Control Configuration' and shows two settings: 'Fan Control Mode' set to '<Auto>' and 'Fan Start Trip Point' set to '[30]'. Below these, 'Fan Max. Trip Point' is set to '[60]'. A help text box on the right explains: 'Specify tht trip point in degrees Celsius to start the fan. Fan speed is automatically controlled between start and max. trip point according to reading of on-board temperature sensor.' A small dialog box with a blue bar and '[Yes] [No]' buttons is centered on the screen. The bottom status bar lists function keys: F1 Help, Esc Exit, ↑/↓ Select Item, ←/→ Select Item, F5/F6 Change Values, Enter Select ► SubMenu, F9 Setup Defaults, and F10 Save and Exit.

Nuvo-10108GC Series Setup Utility		Rev. 5.0
Advanced		
Fan Control Configuration		Specify tht trip point in degrees Celsius to start the fan. Fan speed is automatically controlled between start and max. trip point according to reading of on-board temperature sensor.
Fan Control Mode	<Auto>	
Fan Start Trip Point	[30]	
Fan Max. Trip Point	[60]	
<div>[Yes] [No]</div>		
F1 Help Esc Exit	↑/↓ Select Item ←/→ Select Item	F5/F6 Change Values Enter Select ► SubMenu
		F9 Setup Defaults F10 Save and Exit

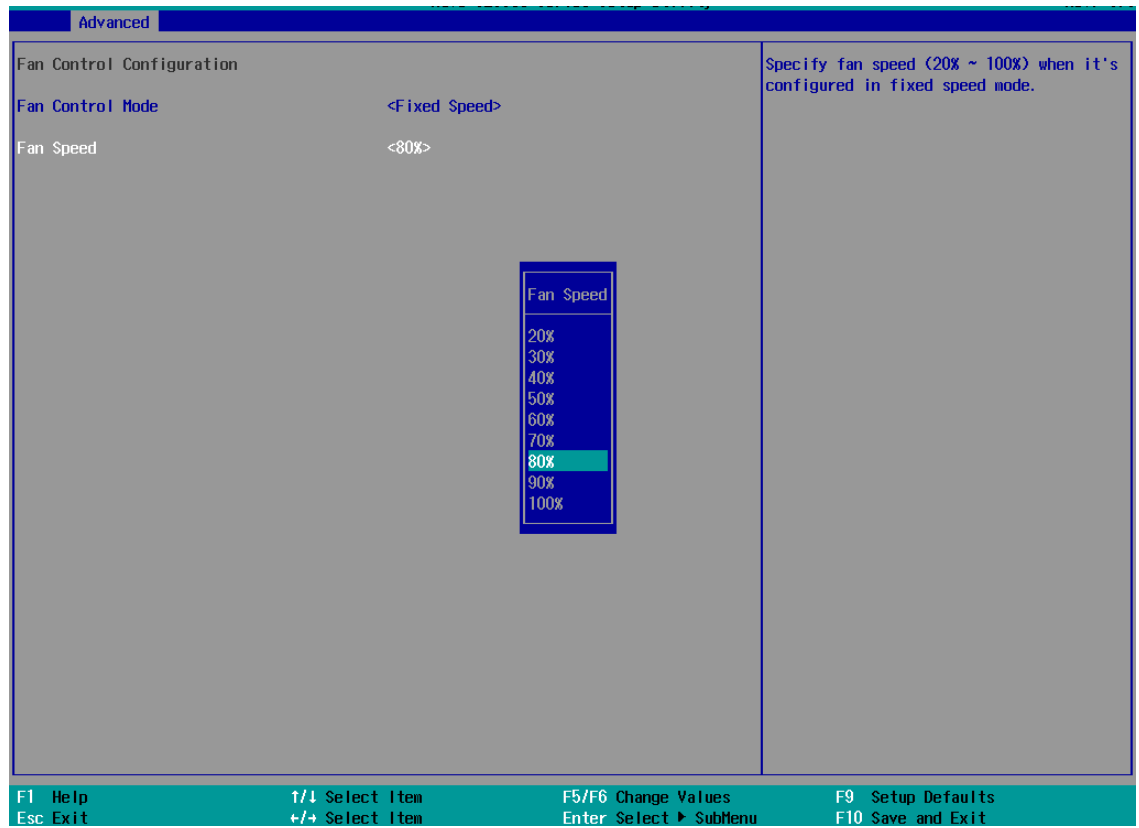
5. When done, press F10 to "Exit Saving Changes".

To set Fan Control Configuration to Fixed Speed mode:

1. When system boots up, press F2 to enter BIOS setup utility.
2. Go to **[Advanced]** > **[Fan Control Configuration]** and press ENTER.
3. To set auto fan control, highlight **[Fan Control Mode]** and press ENTER, highlight **[Fixed Speed]**.



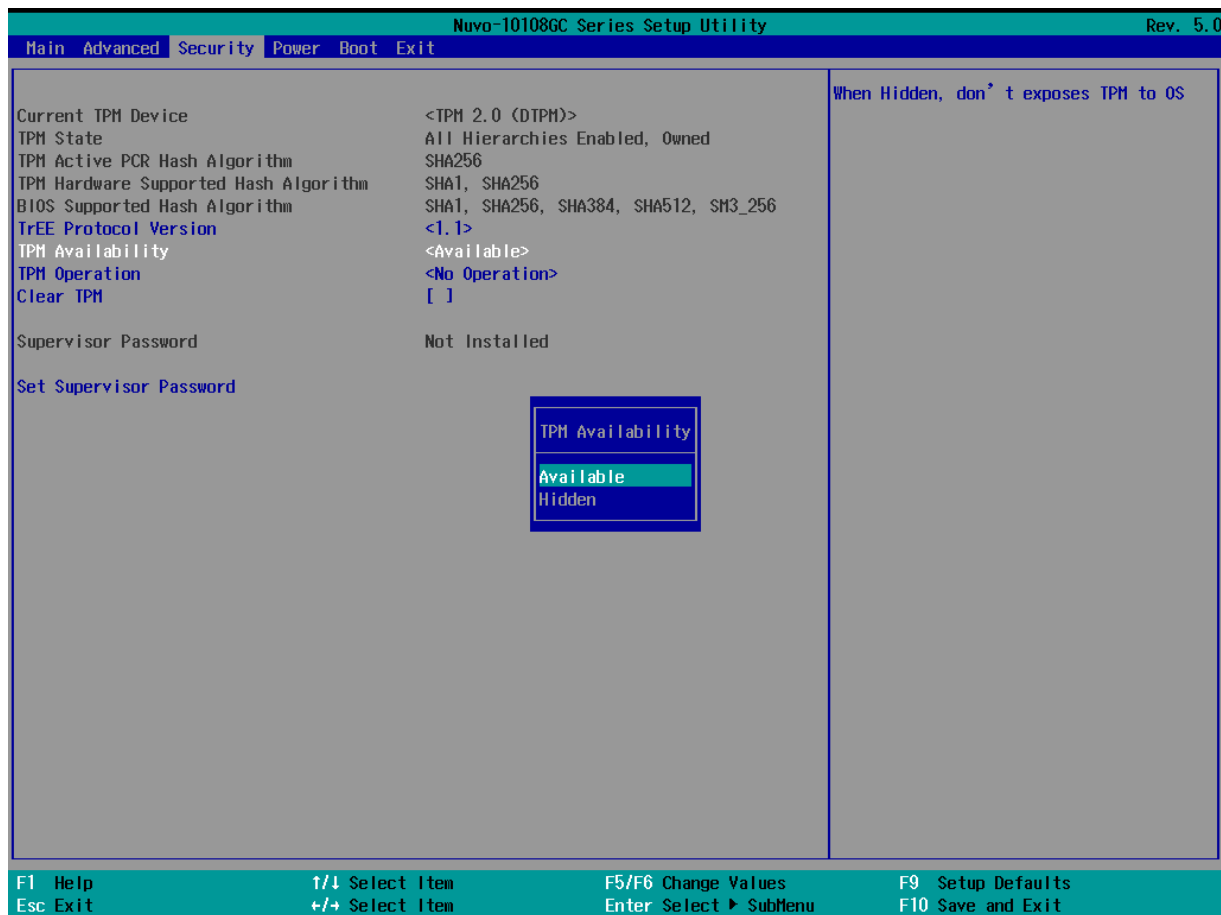
4. Highlight [**Fan Speed**] and press ENTER.
5. A window appears and you may use the up/ down arrow keys to select between 20~100% as your fixed fan rotation speed.



6. When done, press F10 to "Exit Saving Changes".

4.1.5 TPM Availability

Trusted Platform Module (TPM) is a hardware-based cryptoprocessor to secure hardware by integrating cryptographic keys into devices. The system is designed with on-board TPM 2.0 module. As TPM 2.0 requires 64-bit Windows 7/8/10 with UEFI boot mode, it is disabled in BIOS by default. For customers who want to utilize TPM feature, you will need to enable TPM in BIOS as well as install Windows with UEFI mode.



To enable TPM availability:

1. When system boots up, press F2 to enter BIOS setup utility.
2. Go to **[Security] > [TPM Availability]**, press ENTER to bring up Options, Available/Hidden.
3. Highlight your selection, press ENTER and press F10 to "Exit Saving Changes".

4.1.6 Auto Wake on S5

When the system is set to operate in S5 state, the user can specify a time to turn on the system, daily or monthly.

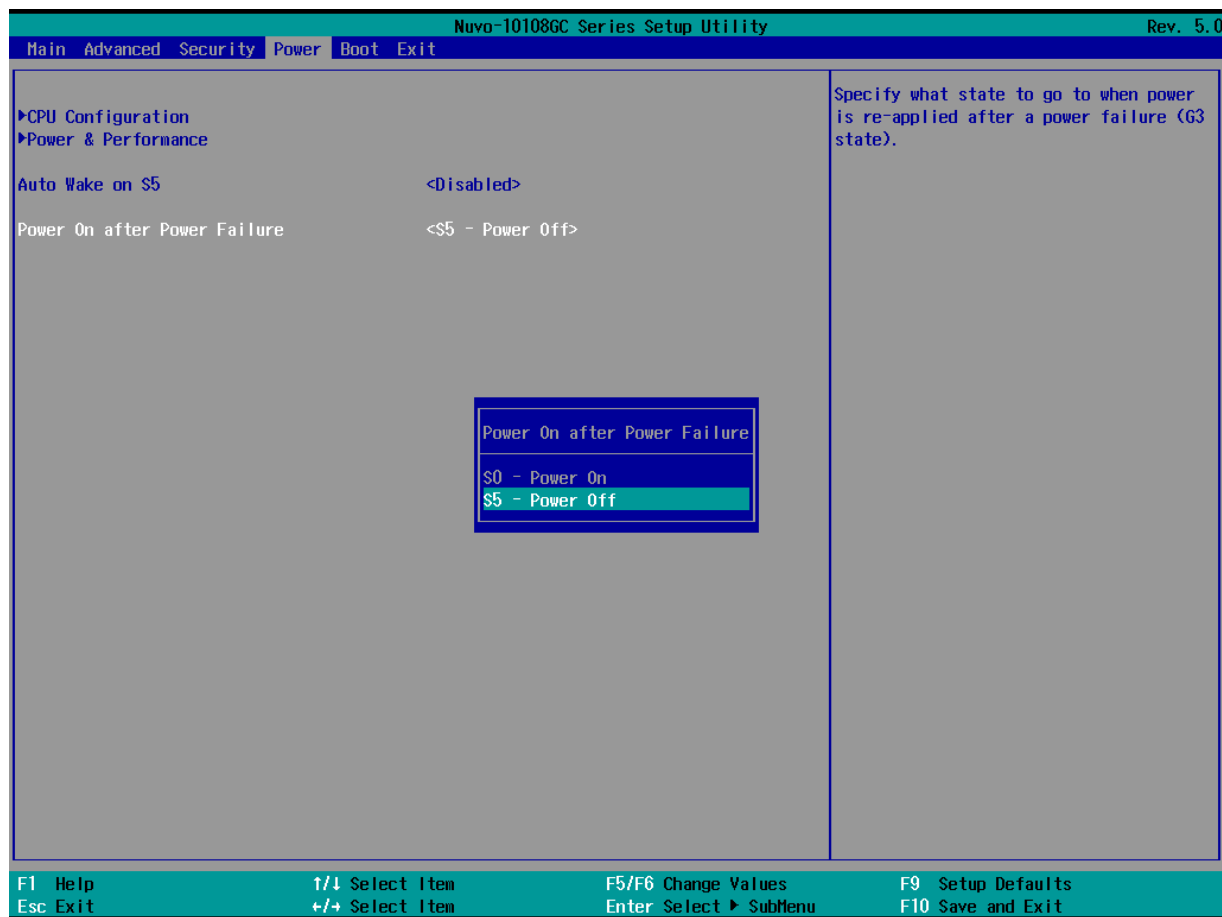


Value	Option	Description
Auto Wake on S5	Disabled	The system does not turn on when operating in state S5.
	By Every Day	The system turns on each day when operating in state S5. Specify the time of day.
	By Day of Month	The system turns on each month when operating in state S5. Specify the day and time.

Highlight your selection, press ENTER and press F10 to “Exit Saving Changes”.

4.1.7 Power On After Power Failure Option

This option defines the behavior of System series when DC power is supplied.



Value	Description
S0 – Power On	System is powered on when DC power is supplied.
S5 – Power Off	System is kept in off state when DC power is supplied.

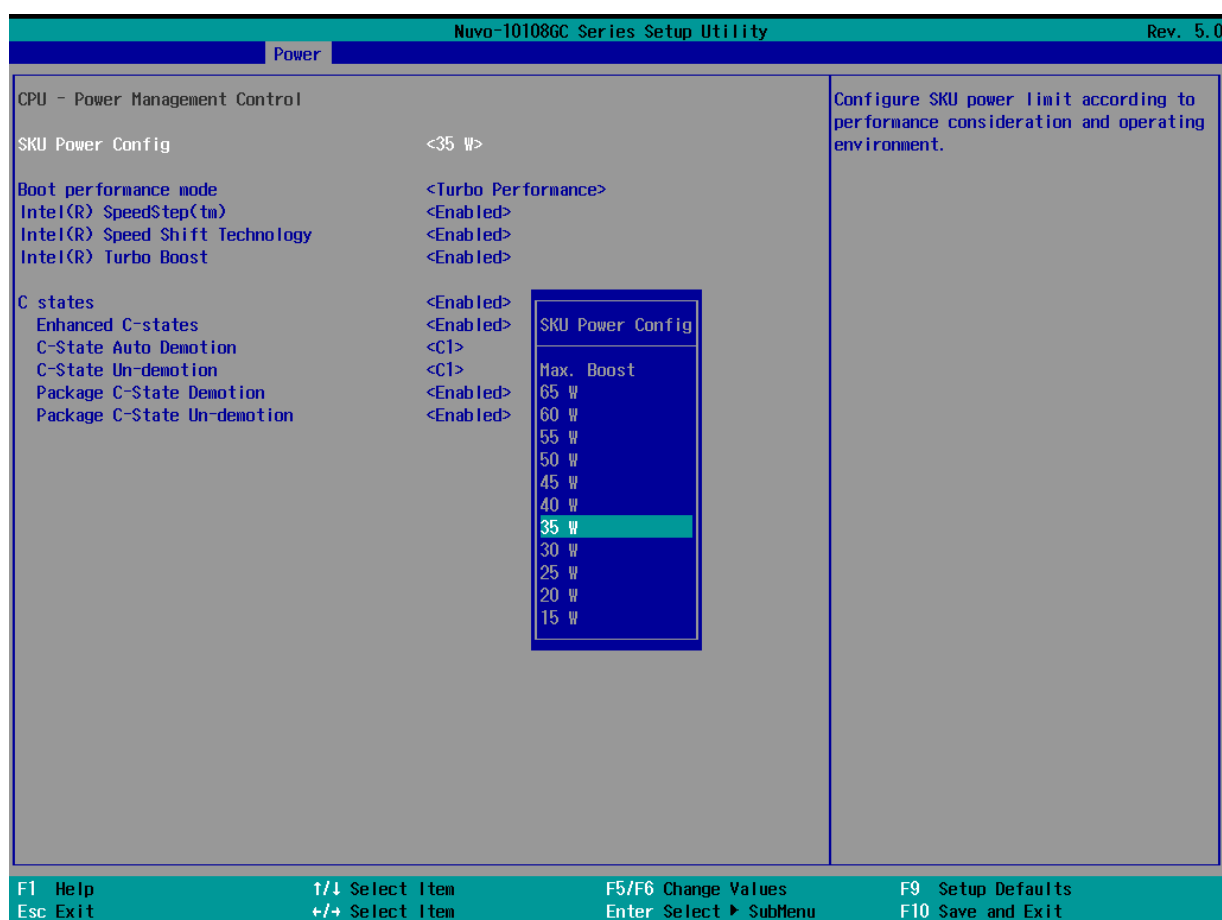
To set “Power On after Power Failure” option:

1. When system boots up, press F2 to enter BIOS setup utility.
2. Go to **[Power] > [Power On after Power Failure]**.
3. Scroll down to highlight **[Power On after Power Failure]**, press ENTER to bring up setting options, S0 – Power On or S5 – Power Off, and press ENTER to select the setting.
4. Press F10 to “Exit Saving Changes”.

4.1.8 Power & Performance (CPU SKU Power Configuration)

The system supports Intel® 14th/ 13th/ 12th-Gen Core CPUs. A unique feature, “**SKU Power Config**” is implemented in BIOS to allow users to specify user-defined SKU power limit.

Although the system is designed to have best thermal performance with CPUs of 35W TDP, you can install a 65W CPU and limit its SKU power (to 35W) to obtain more computing power. This feature gives you the flexibility of CPU selection and great balance between computing power and operating temperature range. Depending on the CPU installed, SKU Power Config settings may include Max/ 65W/ 45W/ 35W/ 25W/ 15W options.

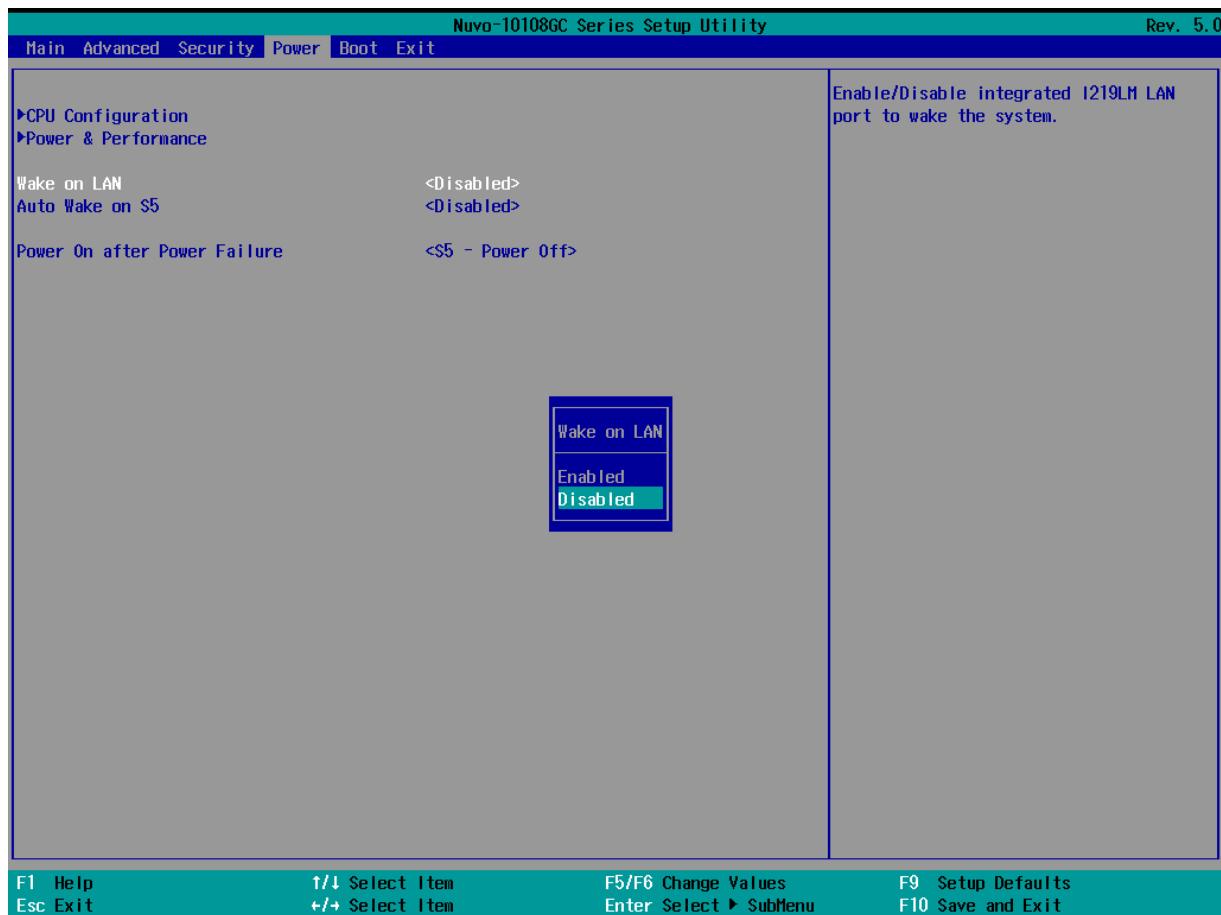


To configure the CPU SKU power limit:

1. When the system boots up, press F2 to enter BIOS setup utility.
2. Go to **[Power]** → **[Power & Performance]**.
3. Select a proper value of SKU power limit for **[SKU Power Config]** option.
4. Press F10 to "Exit Saving Changes".

4.1.9 Wake on LAN Option

Wake-on-LAN (WOL) is a mechanism which allows you to turn on your System series via Ethernet connection. To utilize Wake-on-LAN function, you have to enable this option first in BIOS settings. Please refer "[Powering On Using Wake-on-LAN](#)" to set up the system.

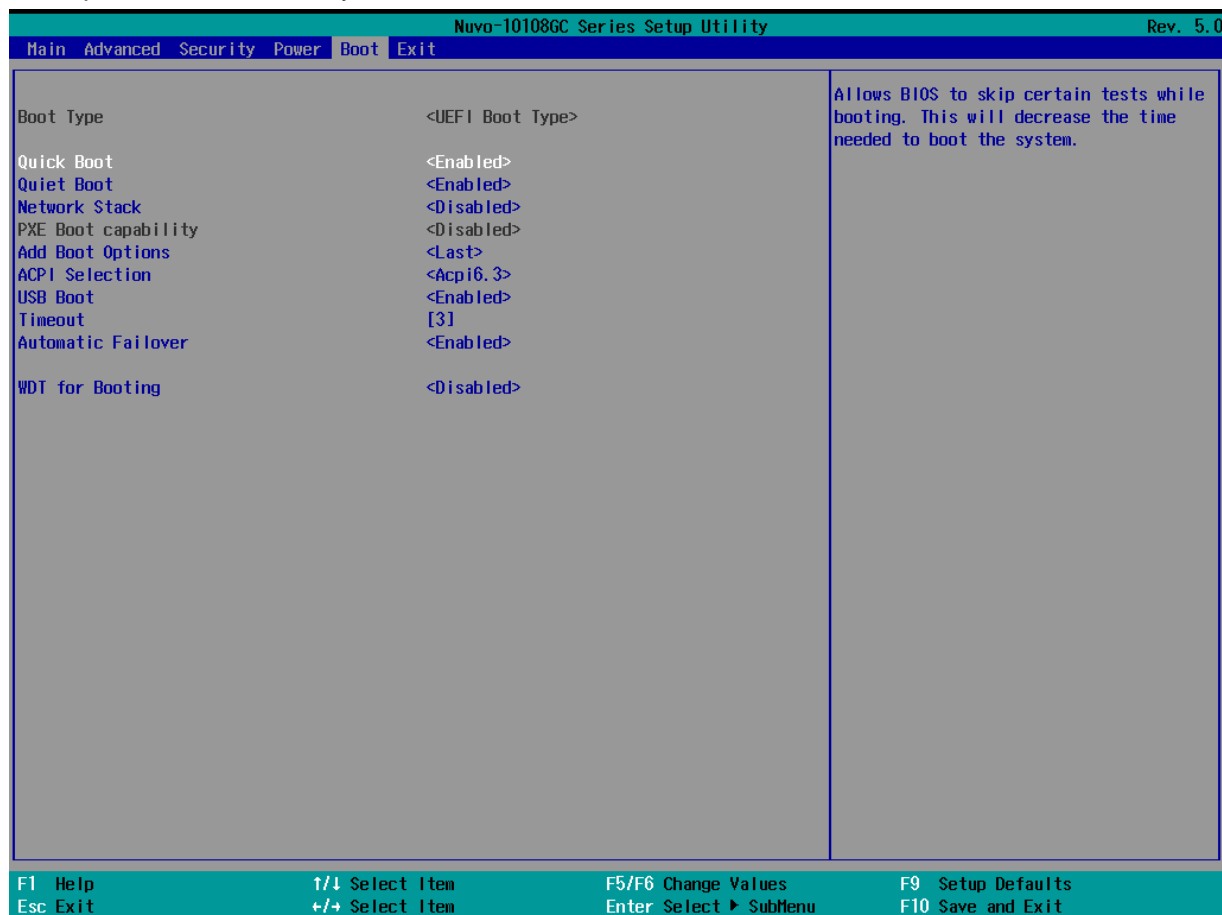


To enable/ disable "Wake on LAN" option:

1. When system boots up, press F2 to enter BIOS setup utility.
2. Go to **[Power]> [Wake on LAN]**.
3. Press ENTER to bring up setting options, scroll to the setting you desire and press ENTER to set.
4. Press F10 to "Exit Saving Changes."

4.1.10 Boot Menu

The Boot menu in BIOS allows you to specify the system's boot characteristics by setting bootable device components (boot media) and method. Or, you may press F12 upon system start up and select a device you wish boot from.



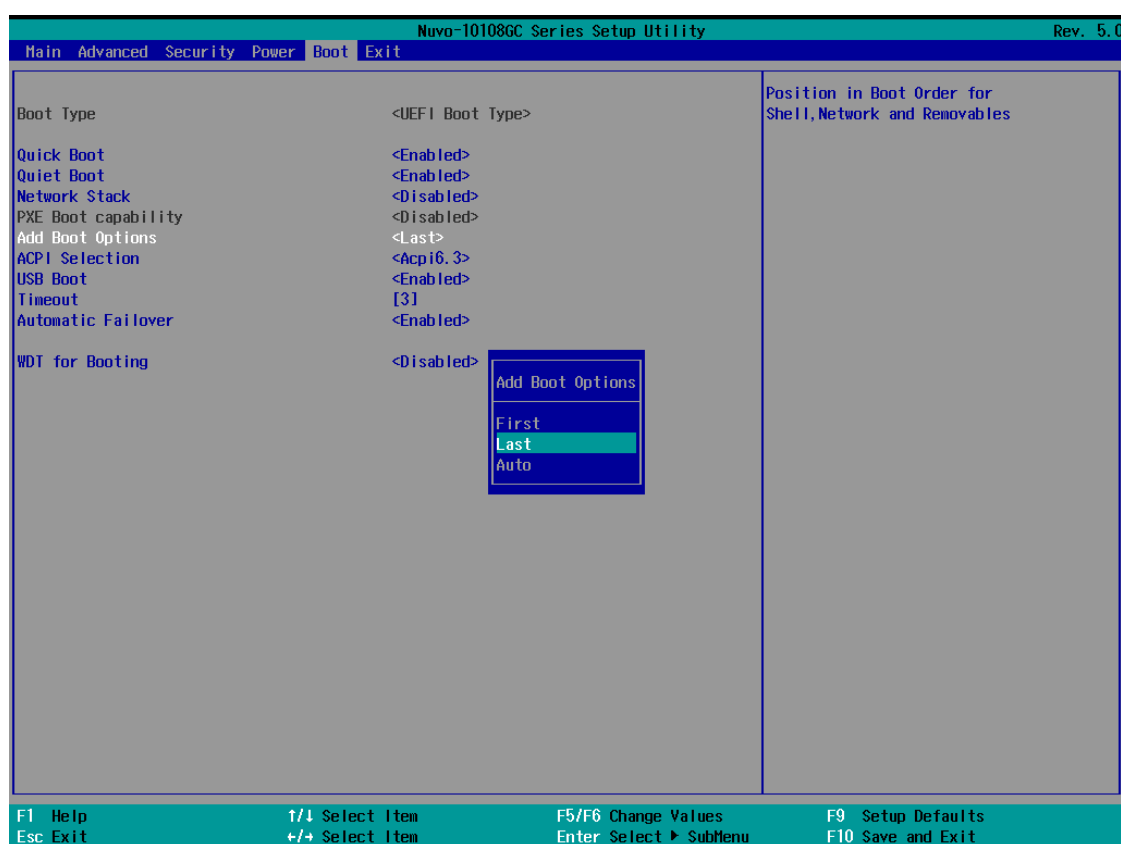
capability		Environment (PXE) is not supported
	Enabled	By enabling the PXE boot, one can choose to boot via I219 Only/ I210 Only or All NICs
Add Boot Options	First	Newly detected boot media are placed at the top of the boot order
	Last	Newly detected boot media are placed at the bottom of the boot order
ACPI Selection	1.0B/ 3.0/ 4.0/ 5.0/ 6.0	Advanced Configuration and Power Interface allows the operating system to control system power management
USB Boot	Enabled	Allow boot from bootable USB devices
	Disabled	Does not allow boot from bootable USB devices
EFI Device First	Enabled	Set to boot bootable EFI media first
	Disabled	Will not boot bootable EFI media first
Timeout	1, 2, 3, etc (in seconds)	Boot delay time in seconds to give the user time to activate the hotkey to access the BIOS
Automatic Failover	Enabled	Automatically checks for the next bootable device when the set default device fails
	Disabled	Will only boot from the designated device
WDT for booting	Disabled, 1, 3, 5, 10 (minutes)	WDT ensures a successful system boot by specifying a timeout value

4.1.11 Position New Boot Device

The “Add Boot Options” allow you to determine whether a newly added device (eg. USB flash disk) is to boot as the first device to boot or the last in the boot sequence.

To set the newly-installed boot device as the first or last boot device:

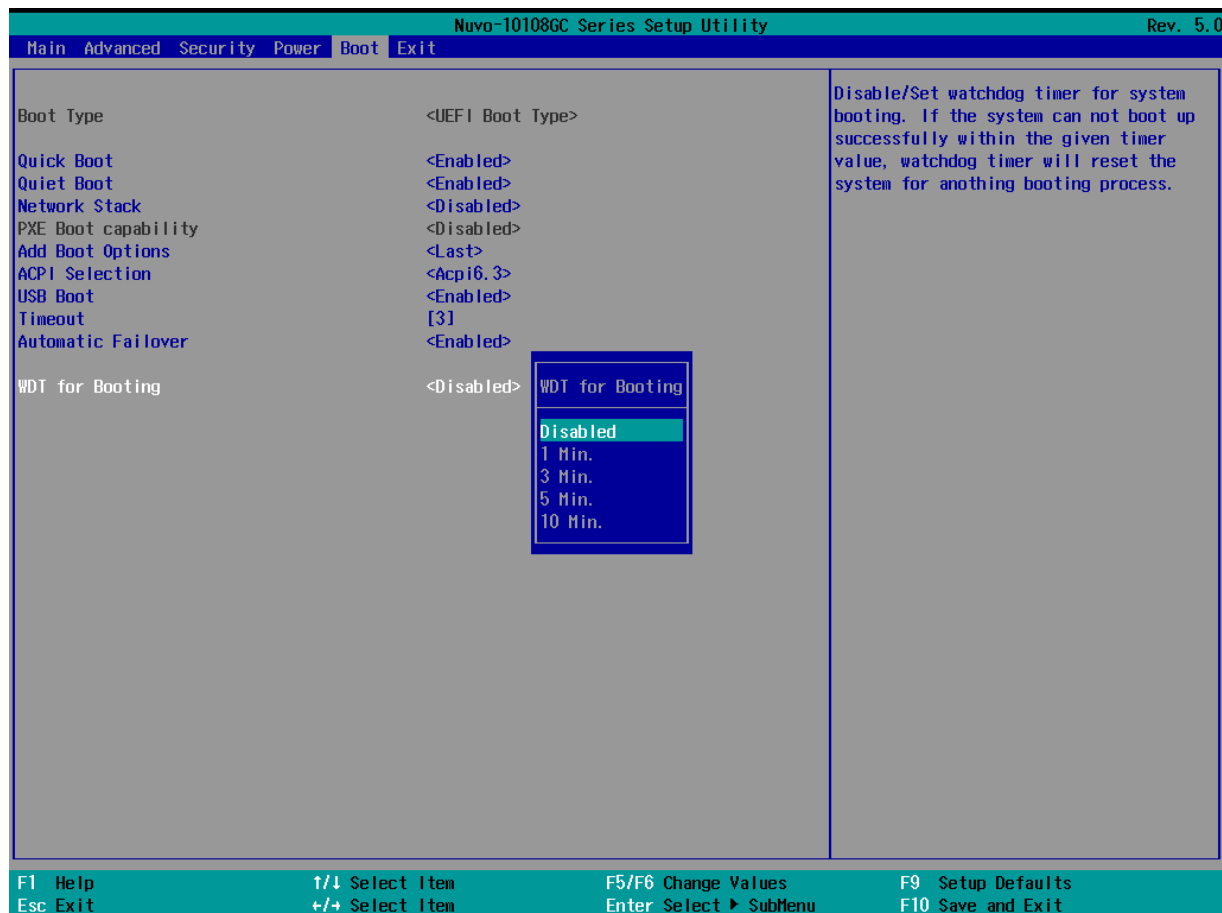
1. Press **F2** when the system boots up to enter the BIOS setup utility.
2. Go to **[Boot] > [Add Boot Options]** menu.
3. Select **[First]** or **[Last]** for your newly-added boot device and press ENTER.



4. Once set, press **F10** to save setting and exit.

4.1.12 Watchdog Timer for Booting

The watchdog timer secures the boot process by means of a timer. Once the timer expires, a reset command is issued to initiate another booting process. There are two options in BIOS menu, “*Automatically after POST*” and “*Manually after Entering OS*”. When “*Automatically after POST*” is selected, the BIOS automatically stops the watchdog timer after POST (Power-On Self Test) OK. When “*Manually after Entering OS*” is selected, the user must stop the watchdog timer once booted into the OS. This guarantees the system can always boot into the OS, otherwise another booting process will be initiated. For information about programming watchdog timer, please refer to [Watchdog Timer & Isolated DIO](#).



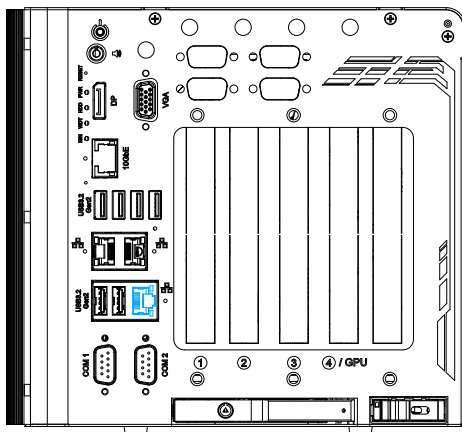
To set the watchdog timer for boot in BIOS:

1. When system boots up, press F2 to enter BIOS setup utility.
2. Go to **[Boot]** menu.
3. Disable or select timeout value for **[WDT for Booting]** option.
4. Once you give a timeout value, the **[WDT Stop Option]** option appears. You can select “*Automatically after POST*” or “*Manually after Entering OS*”.
5. Press F10 to “Exit Saving Changes.”

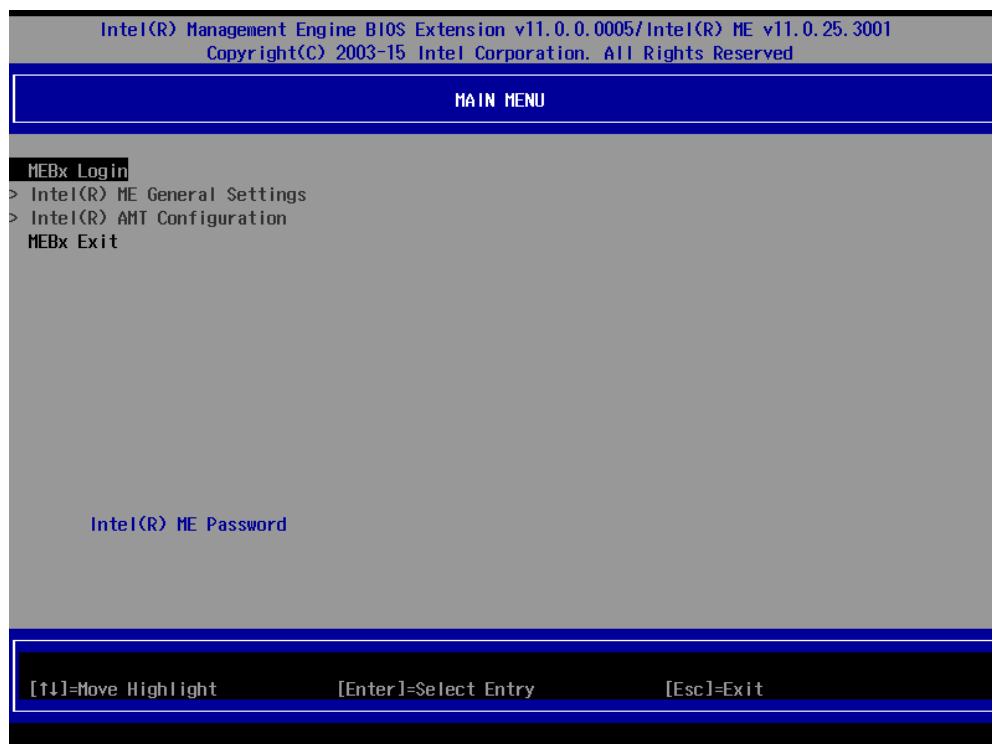
4.2 AMT Configuration

Intel® AMT (Active Management Technology) is a hardware-based technology for remotely managing target PCs via Ethernet connection. The system supports AMT function via its Ethernet port implemented with Intel I219-LM. Prior to using the AMT function to remotely control the system, you need to configure AMT password and network settings.

1. Connect Ethernet cable to I219-LM Ethernet port (indicated in blue).



2. When the system boots up, press F10 to enter the MEBx configuration menu.



3. Highlight MEBx Login and press Enter, a prompt will appear asking for password. The default password is "admin". For further MEBx configuration details, please refer to [Intel® MEBX User Guide](#).

5 OS Support and Driver Installation

5.1 Operating System Compatibility

The system supports most operating system developed for Intel® x86 architecture. The following list contains the operating systems which have been tested by Neosys Technology.

- Microsoft Window 10 LTSC 2021 (x64)
- Ubuntu 20.04.5 LTS, 22.04 LTS, 22.04.1 LTS or other distribution with kernel version ≥ 5.15 */**



NOTE

For other Linux OS, Linux kernel should upgrade to 4.15.18.

**For Linux system, user may need to manually compile and install the driver for Intel graphics or I225/ I226 GbE controller if the driver is not embedded in kernel. You can visit Intel website for further information.*

***For distributions, graphics driver may not be completely implemented in its kernel. You may encounter restrictions when using these features, such as multiple independent displays. For optimum operation, it is the users' responsibility to manually check for new drivers and upgrades!*

Neosys may remove or update operating system compatibility without prior notice. Please contact us if your operating system of choice is not on the list.

5.2 Driver Installation

The system drivers are available online, please click on this [link](#) to download the drivers.

5.3 Driver Installation for Watchdog Time Control

Neosys provides a driver package which contain function APIs for Watchdog Timer control function. You should install the driver package (WDT_DIO_Setup.exe) in prior to use these functions. Please download the latest version of WDT_DIO_Setup.exe to ensure compatibility.

Please refer to this [link](#) to download WDT_DIO.

Appendix A Using WDT & DIO

The watchdog timer (WDT) function to ensure reliable system operation. The WDT is a hardware mechanism to reset the system if the watchdog timer is expired. Users can start the WDT and keeping resetting the timer to make sure the system or program is running. Otherwise, the system shall be reset.

In this section, we'll illustrate how to use the function library provided by Neosys to program the WDT functions. Currently, WDT driver library supports Windows 10 x64 and WOW64 platform. For other OS support, please contact Neosys Technology for further information.

Installing WDT_DIO Library

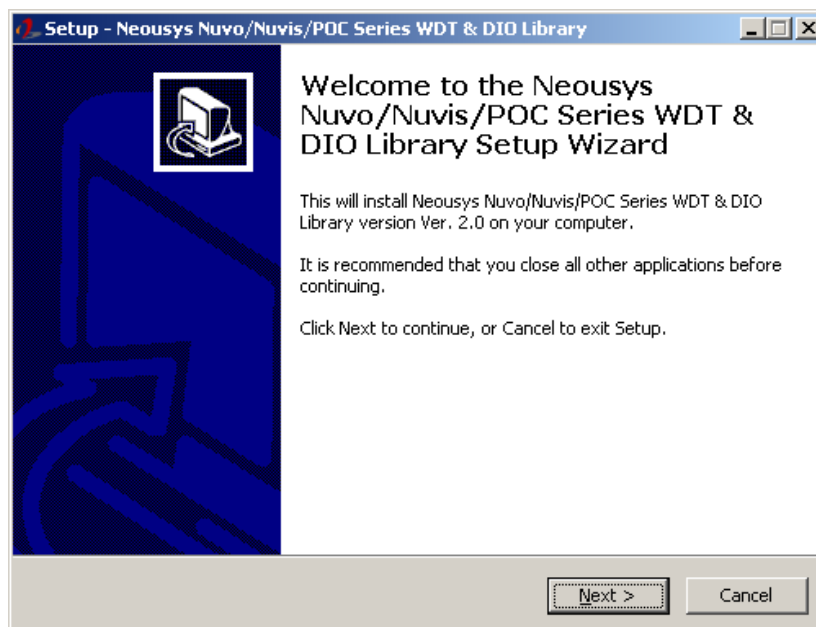
The WDT_DIO function library is delivered in the form of a setup package named **WDT_DIO_Setup.exe**. In prior to program WDT, you should execute the setup program and install the WDT library. Please download and install the latest WDT_DIO_Setup packages to ensure compatibility.

- For Windows 10 64-bit OS with 64-bit application (x64 mode), please download and install the latest version available.
- For Windows 10 64-bit OS with 32-bit application (WOW64 mode), please download and install the latest version available.

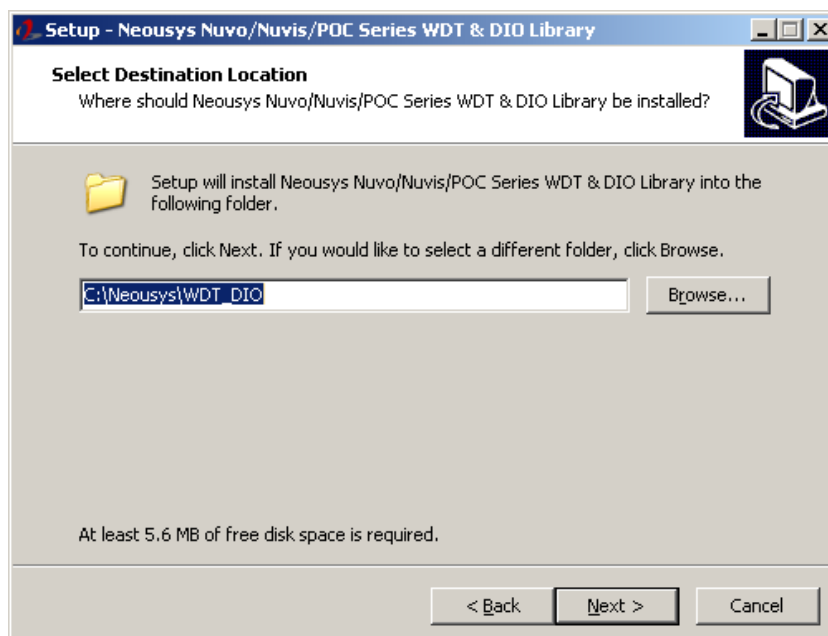
WDT and DIO Library Installation

To setup WDT & DIO Library, please follow instructions below.

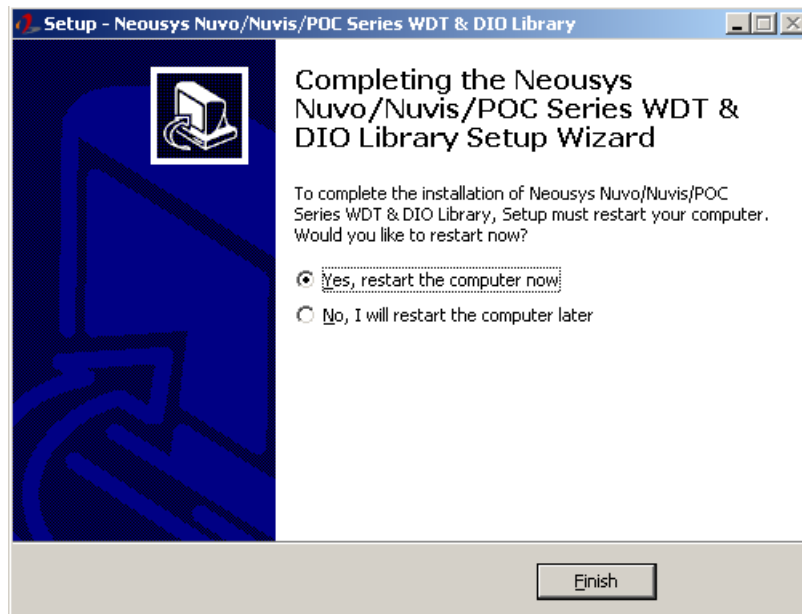
1. Execute **WDT_DIO_Setup.exe**. and the following dialog appears.



2. Click "Next >" and specify the directory of installing related files. The default directory is *C:\Neosys\WDT_DIO*.



3. Once the installation has finished, a dialog will appear to prompt you to reboot the system. The WDT & DIO library will take effect after the system has rebooted.



4. When programming your WDT or DIO program, the related files are located in

Header File:	\Include
Library File:	\Lib
Function	\Manual
Reference:	
Sample Code:	\Sample\WDT_Demo (Demo for Watchdog Timer)

WDT Functions

InitWDT

Syntax	BOOL InitWDT(void);
Description:	Initialize the WDT function. You should always invoke InitWDT() before set or start watchdog timer.
Parameter	None
Return Value	TRUE: Successfully initialized FALSE: Failed to initialize
Usage	<pre> BOOL bRet = InitWDT() </pre>

SetWDT

Syntax	BOOL SetWDT(WORD tick, BYTE unit);
Description	Set timeout value and unit for watchdog timer. When InitWDT() is invoked, a default timeout value of 255 seconds is assigned.
Parameter	<i>tick</i> WORD value (1 ~ 65535) to indicate timeout ticks. <i>unit</i> BYTE value (0 or 1) to indicate unit of timeout ticks. 0 : unit is minute 1: unit is second
Return Value	If value of unit is correct (0 or 1), this function returns TRUE, otherwise FALSE.
Usage	<pre> WORD tick=255; BYTE unit=1; //unit is second. BOOL bRet = SetWDT(tick, unit); //timeout value is 255 seconds </pre>

StartWDT

Syntax	BOOL StartWDT(void);
Description	Starts WDT countdown. Once started, the WDT LED indicator will begin blinking. If ResetWDT() or StopWDT is not invoked before WDT countdowns to 0, the WDT expires and the system resets.
Parameter	None
Return Value	If the timeout value is given in correct format (WDT started), this function returns TRUE, otherwise FALSE
Usage	<pre> BOOL bRet = StartWDT() </pre>

ResetWDT

Syntax	BOOL ResetWDT(void);
Description	Reset the timeout value to the value given by SetWDT().If ResetWDT() or StopWDT is not invoked before WDT countdowns to 0, the WDT expires and the system resets.
Parameter	None
Return Value	Always returns TRUE
Usage	<pre> BOOL bRet = ResetWDT() </pre>

StopWDT

Syntax	BOOL StopWDT(void);
Description	Stops the countdown of WDT. When WDT has stopped, the WDT LED indicator stops blinking.
Parameter	None
Return Value	Always returns TRUE
Usage	<pre> BOOL bRet = StopWDT() </pre>